Use LEYBOLD training systems to impart to your students and trainees a multitude of training subjects in the areas of automotive, electrical engineering as well renewable energy technology. Our educationally-designed equipment and systems for technical vocational training combine theory and practical applications in an ideal manner and can be integrated perfectly into project work.

In this catalogue we will be presenting our training systems from the drive technology area. You are at the right address when it comes to obtaining customised solutions for your technology and workshop laboratory, designed especially for specific fields of training.
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COM3LAB MULTIMEDIA 08
MACHINE TESTING SYSTEMS 10
STE PLUG-IN SYSTEM 12
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LEYLAB – THE INTERACTIVE LAB 16
LAB AND FACILITY INSTALLATION PLANNING 18
CASSY - COMPUTER ASSISTED MEASUREMENT AND EVALUATION 20

EQUIPMENT SETS ACCORDING TO TOPIC
COMPLETE EQUIPMENT SETS TAILORED TO THE TRAINING CONTENT CAN BE FOUND FROM PAGE 24 ONWARDS

INDIVIDUAL COMPONENTS
TECHNICAL DETAILS ON INDIVIDUAL COMPONENTS IN EQUIPMENT SETS CAN BE FOUND FROM PAGE 74 ONWARDS

INDEX
FROM PAGE 150 ONWARDS
ENERGY-EFFICIENT ELECTRICAL MACHINES

Now this topic can also be investigated using the new LEYBOLD components for electrical machine teaching models.

By mounting a multipole stator and a rotor equipped with permanent magnets on our tried and true platform, it is now possible to cover completely new uses and applications during instruction.

Now for the first time, the topics of highly-efficient motor and generator operation can be investigated using this stator/rotor combination.

FEATURES ELECTRICAL MACHINES

- Vertical electrical machine setup
- Three-phase stator with colour-coded windings
- Coloured rotor magnets
- Synchronous machine (PMSM)
- BLDC drive system or
- Modern type generator

| 727 815 | ELM multipole stator rotor kit |
| 727 816 | ELM PM rotor magnets (internal) |
MACHINES WITH INTERCHANGEABLE ROTORS

Machine models for mains voltage consist of a stator and various, interchangeable rotors. Once the stator and rotor have been assembled, a fully operational electrical machine of the 300 W class is realised.

The stator housing is mounted on a base and can be connected directly to the machine testing system 0.3 (731 989 USB). The star-shaped tie-bolts are responsible not only for the secure connection of the stator and the rotor but also the quick exchange of rotors. The rotors are equipped with B-type end shields, fan impellers, jackets and possibly slip-rings, brushes etc. In conjunction with the machine testing system, the machine characteristics can be traced back to particular features of the specific rotor. Depending on the rotor in use the machine model demonstrates the typical properties of induction (asynchronous) or synchronous machines.

747 720 Three-phase stator
747 721 Squirrel cage rotor

Additional rotors can be found in the catalogue section devoted to single components.
LEYBOLD'S ELECTRONIC LIBRARY

- Display and manage student experiment literature, demonstration experiment instructions or operating instructions in one program
- Automatically update all documents thanks to free online updates
- Benefit from convenient, fault-tolerant keyword and catalogue number search features
THE DAYS OF ENDLESS SEARCHING ARE OVER

The time consuming search for experiment instructions in folders is finally over. The new and free-of-charge Document Center saves you valuable class preparation time. With the new Document Center you have digital access to all the technical documentation which we have placed at your disposal (partially free-of-charge) in the form of extensive literature packets.

Once installed, you can set the documents to automatically update to the latest versions. The literature packets are clearly displayed in the form of a table of contents that also guides you intuitively to the desired document. The more literature packets you have installed, the more entries you will have in your table of contents.

Using the fault-tolerant search function you can quickly and easily find the correct document. Here again, the more literature packets installed, the more powerful the search function becomes.

CONDUCT EXPERIMENTS INTERACTIVELY AND LOG THE RESULTS DIGITALLY

Literature packets not only contain documents but also application data. Thus, for example, it is possible to take settings and examples from one of the experiment descriptions included in the literature packet and load this data into CASSY Lab with a simple click of the mouse.

If student and teacher versions from a packet are installed, switching back and forth between versions is also as easy as a mouse click. Student documents can be filled out in the Document Center and logged findings saved or printed out as a hardcopy.
The master unit is compatible with all of the courses and includes two digital multimeters, a function generator, a digital storage oscilloscope and a digital analyzer. By simply inserting a different experiment board into the Master Unit a completely new topic area can be explored.

New courses in the area of power electronics and electrical machines impart the subject’s fundamentals and support the practical hands-on experimentation with measureable learning results.

COM3LAB Multimedia combines training software with real hardware that can be used in schools, universities or vocational training centres in industry.

COM3LAB courses are well suited for both classroom presentation, self-directed home study or for project work. They are comprised of an electronic and an interactive instruction manual and the corresponding hardware.
In this COM3LAB course, the basics of drive technology are presented and conveyed in an understandable way. The highlight of the course is the integrated machine testing system. This system allows you to really measure and compare the characteristics of all standard electrical motors.

There is an electronic, interactive text book included with each COM3LAB course each containing in-depth experiment instructions featuring technical specifications, images, videos and animations to support both theoretical and practical applications. Besides all of this material, the text book also contains a virtual laboratory and a large number of tools, e.g. for creating documentation.
MACHINE TESTING SYSTEMS

TOPICS

RECORDING THE CHARACTERISTICS OF ELECTRICAL MACHINES

- DC, AC and three-phase machines
- Investigating machines operating in motor and generator modes
- Plotting the locus diagrams for (asynchronous) induction motors (Heyland or circle diagrams)

ACTIVE LOAD SIMULATION

- Fan characteristic, winder characteristic
- Flywheel
- User-defined load characteristics
FEATURES OF THE MACHINE TEST SYSTEM

- Simple operation also without a PC
- Modular system configuration with short set-up time
- Test machines in 300 W or 1 kW power classes
- Protection for man and machine thanks to integrated temperature sensor and shaft-end monitoring of all machines
- Compare several characteristics on a single diagram
- Calculate mechanical and electrical characteristics
- Manage characteristic curves in table form
- Recording curves in both standardised and absolute plotted diagrams
- Blocking student access to select curves

SAFETY

- Monitoring shaft-end guard
- Temperature monitoring of the DUT

LEYBOLD MACHINE TEST SYSTEM PERFORMS IMPORTANT TASKS IN THE EXPERIMENT SET-UP:

- Regulated control of a motor braking system
- Measurement and processing of real-time data for computer-assisted characteristic evaluation
- Controlled drive of generators and drive gears

This makes the recording of important characteristics of real motors and generators easy to do even for trainees and students.

In vocational training, the mechanical and electrical variables of electrical machines need to be measured and evaluated. To do this, the AC, DC or three-phase machine is securely and mechanically coupled to the drive and load unit of the machine test system. During the measurement the drive unit of the machine testing system continuously records the torque and speed of the machine under test.

Recording and evaluating characteristics is carried out by computer control using the CBM 10 software. Based on the torque, speed, current and voltage parameters measured directly, additional variables can be deduced, e.g. the power output and consumption, degree of efficiency, power factor $\cos \phi$. 

Torque-speed characteristic
The LEYBOLD plug-in system is a tried and tested experimentation program for electrical engineering and electronics. The extensive experimentation program covers beside the basics also advanced topics, for example, communications, IT, open- and closed-loop control technology as well as areas from automotive electronics.

Instruction sheets for students and accompanying teacher information are available to assist with the performance of experiments. The printed symbols on the plug-in housing elements, connectors and training panels provide the experiment set-ups with a circuit-like appearance. This facilitates the knowledge transfer between the circuit diagrams in the text books and the circuitry being assembled and makes the documenting of the experiment set-ups easier to do and ultimately promotes circuit-based thinking, learning and experimenting.
The STE elements come ready for operation and assembly with their electrical and electronic components encased in transparent housings to protect against external mechanical damage. Thanks to the transparent bottom part the original component is visible.

Stackable plastic trays offer alternatively a space saving and clear storage configuration of STE-elements, components and accessories in cabinets or drawers.

ADVANTAGES

- Modular system
- Comfortable storage solutions for rapid assembly and disassembly
- Easy to expand
- Variety of A4 base panels, A3 available for vertical assemblies
- Clearly printed circuit symbols and designations
THE MODULAR TRAINING PANEL SYSTEM FOR STUDENT EXPERIMENTS AND CLASSROOM DEMONSTRATIONS

- Use of original components
- Experiment literature for classroom preparation and experiment procedures
- Featuring clearly laid out frontal panels
Thanks to the modular design, technology labs can quickly and easily be outfitted or extended using the TPS system.

The systematic use of 4-mm safety sockets, cables and bridging plugs (jumpers), ensure that the experiment procedures are carried out safely. With the support of extensive experiment instructions and literature the students and trainees have lots of opportunities to acquire knowledge and new skills while at the same time deepening what they have already learned previously.

The proven TPS training panel system is also perfectly suited for instructors who have to demonstrate complex experiments. The additional TPS.NET and CASSY technologies offer the option of conducting all experiments with computer assistance. This builds a bridge between traditional learning and new technologies.
From the teacher’s PC, the instructor has password protected access to all of the equipment and can take readings and change settings at any time. Furthermore, for the protection of the connected training environment, maximum parameter limits can be set which the students cannot manipulate.
REMOTE CONTROL OF ALL LABORATORY EQUIPMENT

The LEYLAB.control software is the control centre at the heart of the networked laboratory and permits the switching and activation of interconnected power supply units of the LEYLAB.power series as well as the networkable training panels of the TPS series. The instructor can map out his or her laboratory on the program interface and thus obtain a graphic overview of all the equipment connected via Ethernet.

NETWORK-CAPABLE EXPERIMENTING MODULES

Network-capable TPS modules are equipped with an Ethernet port so that they can be integrated into the LEYLAB.control concept. While the students are busy conducting experiments, the teacher can either monitor or actively access their equipment from his or her computer. Measurement data acquisition, the setting of parameters and limiting values and safe fault simulation are thus possible.

DIRECT COMMUNICATION WITH STUDENT PC AND THE EXPERIMENT MODULES

TPS.NET

THE CUSTOMISED, INTERACTIVE TECHNOLOGY LAB OF THE FUTURE

MONITOR AND CHECK ON STUDENTS
YOUR NEW LEYBOLD LAB FACILITY

Based on your ideas, we team up with you and plan a lab or classroom facility that fits your syllabus. Our room planners custom design your laboratory simply by tailoring the desired experiment equipment, furniture and storage solutions to your specific needs.

Thanks to our many years of experience, we are reliable partners in all phases of project planning from conception to implementation.
EVERYTHING YOU NEED FROM A SINGLE SOURCE

LAB AND CLASSROOM PLANNING

- Furnishings designed for practical use
- In compliance with safety standards
- Blueprints and planning documents
- Specification of performance features

FURNITURE

- Customised solutions
- Networked training systems
- Storage systems designed to fit equipment and equipment sets
- Long availability & supplementation guarantee

FINANCING

Leasing offers for technical equipment and furnishings

LEYBOLD®
The modular CASSY system makes computer-assisted measurement and evaluation possible for all training and educational levels up to university level.

THE CASSY SYSTEM COVERS:
1. Interface for recording measurement data
2. Comprehensive offering of sensors for the detection of electrical and non-electrical variables
3. CASSY Lab 2: The intuitive and easy-to-use software for measurement and evaluation designed to fit all of the equipment and sensors

**SENSORS (SELECTION)**

<table>
<thead>
<tr>
<th>Catalogue No.</th>
<th>Designation</th>
</tr>
</thead>
<tbody>
<tr>
<td>738 987</td>
<td>Capacitive-type pick-up</td>
</tr>
<tr>
<td>738 986</td>
<td>Inductive-type pulse pick-up</td>
</tr>
<tr>
<td>524 064</td>
<td>Pressure sensor S</td>
</tr>
<tr>
<td>524 044</td>
<td>Temperature sensor S</td>
</tr>
<tr>
<td>524 0511</td>
<td>Lux adapter S</td>
</tr>
<tr>
<td>666 243</td>
<td>Lux sensor</td>
</tr>
<tr>
<td>524 031</td>
<td>Current source box</td>
</tr>
<tr>
<td>524 043</td>
<td>30 A box</td>
</tr>
<tr>
<td>524 0512</td>
<td>Optical performance sensor</td>
</tr>
</tbody>
</table>
SENSOR-CASSY 2

INTERFACE FOR RECORDING MEASUREMENT DATA

- For connection to the USB port of a computer, to an additional CASSY module or to the CASSY display
- Simultaneous measurement of voltage, current and two additional variables possible
- Automatic sensor box recognition
- Can be setup as table-top, console or demonstration unit (also in CPS/TPS experiment frames)

PLUG & PLAY
Automatic detection and setting of Sensor-CASSY and sensor boxes

COMPATIBLE
with all CASSY sensor boxes and sensors

Sensor-CASSY 2 (524 013) provides two electrically separated voltage inputs, an alternative current input and two sensor box inputs parallel to this. All inputs have variable measurement ranges. Technical specs can be found in the individual component section of the catalogue.

PROFI-CASSY

INTERFACE FOR ALL AREAS OF ELECTRICAL ENGINEERING

- For connection to the USB port of a computer
- Microcontroller-controlled with the CASSY-operating system (upgrades and expansions can be easily updated anytime via software)
- Variable set-up as table-top, console or demonstration device (also in CPS/TPS experiment frames)

Technical data for the Profi-CASSY (524 016) can be found in the individual component section of the catalogue.
SAVE TIME AND EFFORT DURING CLASS PREPARATION AND EXPERIMENT PROCEDURES

LEYBOLD solutions are not only tailored for complex training subjects but also for the continuously growing demands being placed on teachers and instructors. You will only have to invest a short amount of time in preparing your classes or to set up your experiments. This is because with the extensive experiment literature accompanying our systems, you receive guidelines for demonstration experiments that can also serve as experiment instructions and exercise handouts for your students.

LITERATURE

THE EXPERIMENT LITERATURE HAS BEEN WRITTEN WITH SPECIAL EDUCATIONAL CONSIDERATIONS TO SIMPLIFY AND FACILITATE CLASSROOM AND EXPERIMENTATION PREPARATION FOR INSTRUCTORS.
GENERAL INFORMATION

Customer desk  + (49) 22 33 / 604 – 430
Order processing
Available Mon.-Thur. from 8.00 am- 4.00 pm and Fr. from 8.00 am – 2.45 pm
Order fax  + (49) 22 33 / 604 – 193
Help-Line  + (49) 22 33 / 604 – 301
Technical support for queries, advice on equipment or experiments
Available Tues. from 10.00 am - 12.00 pm and Thur. from 2.00 pm - 4.00 pm
E-mail  info@ld-didactic.de
Internet  www.ld-didactic.de

INFORMATION CONCERNING TENDERS

Your contact partners Mr. Kattwinkel and Mr. Schilling are at your disposal from
Mon.-Thur. from 8.00 am to 4.00 pm and Fr. 8.00 am to 2.45 pm.

Contact data:
Achim Kattwinkel  Telefon + (49) 22 33 / 604 - 272  E-mail akattwinkel@ld-didactic.de
Hans Peter Schilling  Telefon + (49) 22 33 / 604 - 305  E-mail pschilling@ld-didactic.de

TECHNICAL SERVICE

Should you have any questions regarding a component or an equipment set:
Our service team is at your disposal by phone at + (49) 22 33 604 – 430 and
per E-mail under service@ld-didactic.de.

YOUR PERSONAL TECHNICAL ADVISOR

You can find the contact data of the technical advisor you need on our internet page.
On the following pages, we present a collection of stand-alone and fully-operational experiment set-ups. These contain individual units, instrumentation, software and teachware. The equipment sets are based on training fields currently required in standard training and education.

Of course, the modular solutions of these equipment sets can be adapted to your specific needs. We are happy to advise you, just ask us!

The following pages present our extensive offering of electrical drives. A brief definition of the term "drive" should help to explain the structure of this catalogue. A drive always comprises two machines coupled together. The motor or driving machine generates the required speed or torque and the working machine absorbs the mechanical energy required to perform the desired process. In the case of an electrical drive the motor is an electrical machine. In modern, electrical drives, the energy-efficient supply of electrical power is performed using power electronics components, e.g. power converters and frequency converters. When high demands are being made on the electrical drive's speed and torque stability, additional automatic control technology is then required. One special area of control applications for closed-loop electrical drives includes positioning or servo drives. For that reason, the catalogue has been arranged in the following topic areas:

E2 ELECTRICAL DRIVES

E2.1 EDUCATIONALLY DESIGNED MACHINES 25-31
E2.2 INDUSTRIAL MACHINES 300 W 32-40
E2.3 INDUSTRIAL MACHINES 1 KW 41-47
E2.4 POWER ELECTRONICS 48-55
E2.5 DRIVE TECHNOLOGY 56-65
E2.6 SERVO TECHNOLOGY 66-73

Detailed information on our equipment sets can also be found at our webpage.
E2 ELECTRICAL DRIVES

E2.1 EDUCATIONALLY DESIGNED MACHINES

E2.1.1 MACHINE LABS WITH THE PLUG-IN SYSTEM
  E2.1.1.1 Electromagnetism & Induction
  E2.1.1.2 3-Phase Transformers
  E2.1.1.3 3-Phase Rectification
  E2.1.1.4 Generators & Motors

E2.1.2 COM3LAB-MULTIMEDIA: MOTORS & GENERATORS
  E2.1.2.1 Basics of Electrical Machines

E2.1.3 MACHINE ASSEMBLY KITS
  E2.1.3.1 ELM Basic Machines for Extra-Low Voltage
  E2.1.3.2 ELM Efficiency Machines for Extra-Low Voltage
  E2.1.3.3 Electrical Machine Teaching Models for Extra-Low Voltage
  E2.1.3.4 Machines with Rotor Kits
  E2.1.3.5 Electrical Machines Training System
Machine Labs with the Plug-In System

**E2.1.1 Electromagnetism & Induction**

<table>
<thead>
<tr>
<th>Cat. No.</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>588 871S</td>
<td>Advanced Science Kit - Set BBL</td>
</tr>
<tr>
<td>588 875S</td>
<td>Advanced Science Kit - Set ELI 1</td>
</tr>
<tr>
<td>588 876S</td>
<td>Advanced Science Kit - Set ELI 2</td>
</tr>
<tr>
<td>521 485</td>
<td>AC/DC power supply, 0...12 V/3 A</td>
</tr>
<tr>
<td>685 48ETS</td>
<td>Batteries 1.5 V (D, mono), set of 5</td>
</tr>
<tr>
<td>531 120</td>
<td>Multimeter L/Dalogo 2</td>
</tr>
<tr>
<td>459 32</td>
<td>Candles, set of 20</td>
</tr>
<tr>
<td>505 07</td>
<td>Bulbs, 4 V/0.16 W, E10, set of 10</td>
</tr>
<tr>
<td>505 08</td>
<td>Bulbs, 12 V/3 W, E10, set of 10</td>
</tr>
<tr>
<td>505 11</td>
<td>Bulbs, 2.5 V/0.25 W, E10, set of 10</td>
</tr>
<tr>
<td>550 42</td>
<td>Constantan resistance wire, 0.35 mm diameter, 100 m</td>
</tr>
<tr>
<td>550 46</td>
<td>Chrome-nickel resistance wire, 0.25 mm diameter, 100 m</td>
</tr>
<tr>
<td>550 47</td>
<td>Chrome-nickel resistance wire, 0.35 mm diameter, 100 m</td>
</tr>
<tr>
<td>550 51</td>
<td>Iron resistance wire, 0.2 mm diameter, 100 m</td>
</tr>
<tr>
<td>578 39</td>
<td>Capacitor (electrolytic), 100 µF, STE 2/19</td>
</tr>
<tr>
<td>578 40</td>
<td>Capacitor (electrolytic), 470 µF, STE 2/19</td>
</tr>
<tr>
<td>667 017</td>
<td>Scissors, 125 mm, round-ended</td>
</tr>
<tr>
<td>501 44</td>
<td>Connecting leads, 19 A, 25 cm, red/blue, pair</td>
</tr>
<tr>
<td>501 45</td>
<td>Connecting lead, 19 A, 50 cm, red/blue, pair</td>
</tr>
<tr>
<td>501 441</td>
<td>Connecting lead, 19 A, 25 cm, black, pair</td>
</tr>
<tr>
<td>588 35DE</td>
<td>LIT: PS3.5 STM Electricity - Electromagnetion</td>
</tr>
<tr>
<td>588 34DE</td>
<td>LIT: PS3.4 STM Electricity - Basic electric circuits</td>
</tr>
<tr>
<td>588 35EN</td>
<td>LIT: PS3.5 STM Electricity, Electro-nage</td>
</tr>
<tr>
<td>588 34EN</td>
<td>LIT: PS3.4 STM, Basic electric circuits</td>
</tr>
<tr>
<td>727 514</td>
<td>Basic set T 2.4.1, STE</td>
</tr>
<tr>
<td>576 74</td>
<td>Plug-in-board, DIN A4, STE</td>
</tr>
<tr>
<td>578 79S</td>
<td>Three-phase voltage supply, 3x12 V, STE 4/100</td>
</tr>
<tr>
<td>562 79I</td>
<td>Plug-in power supply, 12 V AC</td>
</tr>
<tr>
<td>501 641</td>
<td>Two-way adapters, red, set of 6</td>
</tr>
<tr>
<td>524 013S</td>
<td>Sensor-CASSY 2 Starter</td>
</tr>
<tr>
<td>578 212</td>
<td>Two-channel oscilloscope 400</td>
</tr>
<tr>
<td>578 231</td>
<td>Probe 100 MHz, 1:1 / 10:1</td>
</tr>
</tbody>
</table>

**E2.1.2 3-Phase Transformers**

<table>
<thead>
<tr>
<th>Cat. No.</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>531 282</td>
<td>Multimeter Metrahit Pro</td>
</tr>
<tr>
<td>501 23</td>
<td>Connecting lead, 32 A, 25 cm, black</td>
</tr>
<tr>
<td>501 28</td>
<td>Connecting lead, 32 A, 50 cm, black</td>
</tr>
<tr>
<td>501 26</td>
<td>Connecting lead, 32 A, 50 cm, blue</td>
</tr>
<tr>
<td>501 30</td>
<td>Connecting lead, 32 A, 100 cm, red</td>
</tr>
<tr>
<td>501 33</td>
<td>Connecting lead, 32 A, 100 cm, black</td>
</tr>
<tr>
<td>501 48</td>
<td>Bridging plugs, STE 2/9, set of 10</td>
</tr>
<tr>
<td>565 641L</td>
<td>LIT: Three-phase transformers and three-phase transformer circuits, T 2.4.1</td>
</tr>
<tr>
<td>565 641S</td>
<td>LIT: Three-phase transformers and three-phase transformer circuits, T 2.4.1</td>
</tr>
<tr>
<td>565 642L</td>
<td>LIT: Three-phase transformers and three-phase transformer circuits T 2.4.2</td>
</tr>
<tr>
<td>727 515</td>
<td>Basic set T 2.4.2, STE</td>
</tr>
<tr>
<td>524 013</td>
<td>Sensor-CASSY 2</td>
</tr>
<tr>
<td>501 02</td>
<td>BNC cable, 1 m</td>
</tr>
<tr>
<td>565 651L</td>
<td>LIT: Three-phase rectifier circuits, T 2.4.2 (German)</td>
</tr>
<tr>
<td>565 651S</td>
<td>LIT: Three-phase rectifier circuits, T 2.4.2 (German)</td>
</tr>
<tr>
<td>565 652L</td>
<td>LIT: Three-phase rectifier circuits T 2.4.2 (English)</td>
</tr>
</tbody>
</table>

**E2.1.3 3-Phase Rectification**

<table>
<thead>
<tr>
<th>Cat. No.</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>576 74</td>
<td>Plug-in-board, DIN A4, STE</td>
</tr>
<tr>
<td>578 79S</td>
<td>Three-phase voltage supply, 3x12 V, STE 4/100</td>
</tr>
<tr>
<td>562 79I</td>
<td>Plug-in power supply, 12 V AC</td>
</tr>
<tr>
<td>501 641</td>
<td>Two-way adapters, red, set of 6</td>
</tr>
<tr>
<td>524 013S</td>
<td>Sensor-CASSY 2 Starter</td>
</tr>
<tr>
<td>578 212</td>
<td>Two-channel oscilloscope 400</td>
</tr>
<tr>
<td>578 231</td>
<td>Probe 100 MHz, 1:1 / 10:1</td>
</tr>
</tbody>
</table>

* additionally recommended

The experiments are carried out using the STE plug-in system Electricity/Electronics.

**Objectives**

- Recognition of basic physical principles
- Implementation of electrical circuits according to circuit diagrams

The target group is made up of students in general or vocational education. The experiments are designed as an introduction at a simple level of understanding.

**Topics (selection)**

- Circuits, conductors and insulators
- Change-over / two-way circuits
- AND and OR circuits
- Measurement of current, voltage etc.
- Star / delta configuration
- Vector groups for three phase transformers
- Power for three-phase loads
- Diodes with R and RL loads
- Circuits: M2U, M3U, M6U, B2U, B6U
Machine Labs with the Plug-In System

E2.1.1.4
Generators & Motors

Self-assembly of electrical machines is particularly effective for building understanding of how motors and generators work. For example, the process of commutation and the forces involved in it can be grasped intuitively and is especially clear when machines are rotating slowly.

The equipment set incorporates student experiments which can be carried out in a laboratory safely using safety extra-low voltage. Experiment instructions are contained in a manual in either printed or digital form.

For more advanced work, the following sets are recommended:
- E2.1.1.1 Electromagnetism & induction
- E2.1.1.2 Three-phase transformers
- E2.1.1.3 Three-phase rectification

Topics
- Magnetic field of a stator
- Magnetic fields of rotors
- How rotors respond in the magnetic field of a stator
- Electromagnetic induction using a bar magnet and a coil
- Dynamos
- Universal generators – functioning principle/operating properties
- Power station generators
- AC/DC generators with electromagnetic stator
- DC motors – functioning principle/power consumption
- DC motors with electromagnetic stator
- Shunt-wound universal motors
- Series-wound universal motors – functioning principle/power consumption
- Synchronous motors
- Electronic motors

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<table>
<thead>
<tr>
<th>Cat. No.</th>
<th>Description</th>
<th>E2.1.1.4</th>
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</thead>
<tbody>
<tr>
<td>588 871S</td>
<td>Advanced Science Kit - Set BEL 1</td>
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<td>588 875S</td>
<td>Advanced Science Kit - Set ELI 1</td>
<td>1</td>
</tr>
<tr>
<td>588 876S</td>
<td>Advanced Science Kit - Set ELI 2</td>
<td>1</td>
</tr>
<tr>
<td>588 877S</td>
<td>Advanced Science Kit - Set ELI 3</td>
<td>1</td>
</tr>
<tr>
<td>521 485</td>
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<td>Bulbs, 12 V/0.2 W, E10, set of 10</td>
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<td>Chrome-nickel resistance wire, 0.25 mm diameter, 100 m</td>
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<td>Chrome-nickel resistance wire, 0.35 mm diameter, 100 m</td>
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<td>Iron resistance wire, 0.2 mm diameter, 100 m</td>
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<td>Capacitor (electrolytic), 470 µF, STB 2/19</td>
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<td>Plug-in axles, set of 2</td>
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<td>Pulley 100 mm Ø, plug-in, pair, set of 2</td>
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* additionally recommended
The experiments are carried out using the multimedia training system COM3LAB.

The COM3LAB course Electrical machines I guides you through the fascinating world of electric motors and generators. Challenging experiments work through the topics of commutator machines, three-phase machines and stepper motors. The board for the course includes a complete machine testing system with which the characteristics of the most important machines can be investigated. The COM3LAB course Three-phase technology discusses the features of multi-phase networks. It forms a basis for understanding three-phase machines such as asynchronous (induction) and synchronous machines.

**Objectives**
- Recognising basic physical principles
- Recording machine characteristics
- Introduction to drive technology

The equipment set allows students to experiment themselves in a lab equipped with PCs using safety extra-low voltage, which presents no hazard. It is also suitable for demonstration experiments by teachers. Multimedia software explains and monitors how the experiments are carried out.

The target group is made up of commercial apprentices and students of electrical machine technology. The course offers introductory experiments at a simple level and more advanced topics for undergraduate education.

**Topics**
- Lorentz force
- Machine test system
- Torque/speed characteristics
- DC machines
- Separate excitation/shunt-wound/series-wound machines
- Generator operation
- Power characteristics
- Three-phase machines
- Three-phase windings
- Current and voltage in delta and star (Y) circuits
- Reactance of an AC winding
- Power for a three-phase winding
- Synchronous machines
- Function of a stroboscope
- Asynchronous (induction) machines
- Start-up procedure for three-phase machines
- Manual loading above limit of stability
- Power consumption
- Three-phase drives
- Changing speed by altering stator voltage
- Changing speed by altering synchronous speed
- Changing speed by use of V/f operation
- Stepper motors
- Full steps/half steps
### Machine Assembly Kits

#### E2.1.3.1 ELM Basic Machines for Extra-Low Voltage

<table>
<thead>
<tr>
<th>Cat. No.</th>
<th>Description</th>
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<td>Linear motor with coil assembly</td>
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<td>Rotor position pick-up</td>
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* additionally recommended

The experiments use components from the electrical machine teaching models system and utilise safety extra-low voltage. All machines are mounted on a base unit which is set up vertically in a training panel frame.

#### Objectives

- Recognising basic physical principles
- Recording machine characteristics
- Introduction to drive technology
- Use of simple tools (spanners, oil cans etc.)

The knowledge gained from these experiments can be directly applied to the area of industrial machines. The electrical machine teaching models for safety extra-low voltage are therefore the ideal preparation for experimenting with commercial industrial machines.
The experiments are carried out with the industrial machine assembly kits.

Objectives
- Protective measures and electrical safety
- Recording machine characteristics
- Set-up of various electrical machines

Machines with interchangeable rotors consist of a stator and various replaceable rotors. An electrical machine in the 300 W power range only comes into existence when the stator and rotor are put together. The stator has a 4-pole three-phase winding to generate the machine flux, along with a drive-end cap and a terminal box. The stator housing is mounted on a base and can be directly connected to the Machine test system 0.3 (731 989USB). A secure connection between stator and rotor is achieved by means of star-grip bolts, which allow for rapid changing of the rotors. No tools are needed. The rotors are equipped with non-drive-end caps, fan, cover and some include slip-rings, brushes etc. In conjunction with the machine testing system, the model machines then exhibit the typical properties of both synchronous and asynchronous (induction) machines. A DC stator with the relevant rotor is also available.

Highlights
- Comparison of efficiencies and characteristics of machines with different rotors
- Simple assembly for rapid set-up and time-effective lab experiments
- Experiments on high-efficiency rotors

The equipment set is suitable both for student experiments in a lab using low voltage (400 V three-phase) and on a mobile trolley for demonstrations by teachers in a classroom. The experiment procedures are contained in a printed manual. The target group is made up of commercial apprentices and students of electrical machine construction. The course offers experiments at an intermediate level and also allows for the necessary insight into machine behaviour for scientific interpretation at undergraduate level.

Topics
- Recording of torque-speed characteristic
- Determination of nominal ratings for an electrical machine
- Comparison of efficiency for various machines

The experiments are carried out with the industrial machine assembly kits.
The experiments are carried out using assembly kits for the educationally designed electrical machines. This requires simple tools such as screwdrivers and pliers.

Objectives
- Explanation of the components of an electric motor
- Fundamentals of electromagnetism
- DC motors
- Generators
- Series-wound, shunt-wound and compound-wound motors
- Single-phase and three-phase AC motors and generators
- Series-wound, universal and single-phase capacitor motors
- Repulsion, split-phase, shaded-pole and stepper motors
- Faults with electric motors

This training system allows electrical machines to be assembled from individual components and investigated. The topics are highly varied and range from the fundamentals of magnetic fields to commutator and three-phase machines. All the relevant components are visible and only need to be mechanically assembled or electrically connected.

The electrical machine training system utilises the modular concept of the electrical machine teaching models system but using mains voltage (three-phase 400 V). This allows small commercial machines to be assembled step by step in practical laboratory experiments and their ratings can then be determined using the Machine test system 0.3. The procedures for the experiments are contained in a printed manual.

The target group is made up of commercial apprentices and students of power engineering. The course offers experiments at an intermediate level for vocational colleges and undergraduate level.

Topics
- Recording of torque-speed characteristic
- Determination of nominal ratings for an electrical machine
- Comparison of efficiency for various machines
E2  ELECTRICAL DRIVES

E2.2  INDUSTRIAL MACHINES 300 W

E2.2.1  TRANSFORMERS 300 W
E2.2.1.0  Transformers 0.3
E2.2.1.1  3-Phase Transformer 0.3
E2.2.1.2  Scott Transformer 0.3
E2.2.1.3  AC Transformer 0.3
E2.2.1.4  AC Toroidal Core Transformer 0.3
E2.2.1.5  AC Autotransformer 0.3

E2.2.2  DC MACHINES 300 W
E2.2.2.0  DC Machines 0.3
E2.2.2.1  DC Compound Machine 0.3
E2.2.2.2  Universal Motor 0.3

E2.2.3  AC MACHINES 300 W
E2.2.3.0  AC Machines 0.3
E2.2.3.1  Universal Motor 0.3
E2.2.3.2  Capacitor Motor R 0.3
E2.2.3.3  Capacitor Motor CS Basic 0.3

E2.2.4  3-PHASE INDUCTION MACHINES 300 W
E2.2.4.0  Induction Machines 0.3
E2.2.4.1  Squirrel Cage Motor 400/600 0.3
E2.2.4.2  Squirrel Cage Motor 230/400 0.3
E2.2.4.3  Slip Ring Motor 0.3
E2.2.4.4  Squirrel Cage Motor D 0.3
E2.2.4.5  Squirrel Cage Motor SW 0.3
E2.2.4.6  Squirrel Cage Motor 400/690 Basic 0.3
E2.2.4.7  Squirrel Cage Motor 230/400 Basic 0.3
E2.2.4.8  Squirrel Cage Motor 230/400 Brake Basic 0.3

E2.2.5  3-PHASE SYNCHRONOUS MACHINES 300 W
E2.2.5.0  Synchronous Machines 0.3
E2.2.5.1  Salient Pole Rotor 0.3
E2.2.5.2  Smooth Pole Rotor 0.3

E2.2.6  MECHATRONIC MOTORS 300 W
E2.2.6.1  Motor with Frequency Converter 0.3
E2.2.6.2  Brushless DC Machine 0.3
The experiments are carried out using transformers on training panels in panel frames.

**Objectives**
- Protective measures and electrical safety
- Set-up of power generation systems according to circuit diagrams
- Use of commercial measuring instruments, hand-held multimeters, oscilloscopes, measuring interfaces

Transformers are magnetically coupled systems used for transforming AC voltages or matching impedance. Transformers can therefore be used primarily for measurement or generation of electric power. These practical exercises study exclusively transformers used in energy generation. Transformer power ratings can range from a few mVA up to several MVA. The size and design also have an important effect on the transformer ratings. Transformers are regarded as electrical machines even though they contain no moving parts. The windings of three-phase transformers can be connected in a variety of circuit configurations.

Students carry out the experiments as specified in the printed manual. Hand-held multimeters are used to measure the characteristics of the transformers. Display of current or voltage against time is particularly interesting for three-phase equipment, although it is not essential. If this aspect is not required, then it is possible to dispense with the oscilloscope, isolating amplifier etc. or Sensor-CASSY. In this case multimeters are sufficient for measuring RMS values.

The target group is made up of commercial apprentices and students of power engineering. The course offers experiments at an intermediate level for vocational colleges and undergraduate level.

The complete equipment set allows for experiments on all the most important types of transformer in the 300 W rating class.

**Topics**
- Voltage equation and equivalent circuit
- Measurement without load, with load and with a short circuit
- Determination of self-inductance, magnetic coupling and leakage
- Losses, changes in voltage and efficiency
Objectives

• Protective measures and electrical safety
• Setting up electrical machines and putting them into operation
• Use of starting circuits
• Assessment of electrical machine characteristics

Features

• In order to protect against overheating, the stator windings of the test machines are equipped with temperature sensors
• Should overheating occur, the machine testing system automatically shuts down the machine under test, thus preventing any damage to it.
• The test machines are equipped with an educationally designed terminal board with the winding configuration printed on it.
• The ends of all the windings are connected to the terminal board and can be accessed via 4-mm safety sockets
• Computer-supported acquisition of measurement data provides for meaningful measurement results.

The complete set is equally suitable for student experiments in laboratories with low voltage supplies (230 V AC) and for setting up on a mobile trolley for demonstration by teachers in a classroom. The procedures for the experiments are provided in a printed manual.

The target group is made up of commercial apprentices and students of electrical machine construction. The course offers experiments at an intermediate level and also allows for the necessary insight into machine behaviour for scientific interpretation at undergraduate level.

Topics

• Design and function of DC machines
• Armature reaction and commutation
• Series-wound machines
• Possibilities for changing speed
• Energy conversion
• Shunt-wound machines
• Operation at constant speed
• Self-excitation, etc.
Objectives
- Protective measures and electrical safety
- Setting up electrical machines and putting them into operation
- Use of starting circuits
- Assessment of electrical machine characteristics

Features
- In order to protect against overheating, the stator windings of the test machines are equipped with temperature sensors.
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The target group is made up of commercial apprentices and students of electrical machine construction. The course offers experiments at an intermediate level and also allows for the necessary insight into machine behaviour for scientific interpretation at undergraduate level.

In addition to the machines included in the equipment sets, the individual component section of the catalogue also includes special machines such as repulsion motors and auxiliary phase motors, which are available on request.

Topics
- Connection and operation of AC machines
- Reversing direction of rotation
- Measurement of efficiency
- Characteristics of motors
- Load characteristics, etc.
The experiments are carried out using machines of industrial manufacture. All the test machines are equipped with a special base for attachment to the Machine test system 0.3. The system allows the characteristics of the machines under test to be recorded. Power for the machines under test is provided either directly from the mains or via special laboratory power supplies.

Objectives
• Protective measures and electrical safety
• Setting up electrical machines and putting them into operation
• Use of starting circuits
• Assessment of electrical machine characteristics

Features
• In order to protect against overheating, the stator windings of the test machines are equipped with temperature sensors
• Should overheating occur, the machine testing system automatically shuts down the machine under test, thus preventing any damage to it.
• The test machines are equipped with an educationally designed terminal board with the winding configuration printed on it.
• The ends of all the windings are connected to the terminal board and can be accessed via 4-mm safety sockets
• Computer-supported acquisition of measurement data provides for meaningful measurement results.
### Basic Drive

- Squirrel cage motors in the Basic Drive class are industrial machines which are supplied with the manufacturers' original terminal board. An illustration of the winding configuration has been deliberately omitted.
- The safety sockets on the terminal board are safely accessible behind a plexiglass pane.
- The winding terminals are labelled according to international standards.
- Basic Drive machines are supplied with no temperature sensors and need to be protected from overloading by means of a motor protection circuit breaker. The experiments are therefore very similar to industrial practice.
- Basic Drive machines are available exclusively in the 300 W rating class.

The individual equipment set is equally suitable for student experiments in laboratories with low voltage supplies (400 V three-phase) and for setting up on a mobile trolley for demonstration by teachers in a classroom. The procedures for the experiments are provided in a printed manual.

### Topics

- Operation of a switchable pole motor with separate windings at low speed and high speed
- Connection and operation of a switchable pole motor with the help of a pole change-over switch
- Recording of characteristics at low speed and high speed
- Design and function
- Characteristics during motor operation
- Starting
- Star-delta starting
- Stator resistance starting circuit
- Braking
- Power performance of an ideal rotating field machine
- Power flux
- Open-circuit experiment
- Short-circuit load experiment
- Design and function of three-phase generator
- Characteristics during generator operation
- Generator slip
- Self-excitation of an induction generator
- Voltage stability
- Insular operation

---

**3-Phase Induction Machines 300 W**

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* additionally recommended
The experiments are carried out using machines of industrial manufacture. All the test machines are equipped with a special base for attachment to the Machine test system 0.3. The system allows the characteristics of the machines under test to be recorded. Power for the machines under test is provided either directly from the mains or via special laboratory power supplies.

**Objectives**
- Protective measures and electrical safety
- Setting up electrical machines and putting them into operation
- Use of starting circuits
- Assessment of electrical machine characteristics

**Features**
- In order to protect against overheating, the stator windings of the test machines are equipped with temperature sensors
- Should overheating occur, the machine testing system automatically shuts down the machine under test, thus preventing any damage to it.
- The test machines are equipped with an educationally designed terminal board with the winding configuration printed on it.
- The ends of all the windings are connected to the terminal board and can be accessed via 4-mm safety sockets
- Computer-supported acquisition of measurement data provides for meaningful measurement results.

**Synchronous motor topics**
- Non-salient-pole and salient-pole rotor
- Voltage equations
- Equivalent circuit and vector diagram
- Operation with no-load and with a permanent three-pole short-circuit
- Locus diagrams and control characteristics
- Torque and loading
- Potier diagram and armature reaction
- Synchronisation and use of multiple machines in parallel
- Starting methods for synchronous motors
- Control of reactive power
- Power performance

**Synchronous generator topics**
- Voltage generation
- Excitation of synchronous machines
- Operating response
- Armature current and torque
- Braking operation and locus diagrams
- Starting and synchronisation
- Single-phase generators

---

**3-Phase Synchronous Machines 300 W**

E2.2.5.0
Synchronous Machines 0.3

E2.2.5.1
Salient Pole Rotor 0.3

E2.2.5.2
Smooth Pole Rotor 0.3

---

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* additionally recommended
The machine to be tested is an industrial frequency converter motor consisting of a four-pole asynchronous three-phase motor with a power rating of 0.55 kW including an integrated frequency converter. The motor and the converter are optimally fine-tuned to one another. The experiment investigates the features of the operating response in comparison to other types of machine without built-in power electronics. More advanced topics such as positioning control or non-linear load characteristics (winding machines, fans etc.) are investigated in E2.6, Servo technology.

Features
- In order to protect against overheating, the stator windings of the test machines are equipped with temperature sensors
- Should overheating occur, the machine testing system automatically shuts down the machine under test, thus preventing any damage to it.
- The test machines are equipped with an educationally designed terminal board with the winding configuration printed on it.
- The ends of all the windings are connected to the terminal board and can be accessed via 4-mm safety sockets
- Computer-supported acquisition of measurement data provides for meaningful measurement results.

The experiments are carried out using machines of industrial manufacture. All the test machines are equipped with a special base for attachment to the Machine test system 0.3. The system allows the characteristics of the machines under test to be recorded. Power for the machines under test is provided either directly from the mains or via special laboratory power supplies.

Objectives
- Protective measures and electrical safety
- Setting up electrical machines and putting them into operation
- Use of starting circuits
- Assessment of electrical machine characteristics

The individual equipment set is equally suitable for student experiments in laboratories with low voltage supplies (400 V three-phase) and for setting up on a mobile trolley for demonstration by teachers in a classroom. The procedures for the experiments are provided in a printed manual. The target group is made up of commercial apprentices and students of electrical machine construction. The course offers experiments at an intermediate level and also allows for the necessary insight into machine behaviour for scientific interpretation at undergraduate level.

Topics
- Design and function of a frequency converter controlled motor
- Operation with a power amplifier
- Run-up and operating characteristics
- How speed depends on frequency
- How speed depends on load: fan, pump, winding machine, flywheel
Mechatronics machines are used in the field of automation. They are distinguished by their area of application, whereby the physical operating principle is unimportant. AC servo motors (synchronous machine) and frequency converter motors (asynchronous machine) are both used. Mechatronics machines of small to medium power carry out positioning tasks. Control of the machines always requires power electronics components.

Features
- In order to protect against overheating, the stator windings of the test machines are equipped with temperature sensors
- Should overheating occur, the machine testing system automatically shuts down the machine under test, thus preventing any damage to it.
- The test machines are equipped with an educationally designed terminal board with the winding configuration printed on it.
- The ends of all the windings are connected to the terminal board and can be accessed via 4-mm safety sockets
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Objectives
- Protective measures and electrical safety
- Setting up electrical machines and putting them into operation
- Use of starting circuits
- Assessment of electrical machine characteristics

The target group is made up of commercial apprentices and students of electrical machine construction. The course offers experiments at an intermediate level and also allows for the necessary insight into machine behaviour for scientific interpretation at undergraduate level.

Topics
- Design and function
- Operation with a power amplifier
- How current and voltage change over time
- Load characteristics
- Automatic or closed-loop current, speed and positioning control
- Dynamics and changing direction of rotation
- Variable speed and load
E2  ELECTRICAL DRIVES

E2.3  INDUSTRIAL MACHINES 1 KW

E2.3.1  TRANSFORMERS 1 KW
E2.3.1.0  Transformers 1.0
E2.3.1.1  3-Phase Transformer 1.0
E2.3.1.2  Scott Transformer 0.3
E2.3.1.3  AC Transformer 0.3
E2.3.1.4  AC Toroidal Core Transformer 0.3
E2.3.1.5  AC Autotransformer 0.3

E2.3.2  DC MACHINES 1 KW
E2.3.2.0  DC Machines 1.0
E2.3.2.1  DC Compound Machine 1.0
E2.3.2.2  Universal Motor 1.0

E2.3.3  AC MACHINES 1 KW
E2.3.3.0  AC Machines 1.0
E2.3.3.1  Universal Motor 1.0
E2.3.3.2  Capacitor Motor R 1.0

E2.3.4  3-PHASE INDUCTION MACHINES 1 KW
E2.3.4.0  Induction Machines 1.0
E2.3.4.1  Squirrel Cage Motor 400/600 1.0
E2.3.4.2  Squirrel Cage Motor 230/400 1.0
E2.3.4.3  Slip Ring Motor 1.0
E2.3.4.4  Squirrel Cage Motor D 1.0
E2.3.4.5  Squirrel Cage Motor SW 1.0

E2.3.5  3-PHASE SYNCHRONOUS MACHINES 1 KW
E2.3.5.0  Synchronous Machines 1.0
E2.3.5.1  Salient Pole Rotor 1.0
E2.3.5.2  Smooth Core Rotor 1.0

E2.3.6  MECHATRONIC MOTORS 1 KW
E2.3.6.1  Motor with Frequency Converter 1.0
The experiments are carried out using transformers on training panels in panel frames.

### Objectives
- Protective measures and electrical safety
- Set-up of power generation systems according to circuit diagrams
- Use of commercial measuring instruments, hand-held multimeters, oscilloscopes, measuring interfaces

Transformers are magnetically coupled systems used for transforming AC voltages or matching impedance. Transformers can therefore be used primarily for measurement or generation of electric power. These practical exercises study exclusively transformers used in energy generation. Transformer power ratings can range from a few mVA up to several MVA. The size and design also have an important effect on the transformer ratings. Transformers are regarded as electrical machines even though they contain no moving parts. The windings of three-phase transformers can be connected in a variety of circuit configurations.

Students carry out the experiments as specified in the printed manual. Hand-held multimeters are used to measure the characteristics of the transformers. Display of current or voltage against time is particularly interesting for three-phase equipment, although it is not essential. If this aspect is not required, then it is possible to dispense with the oscilloscope, isolating amplifier etc. or Sensor-CASSY. In this case multimeters are sufficient for measuring RMS values.

The target group is made up of commercial apprentices and students of power engineering. The course offers experiments at an intermediate level for vocational colleges and undergraduate level.

The complete equipment set allows for experiments on all the most important types of transformer.

### Topics
- Voltage equation and equivalent circuit
- Measurement without load, with load and with a short circuit
- Determination of self-inductance, magnetic coupling and leakage
- Losses, changes in voltage and efficiency
Objectives
- Protective measures and electrical safety
- Setting up electrical machines and putting them into operation
- Use of starting circuits
- Assessment of electrical machine characteristics

Features
- In order to protect against overheating, the stator windings of the machines to be tested are equipped with temperature sensors.
- Should overheating occur, the machine testing system automatically shuts down the test machine, thus preventing any damage to it.
- The machines to be tested are equipped with an educationally designed terminal board with the winding configuration printed on it.
- The ends of all the windings are connected to the terminal board and can be accessed via 4-mm safety sockets.
- Computer-supported acquisition of measurement data provides for meaningful measurement results.
- Machines in the 1 kW rating class have a powerful and realistic operating response.
- In comparison to smaller machines, their characteristics display distinctive features related to the design.

Topics
- Design and function of DC machines
- Armature reaction and commutation
- Series-wound machines
- Possibilities for changing speed
- Energy conversion
- Shunt-wound machines
- Operation at constant speed
- Self-excitation
- Current-voltage characteristics
- Load characteristics
- Possibilities for changing speed and adjusting for load
- Starting and braking
- Characteristics of generators
- Power performance

The experiments are carried out using industrial-design machines. All the test machines possess a special base for connecting the Machine test system 1.0. The testing system can be used to record the characteristics of the machines under test. Power for the machines is supplied either via the mains or by special laboratory power supplies.
AC Machines 1 kW

E2.3.3.0
AC Machines 1.0

E2.3.3.1
Universal Motor AC 1.0

E2.3.3.2
Capacitor Motor R 1.0

Objectives
- Protective measures and electrical safety
- Setting up electrical machines and putting them into operation
- Use of starting circuits
- Assessment of electrical machine characteristics

Features
- In order to protect against overheating, the stator windings of the machines to be tested are equipped with temperature sensors.
- Should overheating occur the machine testing system automatically shuts down the test machine, thus preventing any damage to it.
- The machines to be tested are equipped with an educationally designed terminal board with the winding configuration printed on it.
- The ends of all the windings are connected to the terminal board and can be accessed via 4-mm safety sockets.
- Computer-supported acquisition of measurement data provides for meaningful measurement results.
- Machines in the 1 kW rating class have a powerful and realistic operating response.
- In comparison to smaller machines, their characteristics display distinctive features related to the design.

The complete equipment set is equally suitable for student experiments in laboratories with low voltage supplies (400 V three-phase) and for setting up on a mobile trolley for demonstration by teachers in a classroom. The procedures for the experiments are provided in a printed manual.

Topics
- Connection and operation of AC machines
- Reversing direction of rotation
- Measurement of efficiency
- Characteristics of motors
- Load characteristics

The experiments are carried out using industrial-design machines. All the machines under test possess a special base for connecting the Machine test system 1.0. The testing system can be used to record the characteristics of the machines under test. Power for the machines is supplied either via a variable transformer.
### Induction Machines 1 kW

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<th>Description</th>
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* additionally recommended

The experiments are carried out using industrial-design machines. All the test machines possess a special base for connecting the Machine test system 1.0. The testing system can be used to record the characteristics of the machines under test. Power for the machines is supplied either via the mains or by special laboratory power supplies.

**Objectives**
- Protective measures and electrical safety
- Setting up electrical machines and putting them into operation
- Use of starting circuits
- Assessment of electrical machine characteristics

**Topics for motor operation**
- Design and function
- Operating characteristics
- Starting: slip-ring rotors, deep-bar squirrel cage rotors, star-delta starting, switching via a starting transformer, stator resistance starting circuit
- Braking: regenerative braking, DC braking, dynamic lowering circuit
- Power performance of an ideal rotating field machine
- Power flux
- Locus (Heyland circle) diagram
- Experiment without any load
- Short-circuit load experiment
under test. Power for the machines is supplied either via the mains or by special laboratory power supplies.

**Objectives**
- Protective measures and electrical safety
- Setting up electrical machines and putting them into operation
- Use of starting circuits
- Assessment of electrical machine characteristics

**Features**
- In order to protect against overheating, the stator windings of the machines to be tested are equipped with temperature sensors
- Should overheating occur the machine testing system automatically shuts down the test machine, thus preventing any damage to it.
- The machines to be tested are equipped with an educationally designed terminal board with the winding configuration printed on it.
- The ends of all the windings are connected to the terminal board and can be accessed via 4-mm safety sockets
- Computer-supported acquisition of measurement data provides for meaningful measurement results.
- Machines in the 1 kW rating class have a powerful and realistic operating response
- In comparison to smaller machines, their characteristics display distinctive features related to the design.

**Synchronous motor topics**
- Non-salient-pole and salient-pole rotors
- Voltage equations
- Equivalent circuit and vector diagram
- Operation with no-load and with a permanent three-pole short-circuit
- Locus diagrams and control characteristics
- Torque and loading
- Potier diagram and armature reaction
- Synchronisation and use of multiple machines in parallel
- Starting methods for synchronous motors
- Control of reactive power
- Power performance

**Synchronous generator topics**
- Voltage generation
- Excitation of synchronous machines
- Operating response
- Armature current and torque
- Braking operation and locus diagrams
- Starting and synchronisation
- Single-phase generators

The experiments are carried out using industrial-design machines. All the test machines possess a special base for connecting the Machine test system 1.0. The testing system can be used to record the characteristics of the machines under test. Power for the machines is supplied either via the mains or by special laboratory power supplies.

**Objectives**
- Protective measures and electrical safety
- Setting up electrical machines and putting them into operation
- Use of starting circuits
- Assessment of electrical machine characteristics

**Features**
- In order to protect against overheating, the stator windings of the machines to be tested are equipped with temperature sensors
- Should overheating occur the machine testing system automatically shuts down the test machine, thus preventing any damage to it.
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- Voltage generation
- Excitation of synchronous machines
- Operating response
- Armature current and torque
- Braking operation and locus diagrams
- Starting and synchronisation
- Single-phase generators
ELECTRICAL DRIVES
INDUSTRIAL MACHINES 1 kW

E2.3.6.1
Motor with Frequency Converter 1.0

Mechatronic Motors 1 kW

The experiments are carried out using industrial-design machines. All the test machines possess a special base for connecting the Machine test system 1.0. The testing system can be used to record the characteristics of the machines under test. Power for the machines is supplied either via the mains or by special laboratory power supplies.

Objectives
• Protective measures and electrical safety
• Setting up electrical machines and putting them into operation
• Use of starting circuits
• Assessment of electrical machine characteristics

The test machine is an industrial frequency converter motor consisting of a four-pole asynchronous three-phase motor with a power rating of 1.1 kW and an integrated frequency converter. The motor and the converter are optimally fine-tuned to one another. The experiment investigates the features of the operating response in comparison to other types of machine without built-in power electronics. More advanced topics such as positioning control or non-linear load characteristics (winding machines, fans etc.) are investigated in E2.6 Servo technology using 300 W machines.

Features
• In order to protect against overheating, the stator windings of the machines to be tested are equipped with temperature sensors
• Should overheating occur the machine testing system automatically shuts down the test machine, thus preventing any damage to it.
• The machines to be tested are equipped with an educationally designed terminal board with the winding configuration printed on it.
• The ends of all the windings are connected to the terminal board and can be accessed via 4-mm safety sockets
• Computer-supported acquisition of measurement data provides for meaningful measurement results.
• Machines in the 1 kW rating class have a powerful and realistic operating response
• In comparison to smaller machines, their characteristics display distinctive features related to the design.

The equipment set is suitable both for student experiments in a lab using low voltage (400 V three-phase) and on a mobile trolley for demonstrations by teachers in a classroom. The experiment procedures are contained in a printed manual.

The target group is made up of commercial apprentices and students of electrical machine construction. The course offers experiments at an intermediate level and also allows for the necessary insight into machine behaviour for scientific interpretation at undergraduate level.

Topics
• Design and function of a frequency converter controlled motor
• Operation with a power amplifier
• Run-up and operating characteristics
• How speed depends on frequency
• How speed depends on load: fan, pump, winding machine, flywheel

Cat. No. | Description | E2.3.6.1
--- | --- | ---
732 49 | Motor with FCC 1.0 | 1
735 314 | LCP2 local control panel | 1
732 689USB | Machine test system 1.0 | 1
728 421 | CBM10 MIMO/FCCP | 1
726 09 | Panel frame T130, two-level | 1
726 75 | Three-phase supply unit with ELCB | 1
732 56 | Coupling 1.0 | 1
732 58 | Coupling guard 1.0 | 1
500 59 | Safety bridging plugs, black, set of 10 | 1
500 591 | Safety bridging plugs, yellow/green, set of 10 | 1
500 854 | Safety leads, set of 20 | 1
735 315USB | USB/RS 485 interface converter | 1*
775 355DE | LIT: E2.3.6.1 Motor with Frequency Converter 1.0 (German) | 1
775 355EN | LIT: E2.3.6.1 Motor with Frequency Converter 1.0 | 1*

* additionally recommended
E2  ELECTRICAL DRIVES

E2.4  POWER ELECTRONICS

E2.4.1  COMPACT SYSTEMS FOR POWER ELECTRONICS
E2.4.1.1  Power Electronics with the Plug-In System
E2.4.1.2  COM3LAB Multimedia: Power Electronics

E2.4.2  LINE-COMMUTATED CONVERTERS
E2.4.2.1  Static Converter Valves
E2.4.2.2  Fault Simulator, Phase Control

E2.4.3  SELF-COMMUTATED CONVERTERS
E2.4.3.1  Switchable Valves and DC choppers
E2.4.3.2  Switched-Mode Power Supplies
E2.4.3.3  Inverters
The experiments are carried out using the STE plug-in system Electricity/Electronics.

**Objectives**
- Recognition of basic physical principles
- Implementation of electrical circuits according to circuit diagrams

The power electronics is an important area within electrical engineering. It links power engineering with control technology and electronics. The advances in the production of semiconductor power devices such as diodes, thyristors, triacs and power transistors have essentially promoted their breakthrough. The main task of power electronics is the switching, controlling and transforming of electrical energy with the help of electronic components.

Student experiments with the plug-in system for power electronics investigate the characteristics of power semiconductors as well as basic standard circuits. All experiments work with single-phase, safety extra-low voltage. The necessary prerequisites for successful running the course are knowledge of AC theory, semiconductor technology and experience in handling the oscilloscope.

The target group is made up of students in general or vocational education. The experiments are designed as an introduction at a simple level of understanding. To gain a deeper understanding, experiments with the compact system E2.4.2.1, static converter valves and the COM3LAB courses on power electronics are ideal.

**Topics**
- Components of power electronics
- Characteristics of thyristors, triacs and diacs
- Thyristors used as DC switches and choppers
- Pulse generators and trigger circuits
- Phase angle control
- Circuits with thyristor trigger components
- Circuits with dimmers: touch dimmers, light dimmers
- Thyristor DC quenching
- Zero-voltage switches
- Full-wave control

<table>
<thead>
<tr>
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<th>Description</th>
<th>Cat. No.</th>
<th>Description</th>
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<td>Supplementary set T 6.1.1B</td>
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</table>

* additionally recommended
The equipment set allows students to experiment themselves in a lab equipped with PCs using safety extra-low voltage, which presents no hazard. It is also suitable for demonstration experiments by teachers. Multimedia software explains and monitors how the experiments are carried out.

The target group mainly consists of trainee industrial or jobbing electricians. The systems can also be used for vocational further education.

To gain a deeper understanding, experiments with the compact system E2.4.2.1, Static converter valves, is ideal.

In project lessons an asynchronous machine (732 104) is operated without a load and supplied with three-phase power (3 x 230 V) via a universal converter (735 297). The parameters for the converter can be set via an interface panel on the board itself which connects directly to the COM3LAB course.

### Topics
- Semiconductors in power electronics
- Wiring and control
- Switching processes and commutation
- Uncontrolled rectifier circuits
- Characteristic values for periodic signals
- Controlled line-commutated converters
- Circuits: M1C, M3C, B2C, B6C
- Semi-controlled rectifiers
- Self-commutated converters
- Semiconductor switches and choppers
- Switches and actuators for DC
- Inverters
- Static converters for closed-loop control
- Static converters for drive technology

### Objectives
- Basic physical principles of power semiconductors
- Design of key basic circuits for power electronics
- Assessment of properties of rectifiers and converters

The COM3LAB courses on power electronics convey the topic in concentrated form to deepen understanding. Characteristics of power semiconductors and the basic standard circuits are investigated. All the experiments work with single-phase safety extra-low voltage, which is non-hazardous. Only small amounts of materials and little space are needed for the experiments. A student desk with a PC is entirely sufficient.

### Compact Systems for Power Electronics

#### E2.4.1.2
COM3LAB Multimedia:
Power Electronics

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<td>COM3LAB master unit (USB)</td>
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<tr>
<td>700 CBTDE</td>
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<td>500 851</td>
<td>Safety connecting leads, 32 A, set of 32</td>
<td>1*</td>
</tr>
<tr>
<td>726 19</td>
<td>Panel frame SL85, single-level</td>
<td>1*</td>
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</tbody>
</table>

* additionally recommended

*Cat. No.*

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### Objectives
- Basic physical principles of power semiconductors
- Design of key basic circuits for power electronics
- Assessment of properties of rectifiers and converters

The target group mainly consists of trainee industrial or jobbing electricians. The systems can also be used for vocational further education.

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- Semiconductor switches and choppers
- Switches and actuators for DC
- Inverters
- Static converters for closed-loop control
- Static converters for drive technology

*Cat. No.*

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- Inverters
- Static converters for closed-loop control
- Static converters for drive technology

*Cat. No.*
The job of power electronics is to switch, control and convert electrical energy using power semiconductors with the best possible efficiency. One key application is drive technology. With the help of modern power electronics it is possible to construct variable-speed drives in DC and three-phase circuits for 4-quadrant operation. Nowadays thyristor speed regulation equipment, smooth starting circuits, frequency converters, servo drives etc. are indispensable in industry, skilled electrical work or households.

The equipment set is suitable both for student experiments in a lab using low voltage (400 V three-phase) and on a mobile trolley for demonstrations by teachers in a classroom. The experiment procedures are contained in a printed manual. The target group is made up of commercial apprentices and students of electrical machine technology. The course offers introductory experiments at a simple level and more advanced topics for undergraduate education.

### Topics
- Single static converters and bidirectional static converters with various loads (R, L, RL)
- Resistive-inductive load with freewheeling diode
- Resistive-inductive load with reverse voltage
- Resistive-capacitive load
- Triac AC power controller
- Fully controlled three-phase power controller
- Semi-controlled three-phase power controller
- Three-phase power controller with two bidirectional pairs
- Controlled rectifier mid-point circuits
- Two-pulse centre-tap control
- Controlled six-pulse centre-tap control, M6
- M6 circuit with resistive load
- M6 circuit with resistive-inductive load
- Controlled bridge rectifier circuits with various loads
- Two-pulse bridge circuit
- Six-pulse bridge circuit
- Fully controlled two-pulse bridge circuit, B2C

The experiments are set up with the help of training panels in panel frames. The static converters with overlay masks show the block circuit diagram and a signal flow plan. They also allow the experiment circuits to be set up in clear fashion. The central, microprocessor-monitored trigger lines allow the converter circuits to be changed quickly.

### Objectives
- Measurement of characteristic variables such as average and root-mean-square values, form factor and ripple
- Phase angle control or pulse group control
- Protective equipment, commutation, control characteristics

Power electronics has developed from the technology of static converters to become one of the most important and all-encompassing areas of electrical engineering.
The experiments are carried out on training panels in panel frames.

**Objectives**
- Protective measures and electrical safety
- Finding and analysing faults in phase angle control circuits
- Use of commercial measuring instruments: hand-held multimeters and oscilloscopes

The fault simulator is a standard dimmer for a resistive load ($P = \text{max. } 1.2 \text{ kW}$) pre-calibrated for minimum value. Various measuring points allow for systematic troubleshooting. There are a total of 20 faults which can be switched and which are of the following categories:
- Breaks
- Short circuits
- Wrong components
- Component faults

The faults are activated by slider switches located behind a lockable cover.

The equipment set is designed for student experiments in a laboratory using low voltage (230 V AC). Experiment procedures are provided in a printed manual.

The target group is students in vocational colleges. The experiments are intended as an introduction at a simple level.

**Topics**
- Investigation of a circuit with some 20 different faults
- Component faults (short circuits, high resistance)
- Breaks in conductors
- High or low-resistance connections within the circuit
- Wrong or missing components (e.g. incorrect values)
The experiments are carried out on training panels in panel frames.

**Objectives**
- Protective measures and electrical safety
- Circuit assembly and wiring according to circuit diagrams
- Use of commercial measuring instruments: hand-held multimeters and oscilloscopes

Static converter valves with gate turn-off can be used to assemble a variety of DC choppers (DC/DC converters). Three different control methods are used for this:
- Pulse width modulation
- Pulse sequence modulation
- Two position control

**Topics**
- Thyristor with quenching circuit
- Power MOSFETs
- Insulated gate bipolar transistors (IGBTs)
- On-state characteristics
- Off-state and switching properties
- Control of DC choppers
- Step-up and step-down converters
- DC choppers using a thyristor with quenching circuit, PWM
- Control characteristic for constant load current
- DC chopper using MOSFETs, PWM, PFM and two-position control
- Single-ended forward and push-pull converters
- Half-bridge and full-bridge forward converters
- DC choppers used for step-up conversion, PWM and two-position control
- Energy recovery operation with PWM
- Energy recovery operation with two-position control
- Characteristics with variable current setpoints
- DC choppers with IGBT used as inverting step-up/step-down controllers with PWM

---

**Cat. No.** | **Description**  
--- | ---
734 02 | Reference variable generator  
735 02 | Diode, 1000 V/10 A  
735 09 | Load for power electronics  
735 18 | Fuses, ultra-rapid set of 3  
735 065 | Rectifier B6, 3X400 V/10 A  
735 095 | Capacitors 2x 1000 µF, 385 V  
735 190 | Phase control noise filter 3 x 4.5 A  
735 341 | Control unit PWM, PFM  
735 342 | MOSFET 500 V/10 A  
735 343 | Thyristor with turn-off circuit 230 V/8 A  
735 346 | IGBT 1000 V/10 A  
501 02 | BNC cable, 1 m  
531 282 | Multimeter Metrahit Pro  
575 231 | Probe 100 MHz, 1:1 / 10:1  
575 230 | Digital storage oscilloscope 722  
735 261 | Isolation amplifier, four channel  
726 09 | Panel frame T130, two-level  
726 86 | Stabilised power supply ±15 V/3 A  
726 80 | Transformer, 45/90, 3 N  
537 34 | Rheostat, 100 ohms  
537 35 | Rheostat, 330 ohms  
731 91 | Shunt wound machine 0.3  
731 07 | Shaft end guard 0.3  
500 59 | Safety bridging plugs, black, set of 10  
500 851 | Safety connecting leads, 32 A, set of 32  
500 852 | Safety connecting leads, 32 A, yellow/green, set of 10  
775 260DE | LIT: E2.4.3.1 Switchable Valves and DC Choppers (German)  
775 260EN | LIT: E2.4.3.1 Switchable Valves and DC Choppers  

* additionally recommended
Power electronics allows for power supplies to be built which are characterised by high efficiency and compact size. This is achieved using switching components and switching frequencies which are as high as possible. The following experiments on primary switched-mode power supplies can be set up and their properties investigated:

- Single-ended forward converters
- Push-pull converters
- Asymmetric half-bridge forward converters
- Full-bridge forward converters
- Flyback converters

The equipment set is suitable both for student experiments in a lab using low voltage (400 V three-phase) and on a mobile trolley for demonstrations by teachers in a classroom. The experiment procedures are contained in a printed manual.

### Topics

- Step-down converters with various loads
- Control of average values for voltage and current using PWM
- How voltage and current change over time with a resistive load
- How voltage and current change over time with a resistive-inductive load
- Resistive-inductive load with freewheeling diode and smoothing capacitor
- Step-down converter with $V_I = 110$ V, losses, efficiency
- Step-up/step-down converters
- Control of average values for voltage and current using PWM
- Measurement of voltage and current over time when $V_I = 15$ V
- Measurement of voltage and current over time when $V_I = 110$ V
- Measurement with intermittent choke current
- Step-up/step-down converters with power factor correction
- Effect of hysteresis
- Flyback converters
- Control of average values for voltage and current using PWM
- Measurement of voltage and current over time when $V_I = 15$ V
- Effect of RCD protective circuitry
- Measurement of voltage and current over time when $V_I = 110$ V

### The experiments are carried out on training panels in panel frames.

### Objectives

- Protective measures and electrical safety
- Circuit assembly and wiring according to circuit diagrams
- Use of commercial measuring instruments: hand-held multimeters and oscilloscopes

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### Switched-Mode Power Supplies (E2.4.3.2)

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<td>Isolation amplifier, four channel</td>
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<td>726 09</td>
<td>Panel frame T130, two-level</td>
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</tr>
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<td>726 86</td>
<td>Stabilised power supply ±15 V/3 A</td>
<td>1</td>
</tr>
<tr>
<td>726 80</td>
<td>Transformer, 45/80, 3 N</td>
<td>1</td>
</tr>
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<td>500 09</td>
<td>Safety bridging plugs, black, set of 10</td>
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<tr>
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</tr>
<tr>
<td>500 852</td>
<td>Safety connecting leads, 32 A, yellow/green, set of 10</td>
<td>1</td>
</tr>
<tr>
<td>775 265DE</td>
<td>LIT: E2.4.3.2 Switched-Mode Power Supplies (German)</td>
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<tr>
<td>775 265SEN</td>
<td>LIT: E2.4.3.2 Switched-Mode Power Supplies</td>
<td>1*</td>
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</tbody>
</table>

* additionally recommended
The experiments are carried out on training panels in panel frames.

**Objectives**

- Protective measures and electrical safety
- Circuit assembly and wiring according to circuit diagrams
- Use of commercial measuring instruments: hand-held multimeters and oscilloscopes

Self commutated inverters are used in frequency converters, uninterruptible power supplies, mains coupling equipment for photovoltaic systems etc. This equipment set makes it possible to construct a single-phase AC inverter to create an AC voltage of variable frequency and amplitude.

The equipment set is suitable both for student experiments in a lab using low voltage (400 V three-phase) and on a mobile trolley for demonstrations by teachers in a classroom. The experiment procedures are contained in a printed manual.

The target group is made up of commercial apprentices and students of electrical machine construction. The course offers experiments at an intermediate level and also allows for the necessary insight into machine behaviour for scientific interpretation at undergraduate level.

**Topics**

- **Single ended forward converter**
  - Control of average values for voltage and current using PWM
  - Measurement of voltage and current over time when $V_i = 30$
  - Measurement of voltage and current over time when $V_i = 115$
  - Measurement of efficiency and voltage stability

- **Asymmetric half-bridge forward converter**
  - Control of average values for voltage and current using PWM
  - Time characteristic when $v = 0.75$
  - Time characteristic when $v = 0.50$
  - Time characteristic with duty cycle switch-over
  - Time characteristic for sinusoidal inverter
  - Inverter with $V_i = 115 V$
  - Inverter with $V_i = 115 V, f = 5 kHz$
E2 ELECTRICAL DRIVES

E2.5 DRIVE TECHNOLOGY

E2.5.1 COMPACT SYSTEMS FOR DRIVE TECHNOLOGY
  E2.5.1.1 COM3LAB Multimedia: Machines & Drives
  E2.5.1.2 Drive Control with Training Panels

E2.5.2 INDUSTRIAL DC DRIVES
  E2.5.2.1 Static Converter Drive with DC Machines
  E2.5.2.2 DC-Chopper Drive with DC Machines

E2.5.3 INDUSTRIAL 3-PHASE DRIVES
  E2.5.3.1 Drives with Induction Machines
  E2.5.3.2 Basics of Frequency Converters
  E2.5.3.3 Drives with Educational Frequency Converter
  E2.5.3.4 Drives with Industry Frequency Converter 0.3
  E2.5.3.5 Drives with Industry Frequency Converter 1.0
as well as reversal of direction and adjustment of speed, plus wiring of the terminal board. The closed-loop control course investigates the fundamentals of variable speed drives. The characteristic parameters for control loops are measured and the design of closed control loops is shown experimentally.

Features
- Compact, highly integrated machine course
- Integrated machine test system
- Extensive charting of technical control loops using DDC controllers

The speed control of a commercially available shunt-wound machine rated at 300 W is investigated as part of a project lesson. It is necessary to use the digital controller from the COM3LAB course, Closed-loop control II, in order to configure and optimise this for the industrial motor.

Topics
- Lorentz force
- Commutator machines
- Series-wound and shunt-wound machines
- Separately excited DC machines
- Adjustment of speed
- Reversal of rotation
- Terminal boards
- Three-phase machines
- Synchronous machines
- Starting response
- Measurement of speed using a stroboscope
- Asynchronous (induction) machines
- Three-phase drives
- V/f mode
- Characteristics, determination of breakdown torque
- Thermal effects
- Measurement of slip
- Stepper motors
- Half- and full-step operation
- PID controllers
- Step responses
- Control errors

The experiments are carried out using the multimedia training system COM3LAB.

Objectives
- Recognising basic physical principles
- Recording machine characteristics
- Introduction to drive technology

The equipment set includes the COM3LAB courses, Electrical machines I and Closed-loop control. This allows important experiments to be conducted in the field of electrical drives. The operating response of electrical machines is investigated in terms of physics and mechanics and by means of speed-torque characteristics. The experiments explore how electrical machines are connected, as well as reversal of direction and adjustment of speed, plus wiring of the terminal board. The closed-loop control course investigates the fundamentals of variable speed drives. The characteristic parameters for control loops are measured and the design of closed control loops is shown experimentally.
Compact Systems for Drive Technology

E2.5.1.2
Drive Control with Training Panels

Features
- Compact machine set with integrated power amplifier
- Integrated electronic load with visual display of power which has been converted into heat
- Integrated measuring instruments for speed and torque
- Pre-filter which can be activated/deactivated to change the system's order

The equipment set incorporates student experiments which can be carried out in a laboratory safely using safety extra-low voltage. Experiment instructions are contained in a manual in either printed or digital form.

The target group is made up of commercial apprentices and students of power engineering. The course offers experiments at an intermediate level for vocational colleges and undergraduate level.

Topics
- Speed-torque characteristic
- Characteristic for generator voltage
- Step response of motors
- Load-dependent step responses
- Automatic speed control using digital controllers
- Closed-loop control of generator voltage
- Steady-state control deviation using P-control
- Aperiodic and oscillating control response
- Determination of optimum operating point
- Control errors due to limiting of manipulated variable
- Effects of dead-time and saturation
- Automatic speed control using software controller
- Setpoint control
- Disturbance control

The PID digital controller Net (734 064N) can be incorporated into a network. The basic software LEYLAB.control Lite or the full version LEYLAB.control (725 006) is needed to operate the equipment. An optional non-networkable version is also available.

The experiments are carried out using training panels in panel frames.

Objectives
- Experiment set-up and wiring according to circuit diagrams
- How to handle closed-loop control systems
- Use of computer-controlled measuring interfaces
- Integration of block-oriented software in practical applications of closed-loop control

The equipment set is mainly concerned with the closed-loop control aspects of electrical drives. In addition, various machine characteristics are measured. The main training system is the 10 W machine set, which makes up a coupled motor-generator system. An integrated electronic load can be connected to the generator. This allows the effects of load fluctuations to be checked.
Objectives

- Protective measures and electrical safety
- Setting up variable speed DC drives and putting them into operation
- Assessment of control response

The equipment set is suitable both for student experiments in a lab using low voltage (400 V three-phase) and on a mobile trolley for demonstrations by teachers in a classroom. The experiment procedures are contained in a printed manual.

Topics

- Automatic control of multi-quadrant drive
- Introduction to the requirements
- Analysis of controlled systems
- Analysis of actuating static converters
- Optimisation of the current control loop
- Recording of armature circuit constants
- Adaptation of current controller
- Adjustment of current limiting
- Optimisation of speed control loop
- Putting thyristor speed control in the first quadrant into operation
- Setting of DC chopper and inverter stability limits
- Recording of static converter control characteristic
- Determination of armature circuit constants
- Recording of the transient function of the controlled variable, armature current
- Determination of the transient of the controlled variable, speed
- Recording a switching diagram

The Function generator 200 kHz Net (726 962N) can be incorporated into a network. The basic software LEYLAB.control Lite (725 007) or the full version LEYLAB.control (725 006) is needed to operate the equipment. An optional non-networkable version is also available.
The experiments are carried out using training panels in panel frames along with a DC machine of industrial design.

Objectives

- Protective measures and electrical safety
- Experiment set-up and wiring according to a circuit diagram
- Setting up industrial commutator machines and putting them into operation
- Use of computer-assisted measurement interfaces

This equipment set allows you to set up a modern drive system in order to adjust the speed. The power electronics is implemented in the form of circuits using modular, discrete components. The load used is a DC machine operating without a load. The chopper allows for the speed to be set by limiting trigger angle and for the direction of rotation to be reversed. The trigger response of thyristors to pulse and burst control is investigated along with the resulting effects on the running characteristics of the machine.

The equipment set is suitable both for student experiments in a lab using low voltage (400 V three-phase) and on a mobile trolley for demonstrations by teachers in a classroom. The experiment procedures are contained in a printed manual.

The target group is made up of commercial apprentices and students of electrical machine construction. The course offers experiments at an intermediate level and also allows for the necessary insight into machine behaviour for scientific interpretation at undergraduate level.

Topics

- Set-up of an H-bridge
- Full-bridge converter
- Reversal of voltage
- Reversal of current
- Setting the speed for DC machines

The function generator 200 kHz Net (726 962N) can be incorporated into a network. The basic software LEYLAB.control Lite (725 007) or the full version LEYLAB.control (725 006) is needed to operate the equipment. An optional non-networkable version is also available.
### Drives with Induction Machines (E2.5.3.1)

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<th>Description</th>
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<tr>
<td>734 02</td>
<td>Reference variable generator</td>
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<tr>
<td>734 19</td>
<td>Gain and offset adjust</td>
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<td>735 07</td>
<td>Thyristor branch pair, 1000 V/12 A</td>
<td>3</td>
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<tr>
<td>735 09</td>
<td>Load for power electronics</td>
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<tr>
<td>735 17</td>
<td>Run-up control unit</td>
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<tr>
<td>735 18</td>
<td>Fuses, ultra-rapid set of 3</td>
<td>2</td>
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<tr>
<td>735 20</td>
<td>Trigger point limiter</td>
<td>1</td>
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<tr>
<td>734 064N</td>
<td>PID digital controller Net</td>
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<tr>
<td>725 007</td>
<td>Software: Leylab.control Lite</td>
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<tr>
<td>735 065</td>
<td>Rectifier B6, 3X400 V/10 A</td>
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<tr>
<td>735 135</td>
<td>Control unit six pulse, digital</td>
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<tr>
<td>735 190</td>
<td>Phase control noise filter 3 x 4.5 A</td>
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<tr>
<td>735 341</td>
<td>Control unit PWM, PFM</td>
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<tr>
<td>735 346</td>
<td>IGBT 1000 V/10 A</td>
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<td>732 28</td>
<td>Multi-function machine 0.3</td>
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<tr>
<td>731 09</td>
<td>Tacho generator 0.3</td>
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<td>732 28</td>
<td>Rotor starter 0.3</td>
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<tr>
<td>727 11</td>
<td>Power meter</td>
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</tr>
<tr>
<td>575 231</td>
<td>Probe 100 MHz, 1.1 / 10:1</td>
<td>2</td>
</tr>
<tr>
<td>575 230</td>
<td>Digital storage oscilloscope 722</td>
<td>1</td>
</tr>
<tr>
<td>735 261</td>
<td>Isolation amplifier, four channel</td>
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<tr>
<td>501 02</td>
<td>BNC cable, 1 m</td>
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<td>731 980USB</td>
<td>Machine test system 0.3</td>
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<td>728 431</td>
<td>CBM10 MOM0FCCP</td>
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<tr>
<td>726 09</td>
<td>Panel frame T100, two-level</td>
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<tr>
<td>726 86</td>
<td>Stabilized power supply ±15 V/3 A</td>
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<tr>
<td>726 75</td>
<td>Three-phase supply unit with ELCB</td>
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<tr>
<td>726 80</td>
<td>Transformer, 45/90, 3 N</td>
<td>1</td>
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<tr>
<td>731 06</td>
<td>Coupling 0.3</td>
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<tr>
<td>731 07</td>
<td>Shaft end guard 0.3</td>
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<td>731 081</td>
<td>Coupling guard 0.3 transparent</td>
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<tr>
<td>500 59</td>
<td>Safety bridging plugs, black, set of 10</td>
<td>2</td>
</tr>
</tbody>
</table>

The PID digital controller Net (734 064N) can be incorporated into a network. The basic software LEYLAB.control Lite or the full version LEYLAB.control (725 006) is needed to operate the equipment. An optional non-networkable version is also available.

### Objectives

- Protective measures and electrical safety
- Set-up of power generating systems according to circuit diagrams
- Putting electrical drives into operation
- Recording of load characteristics with various operating parameters
- Achieving skills in measuring electrical machines
- Automatic speed control for an asynchronous (induction) machine

This equipment set allows experiments on how the speed of asynchronous (induction) machines can be modified using line-commutated static converters. The speed of the machine depends on the stator voltage and rotor impedance and can be adjusted in the experiment by changing these two variables. As well as putting the machine into operation and setting its parameters, the main thing considered is the change in the response of the machine. This involves recording load characteristics and determining key parameters. Addition of a PID controller allows the experiment set-ups to be enhanced into variable-speed drives with closed-loop speed control.

Students work in the power engineering lab with mains voltage. Experiments procedures are contained in a printed manual. The experiments are designed for intermediate and advanced levels.

### Topics

- Drives using motors with slip-ring rotors and three-phase power controllers
- Drives using motors with slip-ring rotors and pulse-controlled rotor impedance
- Drives using motors with slip-ring rotors and static converter cascades

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* additionally recommended
Basics of Frequency Converters

<table>
<thead>
<tr>
<th>Cat. No.</th>
<th>Description</th>
<th>726.5.3.2</th>
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<tbody>
<tr>
<td>735 297</td>
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<tr>
<td>735 09</td>
<td>Load for power electronics</td>
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<tr>
<td>735 296</td>
<td>Converter input/output</td>
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<td>501 02</td>
<td>BNC cable, 1 m</td>
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<tr>
<td>531 282</td>
<td>Multimeter Metrahit Pro</td>
<td>1</td>
</tr>
<tr>
<td>575 231</td>
<td>Probe 100 MHz, 1:1 / 10:1</td>
<td>2</td>
</tr>
<tr>
<td>575 230</td>
<td>Digital storage oscilloscope 722</td>
<td>1</td>
</tr>
<tr>
<td>735 261</td>
<td>Isolation amplifier, four channel</td>
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<td>726 09</td>
<td>Panel frame T130, two-level</td>
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<td>726 71</td>
<td>Single-phase supply unit</td>
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<td>1</td>
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</tbody>
</table>

* additionally recommended

This laboratory practical utilises training panels in panel frames. The power is supplied to the frequency converter directly from the mains (mains voltage, 230 V).

**Objectives**
- Protective measures and electrical safety
- Components of a frequency converter with variable voltage link
- Setting parameters for frequency converters
- Gaining skill in measurement techniques

This equipment set offers an insight into the circuitry of frequency converters with variable voltage link. Measurements are made on the components of a frequency converter especially designed for educational purposes. The experiments use a static electronic load, which facilitates the evaluation of current and voltage curves. A rotating field with variable frequency is also investigated. The following components can be accessed:
- Input bridge rectifier with link capacitor
- Brake chopper
- Power inverter

Students work in the power engineering lab with mains voltage. Experiments procedures are contained in a printed manual. The experiments are designed for intermediate and advanced levels.

**Topics**
- Rotating field and space vectors
- Feeding a sinusoidal signal from the normal three-phase mains network
- Representation of space vectors
- Generation of a rotating field from a DC voltage
- Putting a converter into operation
- Fault-free activation of the mains voltage
- Activation of the input rectifier
- Switching off the converter
- Discharging the buffer capacitor
- Investigation of input rectifier
- Response with zero-delay angle setting, Cl = 0°
- Control characteristic
- Loading
- Control via external control voltage
- Investigation of output inverter
- Control of individual power transistors
- Generation of rotating field
- Loading with resistive load
The power electronics part of this lab practical uses training panels. The electrical machine employed is an industrial machine on a base, whereby the characteristics of the machine can be determined using the Machine test system 0.3. Power is supplied to the machine under test via an educationally designed frequency converter, which obtains its power from the normal mains (mains voltage, 230 V).

Objectives
- Protective measures and electrical safety
- Set-up of power generating systems according to circuit diagrams
- Putting electrical drives into operation
- Recording of load characteristics with various operating parameters
- Achieving skills in measuring electrical machines
- Automatic speed control for an asynchronous (induction) machine

Power electronics has developed from the technology of static converters to become one of the most important and all-encompassing areas of electrical engineering. The job of power electronics is to switch, control and convert electrical energy using power semiconductors with the best possible efficiency. One key application is drive technology. With the help of modern power electronics, it is possible to construct variable speed drives in DC and three-phase circuits for 4-quadrant operation. In this equipment set, a universal converter is used for open- and closed-loop control of speed for a squirrel cage motor.

Students work in the power engineering lab with mains voltage. Experiments procedures are contained in a printed manual. The experiments are designed for intermediate and advanced levels.

Topics
- Rotating field and space vectors
- Modulation types: square, trapezoidal, sinusoidal, pulse width modulation (PWM)
- Voltage vector control VVC
- Magnetisation with a linear V/f characteristic
- Boosting of magnetisation by means of the start voltage
- Optimisation of load characteristics by means of lXr compensation
- Slip compensation
- Operation of the motor in a star configuration
- Computer-assisted measurement and evaluation using CBM 10 software
- Recording a load characteristic
- Comparison of multiple load characteristics
- Brake choppers
- Variable-speed drives
• Recording of load characteristics with various operating parameters
• Achieving skills in measuring electrical machines
• Automatic speed control for an asynchronous (induction) machine
Using switchable converter valves, it is possible to set-up three-phase networks with variable frequency and amplitude. The speed of asynchronous (induction) machines is then variable with practically no losses over a broad range. In this lab, machines in the power class 0.3 kW are used. The equipment set includes an industrial compact converter. The experiments focus on putting converters into operation, setting their parameters and investigating machine response.
Students work in the power engineering lab with mains voltage. Experiments procedures are contained in a printed manual. The experiments are designed for intermediate and advanced levels.

Topics
• Fundamentals of three-phase machines
• Equivalent circuit for an asynchronous (induction) motor
• Torque, efficiency and optimum magnetisation
• Circuit wiring and connection of components
• Setting up a drive and testing its operation
• Parameter setting for a frequency converter
• Learning the key menus
• Measurement of converter output voltage
• Effect of start voltage
• Effect of start compensation (I&X compensation)
• Response of the machine in the absence of starting voltage and compensation
• Effect of slip compensation
• Recording of V/f characteristic for a machine operating without a load, with and without compensation of the frequency converter

The power electronics part of this lab practical uses training panels. The electrical machine employed is an industrial machine on a base, whereby the characteristics of the machine can be determined using the Machine test system 0.3. Power is supplied to the machine under test via an industrial frequency converter, which obtains its power from the normal mains power supply (mains voltage, 230 V).

Objectives
• Protective measures and electrical safety
• Set-up of power generating systems according to circuit diagrams
• Putting electrical drives into operation
• Recording of load characteristics with various operating parameters
• Achieving skills in measuring electrical machines
• Automatic speed control for an asynchronous (induction) machine

Using switchable converter valves, it is possible to set-up three-phase networks with variable frequency and amplitude. The speed of asynchronous (induction) machines is then variable with practically no losses over a broad range. Motors in the 1.0 kW rating class are used in this practical. The equipment set includes an industrial compact converter. The experiments focus on putting converters into operation, setting their parameters and investigating machine response. Students work in the power engineering lab with mains voltage. Experiments procedures are contained in a printed manual.

The experiments are designed for intermediate and advanced levels.

Topics
• Fundamentals of three-phase machines
• Equivalent circuit for an asynchronous (induction) motor
• Torque, efficiency and optimum magnetisation
• Circuit wiring and connection of components
• Setting up a drive and testing its operation
• Parameter setting for a frequency converter
• Learning the key menus
• Measurement of converter output voltage
• Effect of start voltage
• Effect of start compensation (IxR compensation)
• Response of the machine in the absence of starting voltage and compensation
• Effect of slip compensation
• Recording of V/f characteristic for a machine operating without a load, with and without compensation of the frequency converter

The power electronics part of this lab practical uses training panels. The electrical machine employed is an industrial machine on a base, whereby the characteristics of the machine can be determined using the Machine test system 1.0. Power is supplied to the machine under test via an industrial frequency converter, which obtains its power from the normal (three-phase) mains.

Objectives
• Protective measures and electrical safety
• Set-up of power generating systems according to circuit diagrams
• Putting electrical drives into operation

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<th>Description</th>
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<td>735 3101</td>
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<td>732 81</td>
<td>Squirrel cage motor 400/690 1.0</td>
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<td>Multimeter Metrahit Pro</td>
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<td>732 689USB</td>
<td>Machine test system 1.0</td>
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<td>CBM10 MMSI/CCP</td>
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<td>732 56</td>
<td>Coupling 1.0</td>
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<td>Coupling guard 1.0</td>
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<td>LIT: E2.5.3.5 Drives with Industry Frequency Converter 1.0</td>
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* additionally recommended
E2  ELECTRICAL DRIVES

E2.6  Servo Technology

E2.6.1  Educationally Designed Servos
  E2.6.1.1  Basics of Servo Technology
  E2.6.1.2  DC Servo
  E2.6.1.3  AC Servo
  E2.6.1.4  Stepper Motor

E2.6.2  Industrial Servos 300 W
  E2.6.2.1  AC Servo with Block Commutation
  E2.6.2.2  AC Servo with Sine Commutation
  E2.6.2.3  Position Servo Control
Servos are drives used for open- and closed-loop control of position, speed or torque. In manufacturing, servos are often used as auxiliary drives for positioning items being worked on by machines. Servos are used in that sphere in CNC machines or robots. The requirements for servos demand high accuracy, dynamic properties and resilience to overloading.

The experiments are carried using training panels in panel frames.

Objectives

- Experiment set-up and wiring according to circuit diagrams
- Working with closed-loop control systems
- Optimisation of servo systems
- Use of computer-controlled measuring interfaces

The equipment set incorporates student experiments which can be carried out in a laboratory safely using safety extra-low voltage. Experiment instructions are contained in a manual in either printed or digital form.

The target group is made up of commercial apprentices and students of power engineering and mechatronics. The course offers introductory experiments at an intermediate level for vocational schools and colleges.

Topics

- Operation with a P-controller: determination of system deviation (error signals) or oscillation
- Operation with a PI-controller: elimination of system deviation (error signals), overshoot and tracking error
- Operation with a PID-controller: optimisation of system deviation (error signals) and oscillation

The Function generator 200 kHz Net (726 962N) can be incorporated into a network. The basic software LEYLAB.control Lite (725 007) or the full version LEYLAB.control (725 006) is needed to operate the equipment. An optional non-networkable version is also available.

---

**Basics of Servo Technology (E2.6.1.1)**

<table>
<thead>
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<tr>
<td>734 10</td>
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<td>1</td>
</tr>
<tr>
<td>734 13</td>
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<td>DC servo</td>
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<td>734 084N</td>
<td>PID digital controller Net</td>
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<td>Profi-CASSY Starter 2</td>
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<td>500 851</td>
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* additionally recommended
Servos are drives used for open- and closed-loop control of position, speed or torque. In manufacturing, servos are often used as auxiliary drives for positioning items being worked on by machines. Servos are used in that sphere in CNC machines or robots. The requirements for servos demand high accuracy, dynamic properties and resilience to overloading.

The experiments are carried using training panels in panel frames.

Objectives

- Experiment set-up and wiring according to circuit diagrams
- Working with closed-loop control systems
- Optimisation of servo systems
- Use of computer-controlled measuring interfaces

The equipment set incorporates student experiments which can be carried out in a laboratory safely using safety extra-low voltage. Experiment instructions are contained in a manual in either printed or digital form.

The target group is made up of commercial apprentices and students of power engineering and mechatronics. The course offers introductory experiments at an intermediate level for vocational schools and colleges.

Topics

- Recording of step response
- Determination of $K_{\text{p,\text{lim}}}$ und $T_{\text{GR}}$ and calculation of settings for P, PI and PID systems
- Closed-loop step response for P-controller
- Correction for $K_p$ with respect to integral-action systems
- Step response for PID-controller
- Determination of limiting frequency of servos
- Use of measurement interfaces

The PID digital controller Net (734 064N) can be incorporated into a network. The basic software LEYLAB.control Lite or the full version LEYLAB.control (725 006) is needed to operate the equipment. An optional non-networkable version is also available.

---

**Educationally Designed Servos**

E2.6.1.2

DC Servo

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<tr>
<td>734 13</td>
<td>Power amplifier</td>
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<td>734 44</td>
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<td>734 064N</td>
<td>PID digital controller Net</td>
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<td>Software: Leylab.control Lite</td>
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<td>Panel frame T130, two-level</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>726 86</td>
<td>Stabilised power supply ±15 V/3 A</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>579 13</td>
<td>Toggle switch, STE 2/19</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>734 36</td>
<td>Weight disc with hook</td>
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<td></td>
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<tr>
<td>500 59</td>
<td>Safety bridging plugs, black, set of 10</td>
<td>1</td>
<td></td>
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<tr>
<td>500 851</td>
<td>Safety connecting leads, 32 A, set of 32</td>
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<td>775 325DE</td>
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The equipment set incorporates student experiments which can be carried out in a laboratory safely using safety extra-low voltage. Experiment instructions are contained in a manual in either printed or digital form.

The target group is made up of commercial apprentices and students of power engineering and mechatronics. The course offers introductory experiments at an intermediate level for vocational schools and colleges.

Topics

- Open control loops
- Display of voltage across main and auxiliary coils when moving clockwise or anti-clockwise
- Frequencies, synchronous speeds and potentiometer speeds for various desired setpoint values
- Calculation of gear reduction
- Experiments on closed control loops
- Operation with a setpoint integrator
- Response to reversal as a function of the rate of rise in the setpoint
- Response to reversal as a function of the controller gain $K_p$

**Educationally Designed Servos**

<table>
<thead>
<tr>
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<th>Description</th>
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<td>734 45</td>
<td>AC servo</td>
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<td>734 36</td>
<td>Weight disc with hook</td>
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<td>579 13</td>
<td>Toggle switch, STE 2/19</td>
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<td>524 01652</td>
<td>Profi-CASSY Starter 2</td>
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<td>Panel frame T130, two-level</td>
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</tr>
<tr>
<td>728 86</td>
<td>Stabilised power supply ±15 V/3 A</td>
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</tr>
<tr>
<td>500 59</td>
<td>Safety bridging plugs, black, set of 10</td>
<td>1</td>
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<tr>
<td>500 851</td>
<td>Safety connecting leads, 32 A, set of 32</td>
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</tr>
<tr>
<td>775 330DE</td>
<td>LIT: E2.6.1.3 AC Servos (German)</td>
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<tr>
<td>775 330EN</td>
<td>LIT: E2.6.1.3 AC Servos</td>
<td>1*</td>
</tr>
</tbody>
</table>

* additionally recommended
Stepper motors are a special variety of synchronous motor with a large number of pole pairs. The rotor follows the stator field in steps, the size of which is determined by the number of poles. With normal loading, the angular position of the rotor can be determined precisely. If overloaded, however, step losses arise and information about the current position of the rotor is lost. Stepper motors can be wired to operate in both half-step and full-step modes. Due to their discontinuous operation, stepper motors are the ideal drive systems for digital servo systems.

The equipment set incorporates student experiments which can be carried out in a laboratory safely using safety extra-low voltage. Experiment instructions are contained in a manual in either printed or digital form.

The target group is made up of commercial apprentices and students of power engineering and mechatronics. The course offers introductory experiments at an intermediate level for vocational schools and colleges.

**Topics**
- Operation of a simple stepper motor: half-step, full-step
- Design of a stepper motor: function, step angle
- Control methods for bipolar and unipolar stepper motors
- Control program for full and half steps using a unipolar stepper motor
- Control logic with external control
- Dynamic response
- Time constants of the windings
- Rate of rise in current as a function of the clocking frequency
- Starting/stopping regions: start frequencies
- Mechanical resonances: effect of load coupling
- Response as a function of clock frequency

The Function generator 200 kHz Net (726 962N) can be incorporated into a network. The basic software LEYLAB.control Lite (725 007) or the full version LEYLAB.control (725 006) is needed to operate the equipment. An optional non-networkable version is also available.

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For industrial robots, packing machines, NC tooling machines and similar applications, servo drives are needed which are very fast but also very precise in their positioning. These are automatic position-controlled electrical drives, which usually consist of a permanently excited synchronous rotor, a frequency converter with a variable voltage link circuit and digital closed-loop control. A sensor detects the angular position of the motor shaft and uses the information to control the converter.

Power electronics, control equipment, etc. are set up in training panel frames. The servo machine used here is a dynamic industrial machine with a particularly small moment of inertia. The load characteristics can be recorded using the Machine test system 0.3. Power is supplied to the machine under test via a frequency converter especially designed for educational purposes which obtains its power from the mains (mains voltage, 230 V).

Objectives
- Protective measures and electrical safety
- Set-up of power generating systems according to circuit diagrams
- Putting electrical drives into operation
- Recording of load characteristics with various operating parameters
- Achieving skills in measuring electrical machines
- Automatic speed control for an AC servo machine

An AC servo consists of a permanently excited synchronous rotor, a frequency converter with a variable voltage link circuit and digital closed-loop control. A sensor detects the angular position of the motor shaft and uses the information to control the converter. This equipment set investigates AC servos with block commutation. Advanced experiments can be found in the equipment set E2.6.2.3 Position Servo Control.

Topics
- Coupling of motor and commutation sensor
- Steady-state response
- Load characteristics
- Measurement of motor current
- Variation of duty cycle
- Variation variable voltage link
- Variation of commutation angle
- Dynamic response
- Structure of the controlled system
- Stress cycle with servo position control

* additionally recommended
Power electronics, control equipment, etc. are set up in training panel frames. The servo machine used here is a dynamic industrial machine with a particularly small moment of inertia. The load characteristics can be recorded using the Machine test system 0.3. Power is supplied to the machine under test via a frequency converter especially designed for educational purposes which obtains its power from the mains (mains voltage, 230 V).

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- Protective measures and electrical safety
- Set-up of power generating systems according to circuit diagrams
- Putting electrical drives into operation
- Recording of load characteristics with various operating parameters
- Achieving skills in measuring electrical machines
- Automatic speed control for an AC servo machine

Sinusoidally commutated drives are more complex to implement than block-commutated drives, but they do have advantages which can justify the extra complexity. The sensor system uses a so-called resolver, which not only provides very accurate information on the absolute position of the rotor, it also outputs a speedometer voltage reflecting the motor speed. From information on the displacement or angle, signals can be derived which can then be used directly for positioning.

Students work in the power engineering lab with mains voltage. Experiments procedures are contained in a printed manual.

The experiments are designed for intermediate and advanced levels.
### Position Servo Control (E2.6.2.3)

<table>
<thead>
<tr>
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<td>728 71</td>
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<td>AC servo motor 0.3</td>
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<td>531 282</td>
<td>Multimeter Metrahit Pro</td>
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<td>Converter input/output</td>
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<td>CBC 12.5 Servo technology</td>
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<td>Linear unit 0.3</td>
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<td>Panel frame T130, two-level</td>
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<td>728 410</td>
<td>CBC 12.5 Servo technology</td>
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<td>Single-phase supply unit</td>
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<td>Shaft end guard 0.3</td>
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<td>Coupling 0.3</td>
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<td>Coupling 0.3</td>
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</table>

Inverters, control units etc. are mounted in panel frames. The servo machine is a dynamic industrial machine with a particularly small moment of inertia. The power supply for the test machine comes from a didactic frequency converter, which is fed from the mains power source (mains voltage 230 V).

**Objectives**
- Protective measures and electrical safety
- Set-up of power generating systems according to circuit diagrams
- Putting electrical drives into operation
- Achieving skills in measuring electrical machines
- Automatic speed control for an AC servo machine

**Topics**
- Dynamic response of AC servo drives with block commutation
- Dynamic response of AC servo drives with sinusoidal commutation
- Investigation of angular acceleration as a function of the maximum current
- Closed-loop position control with or without secondary current and speed controllers
- Investigation of the time needed for position and of overshoot as a function of speed and maximum current as well as ramp time
- Investigation of tracking (delay) errors
- Direct and indirect servo position control using a linear unit
- Direct servo position control via external analog position controller and potentiometric angle sensor
- Simulation of a work process
- Comparison of AC servo drives with block and sinusoidal commutation

The PID digital controller Net (734 064N) can be incorporated into a network. The basic software LEYLAB.control Lite or the full version LEYLAB.control (725 006) is needed to operate the equipment. An optional non-networkable version is also available.
INDIVIDUAL COMPONENTS IN NUMERICAL ORDER

On the following pages you will find all individual components in numerical order of the catalogue numbers.
Digital hand-held tachometer

For contact-type measurements, battery operated, built-in memory function.

Technical data:
- Range: 1 to 25,000 rpm
- Accuracy: ±1 rpm
- Display: 5 digits, large 7-segment LCD
- Dimensions: 133 mm x 74 mm x 32 mm
- Weight: 200 g including batteries

Scope of delivery:
Complete with carrying case, 3 batteries, 2 conical adapters and 1 funnel-shaped, 1 measurement disc for the measurement of circumferential velocity, 0.1 m.

| 313 20 | Digital hand-held speedometer |

Plug-in axles, set of 2

Designed to act as the fulcrum about which a lever can rotate (340 831).

Technical data:
- Diameter of axle: 4 mm
- Diameter of plug pin: 4 mm
- Total length: 5.5 cm

| 340 811ET2 | Plug-in axles, set of 2 |

Rubber rings, set of 50

Circumference (loose): 30 cm each

| 340 900 | Rubber rings, set of 50 |

Pulley 100 mm Ø, plug-in, pair, set of 2

With cord groove, friction bearing, axial plug-in pin and socket. Plug and socket diameter: 4 mm each

Technical data:
- Effective pulley diameter: 100 mm
- Sockets on pulley disc: 4 in 25 mm

| 340 921ET2 | Pulley 100 mm Ø, plug-in, pair, set of 2 |

Necessary for block and tackle:
1 Set of 2 pulleys, 50 mm
1 Set of 2 pulleys, 100 mm
1 Set of 2 pulley blocks
1 Load hook from 340 87ET2
1 Support clip, plug-in from 314 04ET5
1 Demonstration line 309 50

Candles, set of 20

Technical data:
- Length: 15.5 cm
- Diameter: 1.2 cm

| 459 32 | Candles, set of 20 |
INDIVIDUAL COMPONENTS

Bridging plugs

<table>
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<th>Designation</th>
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<tr>
<td>500 59</td>
<td>Safety bridging plugs, black, set of 10</td>
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<td>500 591</td>
<td>Safety bridging plugs, yellow/green, set of 10</td>
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<tr>
<td>500 592</td>
<td>Safety bridging plugs with tap, black, set of 10</td>
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<tr>
<td>501 48</td>
<td>Bridging plugs, STE 2/19, set of 10</td>
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</table>

Connecting leads

<table>
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<tr>
<th>Cat.-No.</th>
<th>Designation</th>
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<tbody>
<tr>
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</tr>
<tr>
<td>500 644</td>
<td>Safety connecting lead, 100 cm, black</td>
</tr>
<tr>
<td>500 851</td>
<td>Safety connecting leads, 32 A, set of 32</td>
</tr>
<tr>
<td>500 852</td>
<td>Safety connecting leads, 32 A, yellow/green, set of 10</td>
</tr>
<tr>
<td>501 44</td>
<td>Connecting leads, 19 A, 25 cm, red/blue, pair</td>
</tr>
<tr>
<td>501 441</td>
<td>Connecting lead, 19 A, 25 cm, black, pair</td>
</tr>
<tr>
<td>501 45</td>
<td>Connecting lead, 19 A, 50 cm, red/blue, pair</td>
</tr>
</tbody>
</table>

BNC cable, 1 m

Technical data:
- Plugs: BNC/BNC
- Impedance: 50 Ω

<table>
<thead>
<tr>
<th>Cat.-No.</th>
<th>Designation</th>
</tr>
</thead>
<tbody>
<tr>
<td>501 02</td>
<td>BNC cable, 1 m</td>
</tr>
</tbody>
</table>

Connecting leads, 19 A, set of 30

For extra-low voltage circuits. Copper wire, equipped at both ends with a plug and fully insulated axial socket for connecting further cables, with tension relief.

Technical data:
- Plugs and sockets: 4 mm diameter (nickel coated)
- Conductor cross section: 1.0 mm²
- Continuous current: 19 A max.
- Contact resistance: 1.8 mΩ

Scope of delivery:

<table>
<thead>
<tr>
<th>Count</th>
<th>Cat.-No.</th>
<th>Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>3</td>
<td>500 411</td>
<td>Connecting lead, 19 A, 25 cm, red</td>
</tr>
<tr>
<td>3</td>
<td>500 412</td>
<td>Connecting lead, 19 A, 25 cm, blue</td>
</tr>
<tr>
<td>6</td>
<td>500 414</td>
<td>Connecting lead, 19 A, 25 cm, black</td>
</tr>
<tr>
<td>4</td>
<td>500 421</td>
<td>Connecting lead 19 A, 50 cm, red</td>
</tr>
<tr>
<td>4</td>
<td>500 422</td>
<td>Connecting lead 19 A, 50 cm, blue</td>
</tr>
<tr>
<td>4</td>
<td>500 424</td>
<td>Connecting lead 19 A, 50 cm, black</td>
</tr>
<tr>
<td>2</td>
<td>500 441</td>
<td>Connecting lead 19 A, 100 cm, red</td>
</tr>
<tr>
<td>2</td>
<td>500 442</td>
<td>Connecting lead 19 A, 100 cm, blue</td>
</tr>
<tr>
<td>2</td>
<td>500 444</td>
<td>Connecting lead 19 A, 100 cm, black</td>
</tr>
</tbody>
</table>

| 501 532 | Connecting leads, 19 A, set of 30 |

www.ld-didactic.com
Light

<table>
<thead>
<tr>
<th>Cat.–No.</th>
<th>Designation</th>
</tr>
</thead>
<tbody>
<tr>
<td>505 07</td>
<td>Bulbs, 4 V/0.16 W, E10, set of 10</td>
</tr>
<tr>
<td>505 08</td>
<td>Bulbs, 12 V/3 W, E10, set of 10</td>
</tr>
<tr>
<td>505 11</td>
<td>Bulbs, 2.5 V/0.25 W, E10, set of 10</td>
</tr>
<tr>
<td>505 171</td>
<td>Bulbs, 6 V/1.1 W, E10, set of 10</td>
</tr>
<tr>
<td>505 191</td>
<td>Bulbs, 15 V/2 W, E10, set of 5</td>
</tr>
</tbody>
</table>

Bulb, 230 V/40 W, E14

Technical data:
- Voltage: 230 V
- Current: 0.18 A
- Power: 40 W
- Socket: E 14

<table>
<thead>
<tr>
<th>Cat.–No.</th>
<th>Designation</th>
</tr>
</thead>
<tbody>
<tr>
<td>505 27</td>
<td>Bulb, 230 V/40 W, E14</td>
</tr>
</tbody>
</table>

Magnets, 35 mm Ø, pair

Cylindrical magnets (ferrite) with axial bore and coloured north-pole marking.

Technical data:
- Bore diameter: 6.2 mm
- Poles: colour coded
- Diameter: 35 mm
- Height: 20 mm

<table>
<thead>
<tr>
<th>Cat.–No.</th>
<th>Designation</th>
</tr>
</thead>
<tbody>
<tr>
<td>510 48</td>
<td>Magnets, 35 mm Ø, pair</td>
</tr>
</tbody>
</table>

AC/DC power supply, 0...12 V/3 A

With variable and regulated output voltage and analog display instrument, additional 4 AC voltage outputs. AC and DC voltage outputs electrically isolated, therefore especially suitable for students and practical experiments.

Technical data:
- Output voltages: 0 - 12 V DC, continuously adjustable
  3, 6, 9, 12 V AC
- Output current: Max. 3 A
- Stabilisation: < 1%
- Residual ripple: 2 mV approx.
- Overload protection, short circuit-proofed by means of multifuses, safe from external voltage
- Primary fuse: T 1
- Connections: 4-mm safety sockets
- Connection voltage: 230 V, 50/60 Hz
- Dimensions: 23 cm x 12 cm x 19 cm
- Weight: 5.2 kg

<table>
<thead>
<tr>
<th>Cat.–No.</th>
<th>Designation</th>
</tr>
</thead>
<tbody>
<tr>
<td>521 485</td>
<td>AC/DC power supply, 0...12 V/3 A</td>
</tr>
</tbody>
</table>
INDIVIDUAL COMPONENTS

Function generator S 12

Sine, triangle and square-wave generator, continuous frequency adjustment in six decade ranges, with built-in power amplifier. Ideal for students’ experiments because of its small footprint and low-profile design. Safety extra-low voltage power supply.

Technical data:
- Signal waveforms:
  - Sinusoidal, triangular, square-wave
- Frequency range: 0.1 Hz to 20 kHz
- Power output for all types of signal (switchable):
  0 to 12 V across 8 Ω, continuously adjustable, via 4-mm sockets
- Distortion (sine-wave): < 3% (1 kHz)
- Mark-to-space (square-wave): 1:1
- Rise time (square-wave): 2 µs
- Supply voltage: 12 V AC 50/60 Hz (via power supply unit, included)
- Power consumption: 20 VA
- Dimensions: 6 cm x 12 cm x 7 cm
- Weight: 0.5 kg

522 621 Function generator S 12

Adapter, USB port/serial port

For connecting LD equipment with a serial port to computers with USB ports. Especially tested for ease of operation with CASSY and CDM3LAB, including driver CD for Windows and MacOS.

524 004 Adapter, USB port/serial port

Sensor-CASSY 2

Cascadable interface device for recording measurement data

- For connection to the USB port of a computer, another CASSY module or the CASSY display (524 020USB)
- Sensor-CASSY (524 010), Sensor-CASSY 2 and Power-CASSY (524 011USB) can be mixed in cascades
- 3-fold electrical isolation (4-mm inputs A and B, relay R)
- Measurement possible simultaneously at 4-mm inputs and sensor box connector sites (4 channels)
- Cascading of up to 8 CASSY modules possible (to expand the inputs and outputs)
- Up to 8 analog inputs can be provided by adding Sensor-CASSY sensor boxes
- Automatic sensor box detection (plug and play) by CASSY Lab 2 (524 220)
- Microprocessor-controlled with CASSY operating system (easily updatable via software for function enhancements)
- For use as a bench-top, console or demonstration unit (also in CPS/TPS panel frames)
- Voltage supply 12 V AC/DC via cannon plug or adjacent CASSY module
- Developer Information and LabVIEW™ driver available through our internet homepage

Technical data:
- 5 analog inputs
  2 analog voltage inputs A and B on 4-mm safety sockets (electrically isolated)
  Resolution: 12 bits
  Measuring ranges: ±0.1/±0.3/±1/±3/±10/±30/±100/±250 V
  Measurement error: ±1% plus 0.5% of range end value
  Input resistance: 1 MΩ
  Scanning rate: up to 1 MHz per input
  Amount of measured values: nearly unlimited (dependent on PC) up to 10,000 values/s, at higher measuring rate max. 200,000 values
  Pre-trigger: up to 50,000 values per input
  1 analog current input A on 4-mm safety sockets (alternatively to voltage input A)
  Measuring ranges: ±0.03/±0.1/±0.3/±1/±3 A
  Measurement error: voltage error plus 1%
  Input resistance: < 0.5 Ω
INDIVIDUAL COMPONENTS

Scanning rate: up to 1 MHz per input
See voltage inputs for further data

2 analog inputs at sensor box connector sites A and B
(All CASSY sensor boxes and sensors can be connected)
Measuring ranges: ±0.003/±0.01/±0.03/±0.1/±0.3/±1 V
Input resistance: 10 kΩ
Scanning rate: up to 500 kHz per input
See voltage inputs for further data

The technical data will change depending on a connected sensor box. In this case CASSY Lab 2 automatically
detects the possible measurement quantities and ranges when a sensor box is attached.

- 4 timer inputs with 32-bit counters at sensor box sites A and B (e.g. for GM box, timer box or Timer S)
Counting frequency: max. 1 MHz
Time resolution: 20 ns
- 5 LED status indicators for analog inputs and USB-port
  Colours: red and green, according to status
  Light intensity: adjustable
- 1 change-over relay (switching indication via LED)
  Range: max. 250 V/2 A
- 1 analog output (LED switching state indicator, e.g. for holding magnet or supplying experiment)
  Variable voltage range: max. 16 V/200 mA (load ≥ 80Ω)
- 12 digital inputs (TTL) on sensor box sites A and B (at present only used for automatic sensor box detection)
- 6 digital outputs (TTL) on sensor box sites A and B (at present only used for automatic switching of a sensor box
  measuring range)
- 1 USB port for connection to a computer
- 1 CASSY bus for connecting additional CASSY modules
- Dimensions (WxHxD): 115 mm x 295 mm x 45 mm
- Weight: 1.0 kg

Scope of delivery:
- Sensor-CASSY 2
- CASSY Lab 2 software, without activation code, with comprehensive help function (16 full-functionality sessions
  free, then usable as demo version)
- USB cable
- Plug-in supply unit 230 V, 12 V/1.6 A

Sensor-CASSY 2 Starter

Voltage and current input are already integrated into the Sensor-CASSY module. Therefore following experiments
can be implemented without additional sensors:
- Voltage and current measurement
- Ohm’s law
- Electric oscillations
- Characteristic curves
- AC circuit
- Active power

Scope of delivery:

<table>
<thead>
<tr>
<th>Count</th>
<th>Cat.-No.</th>
<th>Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>524 013</td>
<td>Sensor-CASSY 2</td>
</tr>
<tr>
<td>1</td>
<td>524 220</td>
<td>CASSY Lab 2</td>
</tr>
</tbody>
</table>

524 013S Sensor-CASSY 2 Starter
Profi-CASSY Starter 2

The Profi-CASSY starter package is intended for unlimited experimentation. It consists of a Profi-CASSY module with interface [524 016], plus CASSY Lab 2 software (524 220).

Technical data:
- 16 digital inputs I0 to I15
  - (5 V or 24 V logic)
  - Sampling rate: max. 100 values/s
- 16 digital outputs, Q0 to Q15
  - (5 V or 24 V logic)
  - Output current: 10 mA with internal 5 V power supply, 500 mA via external power supply of up to 30 V
  - Total current: 2 A
  - The digital inputs/outputs are each equipped with 10-pin plugs for direct connection to automation equipment.
- Also 8 inputs and 8 outputs are additionally equipped with 2-mm sockets and status LEDs
- 2 analog voltage inputs, A and B
  - 4-mm safety sockets
  - Resolution: 12 bits
  - Amplitude: ±10 V
  - Measuring error: ±1% plus 0.5% from the end value of range
  - Input resistance: 1 MΩ
  - Sampling rate: max. 10,000 values/s
- 2 analog outputs, X and Y
  - 4-mm safety sockets
  - Amplitude: ± 10 V
  - Output current: max. 100 mA per Output
  - Resolution: 12 bits, measuring error: ±1% plus 0.5% from the end value of range
  - Sampling rate: 10,000 values/s
- 1 PROFIBUS connection
  - 9-pin DSUB socket
  - Passive user (slave) on fieldbus PROFIBUS-DP
  - Address adjustable via software with 16 digital inputs/outputs
  - Transmission rate up to max. 3 Mbits/s
- USB port
  - for connection to PC
- 1 CASSY-Bus module
  - or connection to Sensor- or Power-CASSY modules
- Dimensions (BxHxT): 115 mm x 295 mm x 45 mm
- Weight: 1 kg

Scope of delivery:
- 1 Profi-CASSY module
- CASSY lab software with enable code for Windows XP/Vista/7/8 (32+64 bit) and extensive help
- 1 Installation guide
- 1 USB cable
- 1 power adapter 230/12 V/1.6 A
- 1 GSD file for simple parameter settings

Multimeter LDanalog 20

High overload-capacity measuring instrument with integrated protection against damage due to improper handling, specially designed for student’s and practical experiments. The moving coil instrument is protected against damage with two diodes connected in opposing directions. Automatic battery cut-out after approx. 45 min.

Technical data:
- DC voltage ranges: 0.1 ... 300 V (8 ranges)
- AC voltage ranges: 3 ... 300 V (5 ranges)
- DC current ranges: 0.1 mA to 3 A (6 ranges)
- AC current ranges: 0.1 mA to 3 A (5 ranges)
- Internal resistance: 10 MΩ/V (=)6.67 kΩ/V (~)
- Accuracy: class 2/3~
- Zero point: left/centre (switchable)
- Mirror scale: yes
- Batteries (included): 9 V, 6 x F22 (685 45ET5)
- Overload capacity/fuses: F 3.15 A/300 V fuses
- Dimensions: 10 cm x 14 cm x 3.5 cm
- Weight: 270 g
**Digital multimeter DMM120**

Compact multimeter with large-format 3 ½ digit display, automatic or manual range selection, backlit display, automatic display of function symbols and low-battery indication, automatic cut-off, 1 impact-resistant case, 1 set of test leads with probes (red/black).

Technical data:
- 5 DC voltage ranges: 0.1 mV to 600 V
- 5 AC voltage ranges: 0.1 mV to 600 V
- 5 DC current ranges: 0.1 µA to 10 A DC
- 5 AC current ranges: 0.1 µA to 10 A
- Internal resistance: 10 MΩ DC/AC
- 6 resistance ranges: 0.1 Ω to 40 MΩ
- 5 capacitance ranges: 0.01 nF to 100 µF
- 6 frequency ranges: 0.01 Hz to 20 MHz
- Continuity test/diode test
- HOLD measured value memory
- DC voltage accuracy: ±0.5% + 2 digits
- AC voltage accuracy: ±1.0% + 4 digits
- DC current accuracy: ±1.2% + 2 digits
- AC current accuracy: ±1.5% + 4 digits
- Batteries: 2 x 1.5 V, IEC R6
- Overload capacity: 500 V rms
- Fuses: 500 mA/250 V (5x20 mm) and 10 A, HP 600 V
- Vmax CAT II: 600 V
- Dimensions: 16.5 cm x 8.5 cm x 4.0 cm
- Weight: 260 g

**Digital multimeter 3315**

Digital multimeter with 3¾-digit CD display (3999 max.), 40 segment bar graph and function symbols. Special features: USB and RS232 ports, measurement of capacitance, frequency and temperature, diode- and continuity-testing functions plus signal output and buzzer, Data, Min, Max, Rel. functions, auto shut-off (time selectable).

Safety: TÜV/GS, IEC-1010-1; CAT III 1000 V, CAT IV 600 V.

Technical data:
- Measuring ranges:
  - DC voltage: 400 mV/4/40/400/1000 V, ±0.8% + 1 digit
  - AC voltage: 4/40/400/750 V, ±1.0% + 5 digit
  - DC current: 400 µA/4/40/400 mA/10 A, ±1% + 2 digit
  - AC current: 400 µA/4/40/400 mA/10 A, ±1.5% + 5 digit
  - Resistance: 400 Ω/4/40/400 kΩ/4/40 MΩ, ±1% + 2 digits
  - Capacity: 4/40/400 nF/4/40/400 µF/4/40 mF, ±4% + 3 digits
  - Frequency: 4/40/400 kHz/4/40/400 MHz, ±0.1% + 3 digits
  - Temperature: -40 ... +1000°C ±1% + 3 digits
- Dimensions (WxHxD): 100 x 210 x 45 mm
- Weight: 0.33 kg

Scope of delivery:
- Test leads
- testing terminal
- battery
- Type K - Thermocouple
- interface cable USB and RS 232
- software for Windows 95/98/2000/XP/NT
- operating instructions
INDIVIDUAL COMPONENTS

Multimeter Metrahit Pro

Special features:
- Automatic socket blocking prevents the measuring leads from being inserted into the wrong sockets.
- Automatic and manual battery cut-off
- Safety warning for fuse triggering and overload
- Automatic and manual range selection
- True root mean square measurement: TRMS
- Digital display: 65 mm x 36 mm
  4½ digits ±12000 maximum readings
- Automatic scaling of analog display
- Electromagnetically compatible design (EMC)
- Set of safety leads

Technical data:
- DC voltage ranges: 100 mV ... 1000 V
- AC voltage ranges: 100 mV ... 1000 V
- DC current ranges: 1 A ... 10 A
- AC current ranges: 1 A ... 10 A
- Resistance measuring ranges: 100 Ω ... 40 MΩ
- Frequency: 100 Hz ... 30 kHz
- Temperature: -250 °C ... +1372°C
- Resolution: 10 µV; 100 µA; 10 mW; 0.01 Hz; 0.1°C
- Continuity/diode test: yes
- TRMS: AC and AC+DC, 10 kHz
- Inherent discrepancy in DC voltage: 0.05% of measured value/4½ digits
- Batteries (included): 2 x AA IEC LR6
- Overload capability:
  Voltage ranges: 1000 V
  Current: 10 A
- Fuses FF (UR) 10A/1000 V AC/DC
- Dimensions 87 mm x 200 mm x 45 mm
- Weight: approx. 400 g

Multimeter METRAport 3A

Multimeter with high overload capacity and special built-in protection against damage resulting from incorrect use; with integrated measuring amplifier for accurate measurements. Control and display fields are each located in different halves of the hinged housing. Closing the housing automatically switches off the battery. The user can tilt the hinged meter display to achieve the optimum viewing angle.

Technical data:
- DC voltage ranges: 0.1 V to 1000 V (9 ranges)
- AC voltage ranges: 0.1 V to 1000 V (9 ranges)
- DC current ranges: 10 µA to 10 A (7 ranges)
- AC current ranges: 10 µA to 10 A (7 ranges)
- Resistance ranges: 1 Ω to 20 MΩ (5 ranges)
- Other measuring ranges: Level (dB scale)
- Internal resistance: 10 MΩ (const.)
- Accuracy: class > 1.5 DC , class 2.5 AC
- Zero point: left
- Mirror scale
- Battery (included): 9 V/IEC 6 F 22 (685 45)
- Overload capacity: all ranges up to 250 V
- Fuses: FF 1.6 G/250 V
- Dimensions: 14.6 cm x 11.8 cm x 4.4 cm
- Weight: 450 g
### Insulation tester Metriso C

Battery operated insulation tester as per VDE 0413, Part 1, for testing equipment and systems up to 500 V voltage rating.

**Technical data:**

- **Measurement ranges:**
  - Insulating resistance:
    - 0..500 kΩ
    - 0.4..20 MΩ
  - Resistance: 0...1000 Ω (V<sub>0</sub> 370 V DC approx.) with audible signal
  - Voltage: 0..500 V AC/DC
  - For insulation testing:
    - Voltage rating: 500 V
    - Current rating: 1.06 mA
    - Open-circuit voltage: 700 V DC approx.
  - Accuracy:
    - Insulation resistance: class 1.5 as per DIN 43 780 or ±30% of reading as per VDE 0413
    - Resistance: class 2.5
    - Voltage: class 2.5
  - Overload-protected in all ranges
  - Power supply: 4 x mignon (AA) cell, 1.5 V, IEC R6

---

### Rheostat, 100 ohms

Resistance wires wound on a special cement core, perforated cover for touch protection, electrical connections via three safety sockets allowing applications as fixed resistor, variable resistor and potentiometer.

**Technical data:**

- Connection: 4-mm safety sockets
- Resistance: 100 Ω
- Resistor tolerance: 10%
- Max. load:
  - Current (sustained): 1.8 A
  - Current (15 mins.): 2.5 A
- Dimensions: 450 x 95 x 150 mm

---

### Rheostat, 330 ohms

Resistance wires wound on a special cement core, perforated cover for touch protection, electrical connections via three safety sockets allowing applications as fixed resistor, variable resistor and potentiometer.

**Technical data:**

- Connection: 4-mm safety sockets
- Resistance: 330 Ω
- Resistor tolerance: 10%
- Max. load:
  - Current (sustained): 1.0 A
  - Current (15 mins.): 1.4 A
- Dimensions: 450 x 95 x 150 mm
## Resistance wires

To examine the dependence of electric resistances on material, length and cross section of the wire used.

<table>
<thead>
<tr>
<th>Cat.-No.</th>
<th>Diameter</th>
<th>Length</th>
<th>Cross section</th>
<th>Specific resistor</th>
<th>Material</th>
</tr>
</thead>
<tbody>
<tr>
<td>550 35</td>
<td>0,2 mm</td>
<td>100 m</td>
<td>0,03 mm²</td>
<td>0,6 Ω/m</td>
<td>Copper</td>
</tr>
<tr>
<td>550 39</td>
<td>0,5 mm</td>
<td>50 m</td>
<td>0,2 mm²</td>
<td>0,4 Ω/m</td>
<td>Brass</td>
</tr>
<tr>
<td>550 40</td>
<td>0,2 mm</td>
<td>100 m</td>
<td>0,03 mm²</td>
<td>15,4 Ω/m</td>
<td>Constantan</td>
</tr>
<tr>
<td>550 41</td>
<td>0,25 mm</td>
<td>100 m</td>
<td>0,05 mm²</td>
<td>10,4 Ω/m</td>
<td>Constantan</td>
</tr>
<tr>
<td>550 361</td>
<td>0,3 mm</td>
<td>100 m</td>
<td>0,07 mm²</td>
<td>7,7 Ω/m</td>
<td>Constantan</td>
</tr>
<tr>
<td>550 42</td>
<td>0,35 mm</td>
<td>100 m</td>
<td>0,1 mm²</td>
<td>5 Ω/m</td>
<td>Constantan</td>
</tr>
<tr>
<td>550 43</td>
<td>0,4 mm</td>
<td>50 m</td>
<td>0,12 mm²</td>
<td>4 Ω/m</td>
<td>Constantan</td>
</tr>
<tr>
<td>550 44</td>
<td>0,5 mm</td>
<td>50 m</td>
<td>0,2 mm²</td>
<td>2,5 Ω/m</td>
<td>Constantan</td>
</tr>
<tr>
<td>550 443</td>
<td>0,7 mm</td>
<td>20 m</td>
<td>0,4 mm²</td>
<td>1,3 Ω/m</td>
<td>Constantan</td>
</tr>
<tr>
<td>550 445</td>
<td>1 mm</td>
<td>20 m</td>
<td>0,6 mm²</td>
<td>0,6 Ω/m</td>
<td>Constantan</td>
</tr>
<tr>
<td>550 45</td>
<td>0,2 mm</td>
<td>100 m</td>
<td>0,03 mm²</td>
<td>34,5 Ω/m</td>
<td>Chrome-nickel</td>
</tr>
<tr>
<td>550 46</td>
<td>0,25 mm</td>
<td>100 m</td>
<td>0,05 mm²</td>
<td>21,3 Ω/m</td>
<td>Chrome-nickel</td>
</tr>
<tr>
<td>550 47</td>
<td>0,35 mm</td>
<td>100 m</td>
<td>0,1 mm²</td>
<td>11 Ω/m</td>
<td>Chrome-nickel</td>
</tr>
<tr>
<td>550 48</td>
<td>0,4 mm</td>
<td>50 m</td>
<td>0,12 mm²</td>
<td>8,2 Ω/m</td>
<td>Chrome-nickel</td>
</tr>
<tr>
<td>550 49</td>
<td>0,5 mm</td>
<td>50 m</td>
<td>0,2 mm²</td>
<td>5,4 Ω/m</td>
<td>Chrome-nickel</td>
</tr>
<tr>
<td>550 51</td>
<td>0,2 mm</td>
<td>100 m</td>
<td>0,03 mm²</td>
<td>3,3 Ω/m</td>
<td>Iron</td>
</tr>
</tbody>
</table>

## Plug-in power supply, 12 V AC

Universal plug-in power supply, e.g. for CASSY, counter S, counter P, electrometer amplifier etc.

Technical data:
- Primary: 230 V AC, 50/60 Hz
- Secondary: 12 V AC, 20 VA
- Connection: co-axial power connector

| 562 791  | Plug-in power supply, 12 V AC |

## Storage tray for ELM apparatus

Specially moulded for apparatus.

Technical data:
- Dimensions: 55 cm x 28.5 cm x 5 cm

| 563 04   | Storage tray for ELM apparatus |

## ELM pole piece for magnets

With ground, magnetic contact surface and recessed borehole for attachment. Complete with hexagon socket (M6 x 35).

| 563 091  | ELM pole piece for magnets    |

## ELM wide pole piece for coils

For two- and three-pole stator assemblies

| 563 101  | ELM wide pole piece for coils |
### ELM coil, 250 turns

Technical data:
- Number of turns: 250
- Resistance: 1.8 Ω
- Impedance: 6.7 Ω (at 50 Hz)
- Max. current: 1.5 A

| 563 11 | ELM coil, 250 turns |

### ELM coil, 500 turns

For use with pole pieces.

Technical data:
- Current: 0.7 A
- Connection: 4-mm sockets
- Dimensions: 50 mm x 60 mm x 20 mm

| 563 115 | ELM coil, 500 turns |

### ELM squirrel-cage rotor

Technical squirrel-cage rotor of disc design with pulley, rotor: 90 mm diameter.

| 563 12 | ELM squirrel-cage rotor |

### ELM brush

Hard carbon contact with press-on spring, cable and 4-mm plug, for connecting to the commutator and slip rings of the coil rotors.

Technical data:
- Max. current: 1.5 A

| 563 13 | ELM brush |

### Allen key

For fastening the pole piece with a magnet or a coil to a base plate.

| 563 16 | Allen key |

### ELM centring disc

For optimising the distance between the pole pieces and rotors.

| 563 17 | ELM centring disc |

### ELM brush holder rack

For securing the rotor on the axle of a base plate, for 5 brushes. Complete with retaining screw.

| 563 18 | ELM brush holder rack |

### ELM narrow pole piece for coils

With spigot, for use with coils.

Technical data:
- Allen screw, M6 x 35
- Dimensions: 42 mm x 52 mm x 30 mm

| 563 201 | ELM narrow pole piece for coils |
INDIVIDUAL COMPONENTS

ELM split pole piece for coils
With spigot, for use with coils.
Technical data:
• Allen screw, M6 x 35
• Dimensions: 83 mm x 60 mm x 30 mm

ELM two-pole rotor
Coil rotor on iron cores consisting of packed laminated sheets to eliminate eddy currents, with a pivot bearing, pulley and cable drum.
Technical data:
• Number of turns: 2 x 380
• Ohmic resistance: 1.3 Ω
• Impedance: 5.9 Ω
• Max. current: 1.5 A
• Commutator: two-pole
• Slip rings: 2 (180°)

ELM three-pole rotor
Coil rotor on iron cores consisting of core sheet sections free of eddy currents, with a pivot bearing, pulley and cable drum
Technical data:
• Number of turns: 3 x 340
• Resistance: 1.6 Ω
• Impedance: 7 Ω
• Max. current: 1.5 A
• Commutator: three-pole
• Slip rings: 3 (120°)

ELM drum rotor
12 T armature with belt disc.
Technical data:
• Number of turns: 12 x 90
• Current: max. 1.5 A
• Speed: max. 5000 rpm
• Rotor: 90 mm diam.

ELM rotating field attachment and squirrel cage ring
With two threaded bores for attaching magnets and pole pieces for generating a rotating magnetic field. The squirrel cage ring can be plugged into the collectors of the coil rotors to make them act as squirrel cage rotors.

ELM magnetic needle rotor
Magnetic needle with pivot bearing, for demonstrating slowly rotating fields.
**ELM aluminium ring with iron disc**

Rectangular frame made of aluminium with matching iron disc. Model of a short-circuit rotor; D = 90 mm.

---

**Oil, 100 ml, in dropping bottle**

Acid-free machine oil.

---

**Two-channel oscilloscope 400**

Particularly suitable for demonstration and practical experiments. Includes instruction manual. Probes not included.

**Technical data:**
- Bandwidth: 0...40 MHz (-3 dB)
- Input impedance: 1 MΩ, 15 pF, max. 400 V
- Screen: 8 x 10 cm with internal graticule
- Vertical deflection: 1 mV/cm...20 V/cm (14 steps)
- Time bases: 100 ns/div...0.2 s/div with X-axis magnification x10 to 10 ns/division
- Trigger sources: Ch1, Ch2, line, ext.
- Operating modes: Ch1, Ch2, Ch1+Ch2 [alternate or chopped], Ch1/Ch2 sum or difference
- XY mode
- Built-in component tester
- Dimensions (WxHxD): 28.5 x 12.5 x 38.0 cm
- Mains supply: 105...253 V, 50/60 Hz ±10%, Cat II

---

**Probe 100 MHz, 1:1 / 10:1**

For measurements on high-impedance voltage sources in conjunction with oscilloscopes, frequency-compensated. Range selection by switch. Including a spring-loaded hook, trimmer key, BNC adapter, probe tip, insulating cover for the probe tip or for IC measurements, 4-mm adapter, ground lead.

**Technical data:**
- Input resistance: 1 MΩ and 10 MΩ (at 10 MΩ oscilloscope input)
- Bandwidth: 10 MHz or 100 MHz
- Input voltage: 600 V DC including AC peak
- Connection: BNC plug
- Lead length: 1.2 m
- Ground lead length: 30 cm

---

**Digital storage oscilloscope 722**

**Technical data:**
- Bandwidth: 0...70 MHz (-3 dB)
- Input impedance: 1 MΩ, 14 pF, max. 200 V
- Display: 16.5 cm, VGA Colour TFT
- Storage operation modes: refresh, average, envelope, peak-detect, roll (unsolicited/triggered), filter, HiRes
- Cursor measurement: ΔV, Δt, Δf , peak-to-peak, mean value, RMS value, etc.
- Dual interface USB B/RS232, 2 x USB A
- Vertical sensitivity: 1 mV/div...10 V/div (1 - 2 - 5 progression)
- DC amplification accuracy: 2%
- Time base: 2 ns/div...50 s/div
- Accuracy: 50 ppm
- Trigger operating mode: flank, video, pulse length, logic, delayed, event
- Trigger source: CH1, CH2, CH1 and CH2 alternate, line and external
- Component tester
- Mains supply: 100...240 V, 50...60 Hz, Cat. II
- Protection class I (EN61010-1)
- Dimensions: 28.5 cm x 17.5 cm x 14.0 cm
- Weight: < 2.5 kg
- Without probes
## INDIVIDUAL COMPONENTS

### Plug-in board, DIN A4, STE

For assembling electric and electronic experiment circuits for students’ and training experiments. The experimenting surface has sufficient capacity for transistor circuits with up to three stages consisting of small plug-in elements in 2/19, 2/50 and 4/50 formats. Also suitable for extending the base and work panels for the electric machine teaching models.

**Technical data:**
- 24 socket grids
- Front equipped with 24 conductor intersections and 120 sockets
- Rear equipped with 24 conducting squares and 216 sockets
- Dimensions: 30 cm x 20 cm x 2.4 cm

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>576 74</td>
<td>Plug-in board, DIN A4, STE</td>
</tr>
</tbody>
</table>

### Resistor, 4.7 kΩ, STE 2/19

**Technical data:**
- Load capacity: 2 W
- Tolerance: 5%

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>577 52</td>
<td>Resistor, 4.7 kΩ, STE 2/19</td>
</tr>
</tbody>
</table>

### Resistor, 39 kΩ, STE 2/19

**Technical data:**
- Load capacity: 0.5 W
- Tolerance: 1%

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>577 62</td>
<td>Resistor, 39 kΩ, STE 2/19</td>
</tr>
</tbody>
</table>

### Capacitor, 4.7 µF, STE 2/19

**Technical data:**
- Max. allowable voltage: 63 V
- Tolerance: 5%

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>578 16</td>
<td>Capacitor, 4.7 µF, STE 2/19</td>
</tr>
</tbody>
</table>

### Capacitor (electrolytic), 100 µF, STE 2/19

**Technical data:**
- Max. allowable voltage: 40 V
- Tolerance: 20%

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>578 39</td>
<td>Capacitor (electrolytic), 100 µF, STE 2/19</td>
</tr>
</tbody>
</table>

### Capacitor (electrolytic), 470 µF, STE 2/19

**Technical data:**
- Max. allowable voltage: 16 V
- Tolerance: 20%

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>578 40</td>
<td>Capacitor (electrolytic), 470 µF, STE 2/19</td>
</tr>
</tbody>
</table>

### Three-phase voltage supply, 3×12 V, STE 6/100

Plug-in element for generation of a three-phase, alternating sinusoidal voltage.

**Technical data:**
- Input voltage: ±15 V DC or 12 V AC
- Output frequency: 1, 50 or 60 Hz
- Output voltage: 3×12 V Δ
- Output current: 3×0.2 A

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>578 795</td>
<td>Three-phase voltage supply, 3×12 V, STE 6/100</td>
</tr>
</tbody>
</table>
Lamp holder, E10, top, STE 2/19
Lamp holder with an E 10 screw thread. The lamp is screwed on and placed at the side for the direct, lateral illumination of opto-receivers like photoresistors, photodiodes and photoelements.

<table>
<thead>
<tr>
<th>Count</th>
<th>Cat.-No.</th>
<th>Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>579 06</td>
<td>Lamp holder, E10, top, STE 2/19</td>
</tr>
</tbody>
</table>

Push button (NO), STE 2/19
Mechanical push button with 2 positions.

Technical data:
- Switching functions: ON-OFF

<table>
<thead>
<tr>
<th>Count</th>
<th>Cat.-No.</th>
<th>Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>579 10</td>
<td>Push button (NO), STE 2/19</td>
</tr>
</tbody>
</table>

Toggle switch, STE 2/19
Mechanical switch with 2 positions.

Technical data:
- Switching functions: ON-OFF

<table>
<thead>
<tr>
<th>Count</th>
<th>Cat.-No.</th>
<th>Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>579 13</td>
<td>Toggle switch, STE 2/19</td>
</tr>
</tbody>
</table>

Advanced Science Kit – Set BEL
15 pieces of basic equipment for one working group to do experiments on electricity and electronics, in pre-formed storage tray.

**Scope of delivery:**

<table>
<thead>
<tr>
<th>Count</th>
<th>Cat.-No.</th>
<th>Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td>340 89ET5</td>
<td>Coupling plugs, 4 mm, set of 5</td>
</tr>
<tr>
<td>1</td>
<td>501 48</td>
<td>Bridging plugs, STE 2/19, set of 10</td>
</tr>
<tr>
<td>2</td>
<td>501 861</td>
<td>Crocodile-clips, polished, set of 6</td>
</tr>
<tr>
<td>1</td>
<td>576 74</td>
<td>Plug-in board, DIN A4, STE</td>
</tr>
<tr>
<td>1</td>
<td>576 77</td>
<td>Board holders, STE, pair</td>
</tr>
<tr>
<td>2</td>
<td>576 86</td>
<td>Monocell holder STE 2/50</td>
</tr>
<tr>
<td>1</td>
<td>577 28</td>
<td>Resistor, 47 Ω, STE 2/19</td>
</tr>
<tr>
<td>2</td>
<td>577 32</td>
<td>Resistor, 100 Ω, STE 2/19</td>
</tr>
<tr>
<td>2</td>
<td>579 05</td>
<td>Lamp holder, E10, lateral, STE 2/19</td>
</tr>
<tr>
<td>1</td>
<td>579 13</td>
<td>Toggle switch, STE 2/19</td>
</tr>
</tbody>
</table>

Advanced Science Kit – Set ELI 1
8 pieces of supplementary equipment for one working group to do experiments on optics using a ray box. To be stored in the tray for set S24-FN (648 07).

**Scope of delivery:**

<table>
<thead>
<tr>
<th>Count</th>
<th>Cat.-No.</th>
<th>Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>567 06</td>
<td>Conductors/insulators, set of 6</td>
</tr>
<tr>
<td>1</td>
<td>567 18</td>
<td>Wrapping plate for wires</td>
</tr>
<tr>
<td>2</td>
<td>579 331</td>
<td>Plug-in holder, STE</td>
</tr>
<tr>
<td>1</td>
<td>579 332ET</td>
<td>Leaf spring with contact strip and bimetallic strip</td>
</tr>
<tr>
<td>2</td>
<td>582 81</td>
<td>Change-over switch, STE 4/50</td>
</tr>
</tbody>
</table>

588 8755 Advanced Science Kit – Set ELI 1
INDIVIDUAL COMPONENTS

Advanced Science Kit – Set ELI 2

8 pieces of supplementary equipment for one working group to do experiments on electromagnetism and induction. To be stored in the tray for electricity set 1 (588 871S).

Scope of delivery:

<table>
<thead>
<tr>
<th>Count</th>
<th>Cat.-No.</th>
<th>Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 out of</td>
<td>505 36ET10</td>
<td>Glow lamps, 115 V, E10, set of 10</td>
</tr>
<tr>
<td>1 out of</td>
<td>510 50ET2</td>
<td>Bar magnets, 60 x 13 x 5 mm, set of 2</td>
</tr>
<tr>
<td>1</td>
<td>510 51</td>
<td>Rotary support</td>
</tr>
<tr>
<td>1 out of</td>
<td>510 53</td>
<td>Plotting compasses, pair</td>
</tr>
<tr>
<td>1 out of</td>
<td>510 54ET2</td>
<td>Magnetisable rods, set of 8</td>
</tr>
<tr>
<td>1</td>
<td>590 83</td>
<td>Coil, 500 turns, STE 2/50</td>
</tr>
<tr>
<td>1</td>
<td>590 84</td>
<td>Coil, 1000 turns, STE 2/50</td>
</tr>
<tr>
<td>1</td>
<td>593 21</td>
<td>Transformer core kit</td>
</tr>
</tbody>
</table>

588 876S Advanced Science Kit – Set ELI 2

Advanced Science Kit – Set ELI 3

4 pieces of supplementary equipment for one working group to do experiments on motors and generators. To be stored in the tray for electricity set 1 (588 871S).

Scope of delivery:

<table>
<thead>
<tr>
<th>Count</th>
<th>Cat.-No.</th>
<th>Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>579 45</td>
<td>Stator, STE 4/50</td>
</tr>
<tr>
<td>1</td>
<td>579 46</td>
<td>Coil rotor, STE</td>
</tr>
<tr>
<td>1</td>
<td>579 47</td>
<td>Brush yoke, STE</td>
</tr>
<tr>
<td>1</td>
<td>579 48</td>
<td>Magneto inductor, STE</td>
</tr>
</tbody>
</table>

588 877S Advanced Science Kit – Set ELI 3

Scissors, 125 mm, round-ended

Rounded ends.

Technical data:
• Length: 125 mm

667 017 Scissors, 125 mm, round-ended

Batteries, 1.5 V (AA), set of 4

Technical data:
• Voltage: 1.5 V
• Battery type: IEC R6
• Dimensions: 50 mm x 14 mm diameter

685 44ET4 Batteries, 1.5 V (AA), set of 4

Batteries 1.5 V (D, mono), set of 5

Lengths include pole terminals.

Technical data:
• Voltage: 1.5 V
• Battery type: IEC R20
• Dimensions: 60 mm x 33 mm diameter

685 48ETS Batteries 1.5 V (D, mono), set of 5
USB cable, 3 m

689 0605 USB cable, 3 m

COM3LAB software

<table>
<thead>
<tr>
<th>Cat.-No.</th>
<th>Designation</th>
</tr>
</thead>
<tbody>
<tr>
<td>700 00CBTDE</td>
<td>CD: COM3LAB software, German</td>
</tr>
<tr>
<td>700 00CBTEN</td>
<td>CD: COM3LAB software, English</td>
</tr>
<tr>
<td>700 00CBTFR</td>
<td>CD: COM3LAB software, French</td>
</tr>
<tr>
<td>700 00CBTIT</td>
<td>CD: COM3LAB software, Italian</td>
</tr>
<tr>
<td>700 00CBTPT</td>
<td>CD: COM3LAB software, Portuguese</td>
</tr>
<tr>
<td>700 00CBTRU</td>
<td>CD: COM3LAB software, Russian</td>
</tr>
<tr>
<td>700 00CBTSP</td>
<td>CD: COM3LAB software, Spanish</td>
</tr>
</tbody>
</table>

COM3LAB master unit (USB)

For the mounting and supply of power to the COM3LAB multimedia experiment boards. The master unit is connected to the USB Port of a personal computer for the recording of measurements and for remote control of its built-in functions. All the necessary instruments (multimeters, oscilloscope, function generator and digital analyser) are built-into the master unit. The master unit itself can be assembled and disassembled quickly. The handy lid protects the master unit and makes it stackable.

Technical data:
- Dimensions: 380 x 282 x 65 mm (L x W x H)

Integrated measuring instruments and functions:
- Two digital multimeters:
  - Voltage: AC/DC 2/20 V
  - Current: AC/DC 0.2/2 A
  - Resistance: 2/200 Ω, 2 MΩ
  - Auto-ranging for all measurement ranges
  - Single button operation
  - Liquid crystal display, 3.5 digits with special characters
- Digital function generator:
  - Digitally generated signal types
  - Sinusoidal, square-wave, triangular, DC
  - 0.5 Hz...100 kHz
  - Max. ±10 V, max. 250 mA
  - Operation via two push buttons and incremental indicator
  - Liquid crystal display, 4-digit with special characters

The following devices have no display of their own and are operated remotely by the connected PC and through the training programs. The measured values are displayed on the PC monitor.
- Digital storage oscilloscope:
  - Two differential voltage inputs with 8-bit A/D converter
  - Measuring ranges: 20/50/100/200/500 mV, 1/2/5 V per division
  - Sampling frequency: 200 Hz to 1 MHz
  - Digital trigger with pre- and post-function
- Digital analyser:
  - Three digital inputs, TTL compatible
  - Sampling frequency: 200 Hz to 1 MHz, up to 4 MHz with limited trigger resolution
  - Triggering from any combination of input states
  - Memory depth 2048 9-bit words

Oscilloscope and analyser can be used in alternation. All of the measuring equipment and function generator are connectable via 2-mm sockets.

USB port included for connection to PC.

Scope of delivery:
- 1 USB cable
- 1 Set of leads consisting of:
  - Connecting leads of 40 cm and 5 cm length equipped with 2-mm plugs
- 1 Table-top power supply, 100...250 V, 50...60 Hz, with mains lead and earth-contact plug for supply of power to the master unit

700 00USB COM3LAB master unit (USB)
COM3LAB course: Power electronics I

Course on line-commutated and self-commutated static converter circuits, consisting of an experiment board with various circuits for mounting into the master unit and a multimedia CD with interactive training software.

Topics:
- Introduction
- Semiconductors in power electronics
- Wiring and triggering
- Switching processes and commutation
- Uncontrolled rectifier circuits
- Parameters for periodic signals
- Controlled line-commutated static converters
- M1C circuit
- M3C-circuit
- B2C circuit
- B6C semi-controlled rectifiers

Virtual lab:
- Oscilloscope
- Function generator
- Multimeters (2x)
- Digital analyser

Additional functions:
- Word processing
- Printer
- Pocket calculator
- Free experimentation
- Glossary

The experiment board is powered by the Master Unit.
The wiring of the experiments carried out over 2 mm cable.
Course content, experiment instructions and tasks are taught through a course-specific software.

Scope of delivery:
- Set of cables consisting of 40 cm and 5 cm long connecting leads with 2-mm plugs

Operating system: Windows 2000/XP/Vista/7

COM3LAB course: Power electronics II

Supplementary course on power inverters, DC choppers, static converters and drive technology, consisting of a dongle for the PE I experiment board and a multimedia CD with interactive training software.

Topics:
- Self-commutated static converters (power inverters)
- Semiconductor switches and controllers (bidirectional static converters)
- Switches and controller for DC
- Converters
- Static converters in automatic control technology
- Static converters in drive technology

Virtual lab:
- Oscilloscope
- Function generator
- Multimeters (2x)
- Digital analyser

Additional functions:
- Word processing
- Printer
- Pocket calculator
- Free experimentation
- Glossary

The experiment board is powered by the Master Unit.
The wiring of the experiments carried out over 2 mm cable.
Course content, experiment instructions and tasks are taught through a course-specific software.

Additionally required:

<table>
<thead>
<tr>
<th>Count</th>
<th>Cat.-No.</th>
<th>Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>700 21</td>
<td>COM3LAB course: Power electronics I</td>
</tr>
<tr>
<td>1</td>
<td></td>
<td>PC with Windows XP/Vista/7</td>
</tr>
</tbody>
</table>
COM3LAB course: Three-phase technology

This COM3LAB course investigates the behaviour of three-phase systems. Practical exercises show the generation of the rotary field or the function of a transformer. Furthermore, passive components in different circuits are discussed. Coils, capacitors and resistors are analysed and evaluated in different circuits.

Topics:
- Characteristics of a three-phase system
- Representation of line diagrams and phase relationships
- Star-delta circuits with different loads
- Measurement of phase and line voltage/current
- Resistive loads
- Capacitive loads
- Symmetrical and unsymmetrical charges
- Measurement of power in the three-phase system

Virtual lab:
- Spectrum analyser (FFT module)
- Frequency counter
- Multimeters (2x)
- Function generator
- Digital storage oscilloscope

Additional functions:
- Web-based training
- You can write your own pages and experiments
- Access to external programs (as for example Excel, Word).
- Subsequent processing of measured data using external programs (as for example Excel, Word).
- You can produce your own documents.
- The software contains a text editor and allows for free experimentation.

Technical data:
- Star circuit with resistors
- Delta circuit with resistors
- Capacitors
- Load resistors

700 24 COM3LAB course: Three-phase technology

Prerequisites: Fundamentals of AC technology

COM3LAB course: Electrical machines I

Course concerning the connection methods and the recording of characteristics for electric motors and generators. With the integrated machine test system, a multitude of experiments can be carried out, e.g. the recording of torque, power and current-locus curves.

Topics:
- Forces in a magnetic field
- Measurement of Lorentz force
- Drives
- Torque-speed characteristic
- Machine test system
- DC machines
- Speed and induced voltage with DC machines
- Torque and armature voltage with DC machines
- Torque and excitation voltage with DC machines
- DC machines with external excitation
- Reversible of direction
- Characteristics with variable armature voltage
- Characteristics with variable excitation voltage
- Shunt-wound DC machines
- Characteristics with variable operating voltage
- Series-wound DC machines
- Reversal of direction with DC machines
- Characteristics with variable operating voltage
- Generator operation of DC machines
- Drive and generator with a resistive load
- Power output of generator
- Rotating field (three-phase) machines
- Three-phase windings
- Rotating fields
- Direction of rotation with periodic swapping of phase conductors
INDIVIDUAL COMPONENTS

- Direction of rotation when phase conductors are swapped
- Voltage and current in star (Y) circuits
- Voltage and current in delta circuits
- Resistance in stator winding
- Reactance of an AC winding
- Synchronous machines
- Equivalent circuit diagram for synchronous machines and how they are used
- Permanently excited synchronous machines
- Step operation of synchronous machines
- Determining rotor position in star configuration
- Determining rotor position in delta configuration
- Synchronous machine at variable speed (run-up)
- Speed measurement
- Speed setting using frequency converter
- Asynchronous machines
- Block and equivalent circuit diagrams for asynchronous machines
- Determination of slip
- Star-delta starting
- Measurement of torque and line currents during run-up
- Changing direction of asynchronous machines
- Recording of torque-speed characteristic for asynchronous machines
- Three-phase drives
- Changing speed of asynchronous machines
- How speed depends on slip
- How speed depends on stator frequency
- Stepper motors
- Full-step operation
- Half-step operation
- Changing the direction of a stepper motor

Virtual lab:
- Multi-channel oscilloscope
- Oscilloscope
- Function generator
- Multimeter (2x)
- Digital analyser

Additional functions:
- Word processing
- Printer
- Pocket calculator
- Free experimentation
- Glossary

The experiment board is powered by the Master Unit. The wiring of the experiments carried out over 2 mm cable. Course content, experiment instructions and tasks are taught through a course-specific software.

Technical data:
- Synchronous machine with optical rotary field indicator and strobe for speed determination
- Induction motor with star-delta switch
- Optical tachogenerator
- DC motor
- DC generator
- Current-torque converter
- Thermometer
- Electronic load
- Three phase generator, phase voltage: 0 V .. 10 V,
- Frequency converter, Frequency: 1 Hz – 80 Hz
- DC supplies
- Stepper motor
- Electrodynamic force meter
- Multiplexer

Scope of delivery:
- Board for course
- CD with software and documentation
- Power supply, 230/12 V AC

700 25 | COM3LAB course: Electrical machines I

- Working through this course requires the COM3LAB Master Unit 70000USB.
- Also required is a PC running Windows XP, 7 or 8.
- Prerequisites: Fundamentals of AC and three-phase technology
COM3LAB course: Control technology I

Course on the fundamentals of automatic control technology, consisting of an experiment board with various circuits for mounting into the master unit and a Multimedia CD with an interactive training program.

Topics:
- Introduction
- Open-loop control
- Closed-loop control
- Analysis of controlled systems
- Controlled systems with/without compensation
- Controlled systems of a higher order
- Types of controllers
- P, I, PI, PID and PD control
- Automatic digital control
- Performance criteria for automatic controls
- Optimisation guidelines for PID controllers
- Automatic temperature control
- Automatic speed control
- Automatic light control
- Automatic control of systems without compensation
- Automatic control with discontinuous controllers
- Fault simulation

Virtual lab:
- Oscilloscope
- Function generator
- 2 multimeters
- Digital analyser
- Static characteristic plotter
- Step response plotter
- DDC plotter
- Controller design calculator (for optimum controller parameters)

Additional functions:
- Word processing
- Printer
- Pocket calculator
- Free experimentation
- Glossary

The experiment board is powered by the Master Unit.
The wiring of the experiments carried out over 2 mm cable.
Course content, experiment instructions and tasks are taught through a course-specific software.

Technical data:
- Analog controller
- Summation points with disturbance inputs
- Digital controller
- Lag element
- DC signal sources 1V, 5V, 10V
- P-action element
- PT-1 elements (2 x)
- I-action element, resettable
- Non-linear characteristic element
- Speed controlled system with optical speed sensor
- Temperature controlled system with KTY-temperature sensor
- Light controlled system with photodiode sensor and external light source (disturbance source)

700 82 COM3LAB course: Control technology I

- Operating system: Windows XP/Vista/7
- Support for unguided, free experimentation
COM3LAB course: Control technology II

Supplementary course on the fundamentals of control technology including a dongle for the CTI experiment board.

Topics:
- Introduction
- Stability of automatic control systems
- Controller design using the Ziegler/Nichols method
- Systems with lag time
- Limiting the manipulated variable
- Cascade control
- Introduction to frequency response
- Frequency response of single basic elements
- Frequency response of combined elements
- Controller design in the frequency domain
- Fuzzy control
- Adaptive control
- Experiments with external controlled systems

Virtual lab:
- Static characteristics plotter
- Step response plotter
- DDC plotter
- Frequency response plotter
- Controller design calculator (for optimum controller parameters)

Extra-low voltage supply 24/4

Complete power supply in a 19" casing for supplying DC and AC voltage in the extra-low voltage range.

Technical data:
- Mains switch, illuminated
- Outputs are switchable:
  - AC voltage: 0...24 V/4 A, floating earth
  - DC voltage: 0...24 V/4 A floating earth (full-wave rectifier)
- Output protection: thermal circuit-breaker, 4 A
- Display: 2 digital indicators for RMS value (digit height 12.4 mm) for indication of current and voltage
- Outputs: 2 x 4-mm safety sockets
- Width: 42 PU

Three-phase voltage supply 10/17.3

Complete power supply in a 19" casing for extra-low three-phase voltage.

Technical data:
- Mains switch: cam switch, 3-pole
- Mains voltage: 3 x 400 V ±10%, 50...60 Hz
- Outputs:
  - 3 x 17.3 V (delta), floating earth
  - 3 x 10 V (star), floating earth
- Output protection: 3 x thermal circuit-breakers, 5 A
- Outputs: 4 x 4-mm safety sockets
- Width: 42 PU
Three-phase voltage supply 400 V/2.5 A

Complete power supply in a 19" casing for variable three-phase voltage.

Technical data:
- Mains switch: 4-pole cam switch
- Mains voltage: 3 x 400 V ±10%, 50 - 60 Hz
- Outputs:
  - 3 x 0 - 400 V AC
  - 1 x 0 - 250V DC (full-wave rectified)
- 2.5 A, short-term 3 A
- Output protection: 3 x protective circuit breakers Outputs via five 4-mm safety sockets
- Display: 2 digital indicators (digit height 12.4 mm) to display current for L1, L2, L3 (switchable) and voltage
- Switchable between: Live conductors/neutral conductor, Live conductor/live conductor
- 3 x phase indicator lamps
- Width: 70 PU

Three-phase supply / experiment transformer

Complete power supply in a 19" casing for experiments with variable transformer voltages and for extra-low three-phase voltage.

Technical data:
- Variable transformer with three taps
  - Mains switch, illuminated
  - Outputs:
    - 0...24 V/2 A AC voltage, floating earth
    - 0...12 V/4 A AC voltage, floating earth
    - 0...6 V/8 A AC voltage, floating earth
    - 0...3 V/16 A AC voltage, floating earth
  - Bridge rectifier 35 A, for all ranges
  - Protection: thermal circuit-breaker, 1.2 A, in the primary circuit of the output transformer
  - Outputs: 8 x 4 mm safety sockets
- Power supply unit for extra-low three-phase voltage
  - Mains switch: cam switch, 3-pole
  - Mains voltage: 3 x 400 V ±10%, 50...60 Hz
  - Outputs:
    - 3 x 17.3 V (delta), floating earth
    - 3 x 10 V (star), floating earth
  - Output protection: 3 x thermal circuit-breakers, 5 A
  - Outputs: 4 x 4 mm safety sockets
  - Width: 84 PU

Three-phase generator in case

For generating DC, AC or three-phase AC voltages for the ELM system. Complete power supply in a 19" housing equipped with illuminated mains switch.

Technical data:
- Output voltage, AC: 0...15 V/ 1.5 A
- Output voltage, DC: 0...15 V/ 1.5 A
- Input: 6 pole DIN socket for rotor position pick-up
- Outputs: six 4-mm-safety sockets
- Display: 2 digital displays (digit height 12.4 mm) to display voltage, frequency, speed or position
- Width: 49 PU
- Power supply: 230 V, 50/60 Hz
INDIVIDUAL COMPONENTS

DC machine supply 0.3

Complete power supply in a 19" casing for recording the constant-current characteristic of electrical machines with a constant voltage in the power category up to 0.3 kW.

Technical data:
- Mains switch, illuminated
- Output: 40 – 250 V/0 – 6 A DC voltage and current adjustable, stabilised, short circuit-proof, with power factor adjustment
- Output: 220 V/2 A direct current (full-wave rectifier)
- Protection: circuit breaker, 2 A
- Outputs: 4 x 4-mm safety sockets
- Display: 2 digital displays (digit height: 12.4 mm) for indicating current and voltage
- Current overload indicator: 1 red LED
- Change-over switch: V/V ext. [constant], with mode indicator, 1 green LED
- External constant-voltage power supply: (0 – 10 V DC) via 2 x 4-mm safety sockets
- Width: 63 PU

<table>
<thead>
<tr>
<th>Cat.-No.</th>
<th>Designation</th>
<th>Stand</th>
<th>Execution</th>
</tr>
</thead>
<tbody>
<tr>
<td>725 852DG</td>
<td>DC machine supply 0.3</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

DC machine supply 1.0

Complete power supply in a 19" casing for recording the constant-current characteristic of electrical machines with a constant voltage in the power category up to 1.0 kW.

Technical data:
- Mains switch, illuminated
- Output: 40 – 250 V/0 – 6 A DC voltage and current adjustable, stabilised, short circuit-proof, with power factor adjustment
- Output: 220 V/2 A direct current (full-wave rectifier)
- Protection: circuit breaker, 2 A
- Outputs: 4 x 4-mm safety sockets
- Display: 2 digital displays (digit height: 12.4 mm) for indicating current and voltage
- Current overload indicator: 1 red LED
- Change-over switch: V/V ext. [constant], with mode indicator, 1 green LED
- External constant-voltage power supply: (0 – 10 V DC) via 2 x 4-mm safety sockets
- Width: 84 PU

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</thead>
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<tr>
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<td>DC machine supply 1.0</td>
<td></td>
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</tbody>
</table>

Similar to illustration

Experiment frames

<table>
<thead>
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<th>Stand</th>
<th>Execution</th>
</tr>
</thead>
<tbody>
<tr>
<td>726 09</td>
<td>Panel frame T130, two-level</td>
<td>T-Base</td>
<td>standard</td>
</tr>
<tr>
<td>726 10</td>
<td>Panel frame T150, two-level</td>
<td>T-Base</td>
<td>standard</td>
</tr>
<tr>
<td>726 11</td>
<td>Panel frame T180, two-level</td>
<td>T-Base</td>
<td>standard</td>
</tr>
<tr>
<td>726 18</td>
<td>Panel frame T130, three-level</td>
<td>T-Base</td>
<td>standard</td>
</tr>
<tr>
<td>726 19</td>
<td>Panel frame SL85, single-level</td>
<td>L-Base</td>
<td>angled</td>
</tr>
<tr>
<td>726 256</td>
<td>Panel frame VT160, three-level</td>
<td>T-Base</td>
<td>heavy duty</td>
</tr>
<tr>
<td>726 26</td>
<td>Panel frame VT180, three-level</td>
<td>T-Base</td>
<td>heavy duty</td>
</tr>
</tbody>
</table>

Plug-in board, 297 mm x 300 mm, STE

For suspending directly in panel frames (726 03) or demonstration experiment frames (301 300).

Technical data:
- 24 Socket grids with 24 conducting squares and 216 sockets
- 6 Socket grids with 36 sockets
- 2 Conducting paths with 18 sockets each
- Dimensions: 297 mm x 300 mm x 24 mm

<table>
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<th>Cat.-No.</th>
<th>Designation</th>
<th>Stand</th>
<th>Execution</th>
</tr>
</thead>
<tbody>
<tr>
<td>726 50</td>
<td>Plug-in board</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

For suspending directly in panel frames (726 03) or demonstration experiment frames (301 300).
### Single-phase supply unit

To switch the mains voltage in experiments with electrical loads for AC voltage of 230 V.

**Technical data:**
- Cam switch, 2-pole
- Automatic circuit breaker FAZ L 10 A
- Phase monitor light L 1
- Phase monitor light for indication of false polarity of mains plug

**Scope of delivery:**
- Mains connecting cable with earth-contact plug

| 726 71 | Single-phase supply unit |

### Three-phase supply unit with ELCB

To switch the 3-phase supply in experiments with electrical loads for line voltages of 400 V.

**Technical data:**
- Cam switch, 4 pole
- Earth-leakage circuit breaker, 30 mA
- Motor protection switch, 6-10 A
- Phase indicator lamps L1, L2, L3

**Scope of delivery:**
- Mains lead with Cekon plug

| 726 75 | Three-phase supply unit with ELCB |

### Transformer, 45/90, 3 N

Power supply and experiment unit for the area of power electronics.

**Technical data:**
- Mains switch: cam switch, 3-pole
- Mains voltage: 3 x 400 V, ±10 %, 50...60 Hz
- Outputs:
  - 3 x 90 V/1.5 A AC with 3 centre taps, 45 V
  - 1 x 230 V/1 A DC
- Motor protection switch 0.63...1 A (prim.)
- Outputs: via eighteen 4-mm safety sockets.
- Mains lead and 16-A Cekon plug

| 726 80 | Transformer, 45/90, 3 N |

### Adjustable transformer 0...260 V

Power supply and experiment unit for the area of electrical machines and energy technology.

**Technical data:**
- Mains voltage: 230 V, ±10 %, 50...60 Hz
- Output: 1 x 260 V / 4 A AC, short-term 5 A
- 1 Thermomagnetic circuit breaker, 5 A (sec.)
- Output: 2 x 4-mm safety sockets with connecting leads and earth-contact plug, 16 A

| 726 85 | Adjustable transformer 0...260 V |

### Stabilised power supply ±15 V/3 A

Laboratory power supply with two separate and stabilised fixed voltages for vertical assembly in panel frames or demonstration experiment frames using the plug-in system. Short-circuit-proof. Rated-voltage monitoring via two green LEDs.

**Technical data:**
- Output voltage: ±15 V via 4-mm sockets
- Maximum load capacity: 2.4 A, short-term 3 A
- Connection voltage: 230 V, 50/60 Hz
- Fuse: T 1.0
- Power consumption: 160 VA
- Dimensions: 10 cm x 30 cm x 12 cm
- Weight: 5 kg

| 726 86 | Stabilised power supply ±15 V/3 A |
INDIVIDUAL COMPONENTS

**AC/DC stabilizer**

Lab power supply unit with DC and AC voltage outputs. For supplying power to logic components of the SIMULOG LS-TTL range in experiments set up vertically in panel frames or demonstration experiment frames.

Technical data:
- Illuminated mains switch
- DC Outputs:
  - Fixed voltage: 5 V/3 A, floating ground
  - Residual ripple: 1 mV<sub>rms</sub>
  - Tracking stabiliser: ±0...15 V/1 A, floating ground
  - Residual ripple: < 3 mV<sub>rms</sub>
- AC Outputs: 6/12/24 V/1 A, floating ground
- Outputs: via 4 mm sockets and 6pin DIN socket for adapter/clock
- Mains connecting cable with earth-contact plug
- Dimensions: 15 cm x 30 cm x 12 cm
- Weight: 4 kg

726 88 AC/DC stabilizer

**Function generator 200 kHz**

Microprocessor controlled signal generator for experiments on training panels.

Technical data:
- Function: Sine/triangle/square/DC
- Square-wave signal: duty cycle 10%...90%, adjustable in steps of 5%
- Frequency range: 100 mHz...200 kHz
- Resolution: 1 mHz...100 Hz, depending on frequency
- Output voltage: 0...20 V<sub>pp</sub>, continuous
- DC offset: ±10 V
- Display: four-digit 7-segment display for signal parameters and functions
- Attenuation: 0 dB, -20 dB, -40 dB
- Output impedance: 50 Ω
- Trigger output: TTL level
- Outputs: 4-mm safety sockets
- Power supply: +/-15 V DC or plug-in adapter, 12 V AC (562 791)

726 862 Function generator 200 kHz

**Function generator 200 kHz Net**

Microprocessor controlled signal generator for experiments on training panels. Equipped with an RJ 45 socket for connection to a local area network (LAN). Can be controlled by LEYLAB.control 725006 or LEYLAB.control Lite 725007 software, allowing parameters to be read or modified and disturbance variables to be introduced. The equipment can be used in the patented „Networked worlds of learning“ system.

Technical data:
- Function: Sine/triangle/square/DC
- Square-wave signal: duty cycle 10%...90%, adjustable in steps of 5%
- Frequency range: 100 mHz...200 kHz
- Resolution: 1 mHz...100 Hz, depending on frequency
- Output voltage: 0...20 V<sub>pp</sub>, continuous
- DC offset: ±10 V
- Display: four-digit 7-segment display for signal parameters and functions
- Attenuation: 0 dB, -20 dB, -40 dB
- Output impedance: 50 Ω
- Trigger output: TTL level
- Outputs: 4-mm safety sockets
- Power supply: +/-15 V DC or plug-in adapter, 12 V AC (562 791)

726 862N Function generator 200 kHz Net
INDIVIDUAL COMPONENTS

RMS meter

Demonstration meter for measuring true RMS voltages and currents.

- Types of measurement:
  - RMS - AC + DC, overall true RMS
  - RMS - AC, alternating true RMS
  - AV - AC + DC arithmetic average value

It is possible to switch between all ranges and types of measurement at any time.

Technical data:

Measurement ranges for all types of measurement:
- Voltage: 3/10/30/100/300/1000 V, Ri = 10 MΩ
- Current: 0.1/0.3/1/3/10/30 A, Ri = 10 mΩ
- AV-Polarity indicator: 2 LEDs
- Instrument:
  - Moving coil
  - Class 2.5
  - Scale division: 0...10 and 0...3
  - Scale length: 119 mm
- Continuous overload protection in all measurement ranges up to 1000 V and 30 A
- Mains supply: 110/230 V, 50 Hz*
- Weight: 1.4 kg

727 10 RMS meter

*60 Hz on request

Power meter

Demonstration meter for active power and capacitive and inductive reactive power, in the range 0.3 W (var) to 30 kW (kvar).

Technical data:

Measurement ranges:
- Voltage: 3/10/30/100/300/1000 V
- R, = 10 MΩ
- Current: 0.1/0.3/1/3/10/30 A
- R, = 10 mΩ
- Frequency range:
  - Active power: 0...20 kHz
  - Reactive power: 50 Hz sin
- LED indication for:
  - Active power consumption
  - Active power output
  - Capacitive reactive power
  - Inductive reactive power
  - Overload voltage
  - Overload current
- Instrument:
  - Moving coil
  - Class 1.5
  - Scale division: 0...10 and 0...3
  - Scale length: 119 mm
- Continuous overload protection in all measurement ranges up to 1000 V and 30 A
- Mains supply: 110/130/220/240 V, 50 Hz

727 11 Power meter
INDIVIDUAL COMPONENTS

Power factor meter

Demonstration meter for power factor \(\cos \phi\) and phase-angle.

Technical data:

- **Measurement ranges:**
  - Power factor: 0...1...0
  - Phase angle: -90°(cap.) - 0 - +90°(ind.)
  - Voltage range: 3...1000 V, \(R_i = 1 \text{ M}\Omega\)
  - Current range: 0.1...30 A, \(R_i = 10 \text{ m}\Omega\)
  - Frequency range: 20 Hz...2 kHz
  - No voltage range/current range switching
- **Display instrument:**
  - Moving coil
  - Class 1.5
  - Scale length: 119 mm
  - Continuous overload protection in all measurement ranges up to 1000 V and 30 A
  - 192 x 96 mm (W x H)
  - Mains supply: 110/130/220/240 V, 50 Hz

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Multi–functional meter

The multi–functional meter is an all–purpose electronic meter for the measurement and monitoring of all important parameters for three–phase mains. The LC display with background lighting allows for reliable readings with no glare to be made even from long distance. A clear user interface and direct display of the functions used for all measurements are characteristic of the instrument. With integrated active and reactive power meters.

**Features:**
- USB interface
- Compatible with CASSY Lab 524220 software for recording and evaluation of measured data
- Integrated kWh active power meter, kWh reactive energy meter and counter for operating time in hours
- Min/max memory for all relevant measured values
- Simultaneous display of 3 measuring values and energy operating hours
- Display of the mean current and of the mean maximum current (bimetallic/friction pointer function)
- Selectable integration time
- All measuring values with direct dimension display
- Two overload outputs or freely selectable
- One pulse output/one overload output
- Overload monitoring functions of all measuring values, freely selectable pulse output for active power
- Analogue output 0/4–20 mA or 0/2–10 V
- Direct input, 3 x 30 A AC
- Mains connection 230 V AC

**Technical data:**

- **Measurement quantities:**
  - Voltage: \(V, V_{\text{rms}}, V_{\text{min}}, V_{L-N}, V_{L-L}\) up to 3 x 23...475 V AC
  - Current: \(I, I_{\text{rms}}, I_{\text{min}}, I_{L1/L2/L3}\) up to 3 x 10 A AC
  - Active power: \(P, P_{\text{rms}}, P_{\text{min}}, P_{L1/L2/L3}\)
  - Reactive power: \(Q, Q_{\text{rms}}, Q_{\text{min}}, Q_{L1/L2/L3}\)
  - Power factor \(\cos \phi, \cos \phi_{L1/L2/L3}\)
  - Mains frequency: \(f_{\text{mains}}, f_{L1/L2/L3}\) 45...65 Hz
  - Accuracy: 1% of maximum value in measuring range

---

Moving iron meter, 2.5 A

Robust instrument for current monitoring in continuous use.

**Technical data:**

- Moving iron galvanometer
- Front frame: 144 x 144 mm
- Class: 1.5
- Measurement ranges: 0 - 2.5 A

---
Complete equipment set DC/AC/EL

Optimised equipment set for carrying out experiments from the following topic groups:

- STE 2.2 DC Technology
- STE 2.3 AC Technology
- STE 6.1.1 Discrete Components and Basic Electronic Circuits

**Scope of delivery:**

- 1 Resistor, 0.1 \(\Omega\), 2 W
- 1 Resistor, 0.22 \(\Omega\), 2 W
- 1 Resistor, 1 \(\Omega\), 2 W
- 2 Resistors, 10 \(\Omega\), 2 W
- 1 Resistor, 47 \(\Omega\), 2 W
- 2 Resistors, 100 \(\Omega\), 2 W
- 1 Resistor, 150 \(\Omega\), 2 W
- 1 Resistor, 330 \(\Omega\), 2 W
- 1 Resistor, 470 \(\Omega\), 2 W
- 1 Resistor, 1 k\(\Omega\), 2 W
- 1 Resistor, 1.5 k\(\Omega\), 2 W
- 1 Resistor, 2.2 k\(\Omega\), 2 W
- 1 Resistor, 3.3 k\(\Omega\), 2 W
- 1 Resistor, 10 k\(\Omega\), 0.5 W
- 1 Resistor, 47 k\(\Omega\), 0.5 W
- 1 Resistor, 100 k\(\Omega\), 0.5 W
- 1 Resistor, 330 k\(\Omega\), 0.5 W
- 1 Resistor, 1 M\(\Omega\), 0.5 W
- 1 Potentiometer, 220 \(\Omega\), 3 W
- 1 Potentiometer, 1 k\(\Omega\), 1 W
- 1 Potentiometer, 10 k\(\Omega\), 1 W
- 1 Potentiometer, 100 k\(\Omega\), 1 W
- 1 VDR resistor
- 1 Photoresistor, LDR 05
- 1 NTC thermistor, 150 \(\Omega\), 1 W
- 1 PTC thermistor, 150 \(\Omega\), 1 W
- 1 Capacitor, 100 pF, 160 V
- 1 Capacitor, 22 pF, 100 V
- 1 Capacitor, 0.1 \(\mu\)F, 100 V
- 1 Capacitor 1 \(\mu\)F, 100 V
- 1 Capacitor 2.2 \(\mu\)F, 63 V
- 2 Capacitors 4.7 \(\mu\)F, 63 V
- 1 Capacitor 10 \(\mu\)F, 35 V
- 1 Capacitor 47 \(\mu\)F, 40 V
- 1 Capacitor 100 \(\mu\)F, 35 V
- 2 Capacitors 470 \(\mu\)F, 16 V
- 1 LED, red, LED 2, light emitted from top
- 1 LED, infrared, light emitted laterally from side
- 1 LED, green, LED 1, from top
- 1 LED, red, from side
- 1 Ge diode, AA 118
- 4 Si diodes, 1N 4007
- 1 Zener diode, ZPD 6.2
- 1 Zener diode, ZPD 9.1
- 1 Diac, BR 100
- 1 Photo-diode, BPX 43
- 1 Transistor, BD 137 (NPN), emitter at bottom
- 1 FET, BF 244
- 2 Thyristors, TYN 1012
- 1 Triac, BT 137/800
- 1 Inductor, 33 mH
- 2 Screw lamp holders E10, point sideways
- 2 Screw lamp holders E10, pointing up
- 2 Push buttons, single-pole
- 2 Change-over switches, single-pole
- 1 Relay with single-pole change-over contact
- 1 Coil, 500 turns
- 1 Coil, 1000 turns
- 1 Transformer core, for assembly and disassembly
- 2 Plug-in battery holder
- 2 Monocell batteries, 1.5 V
- 1 Magnet with core
- 1 Set of 10 incandescent lamps, 4 V/0.16 W, E10
- 1 Set of 10 incandescent lamps 12 V/3 W, E10
- 1 Set of 10 incandescent lamps, 2.5 V/0.25 W, E10
- 1 Set of 10 incandescent, lamps 6 V/3 W, E10
- 1 Glow lamp 110 V, E10
- 2 Trays, STE

Standard image, contents may differ
INDIVIDUAL COMPONENTS

Basic set T 2.4.1, STE
Collection of STE components for „Three-Phase Transformers and Transformer Circuits“. 
Scope of delivery:
• 1 E-core assembly kit
• 1 Base for E-core
• 6 Coils, 250 turns
• 3 Coils, 500 turns
• 3 Resistors, 56 ohm, 11 W
• 1 Tray STE

Basic set T 2.4.2, STE
Collection of STE components for „Three-Phase Circuits and Rectifiers“. For experiments involving single/3-phase transformers, phase-shifts, transformer configurations and rectifier circuits: M1, M2, M3, M6, B2 and B6.
Scope of delivery:
• 6 Si-diodes, BY 255
• 1 Resistor, 1 Ω, 2 W
• 1 Resistor, 100 Ω, 2 W
• 1 Resistor, 1 kΩ, 2 W
• 1 Capacitor, 22 μF, 16 V
• 1 Capacitor, 100 μF, 35 V
• 1 Capacitor, 1000 μF, 40 V
• 1 Coil, 10 mH
• 1 Tray, STE

Basic set STE 6.1.1
Collection of STE components for „Discrete Components and Basic Electronic Circuits“. 
Scope of delivery:
• 1 Resistor, 10 Ω, 2 W
• 1 Resistor, 100 Ω, 2 W
• 1 Resistor, 330 Ω, 2 W
• 1 Resistor, 470 Ω, 2 W
• 1 Resistor, 1 kΩ, 2 W
• 1 Resistor, 1.5 kΩ, 2 W
• 1 Resistor, 2.2 kΩ, 2 W
• 1 Resistor, 3.3 kΩ, 2 W
• 1 Resistor, 10 kΩ, 0.5 W
• 1 Resistor, 47 kΩ, 0.5 W
• 1 Resistor, 100 kΩ, 0.5 W
• 1 Resistor, 1 MΩ, 0.5 W
• 1 Potentiometer, 1 kΩ, 1 W
• 1 Potentiometer, 10 kΩ, 1 W
• 1 Potentiometer, 100 kΩ, 1 W
• 1 Voltage dependent resistor
• 1 Capacitor, 100 μF, 160 V
• 1 Capacitor, 22 μF, 100 V
• 1 Capacitor, 0.1 μF, 100 V
• 1 Capacitor, 1 μF, 100 V
• 1 Capacitor, 2.2 μF, 63 V
• 2 Capacitors, 4.7 μF, 63 V
• 1 Capacitor, 10 μF, 35 V
• 1 Capacitor, 47 μF, 40 V
• 1 Capacitor, 100 μF, 35 V
• 1 Capacitor, 470 μF, 16 V
• 1 LED, infrared, sideways emission
• 1 GE diode, AA 118
• 4 Si diodes, 1N 4007
• 1 Zener diode, ZPD 9.1
• 1 Zener diode, ZPD 6.2
• 1 LED, green, upwards emission, STE 2/19
• 1 LED, green, upwards emission, STE 2/50
• 1 LED, red, sideways emission
1 Diac, BR 100
1 Photo-diode, BPX 43
1 Transistor, BD 137 (PNP), emitter at bottom
1 FET, BF 244
2 Thyristors, TYN 1012
1 Triac, BT 137/800
1 Inductor, 33 mH
2 Lamp holders, E10, upwards facing
1 Push button, single-pole
1 Set of 10 incandescent lamps, 12 V/3 W, E10
1 Tray, STE

727 531N Basic set STE 6.1.1
Standard image, contents may differ

Supplementary set T 6.1.18
Basic Power Electronics (Supplement to STE 6.1.1).
Scope of delivery:
• 1 Resistor, 10 Ω, 10 W
• 1 Resistor, 100 Ω, 2 W
• 1 Resistor, 220 Ω, 2 W
• 1 Resistor, 680 Ω, 2 W
• 1 Resistor, 1 kΩ, 2 W
• 1 Resistor, 3.3 kΩ, 2 W
• 1 Resistor, 4.7 kΩ, 2 W
• 1 Resistor, 10 kΩ, 0.5 W
• 1 Variable resistor, 47 kΩ, 1 W
• 1 Capacitor, 1 nF, 100 V
• 1 Capacitor, 10 nF, 100 V
• 1 Capacitor, 47 nF, 100 V
• 1 Capacitor, 0.1 µF, 100 V
• 1 Capacitor, 100 µF, bipolar
• 2 Zener diodes, ZPY 8.2
• 1 NPN transistor, BD 137, emitter at bottom
• 1 PNP transistor, BD 138, emitter at bottom
• 1 MOSFET, BSV 81
• 1 Diac, MBS 4991
• 1 Thyristor trigger unit, TCA 785
• 1 GTO thyristor, BTW 58
• 1 Pulse width generator
• 2 Pulse isolating transformers, 1:1, 400 mW
• 1 Ignition pulse generator, activated by touch surface
• 1 Push button, (NC), single-pole
• 1 Change-over switch, two-pole
• 1 Coil, 1000 turns
• 1 Incandescent lamp, 24 V/3 W, E10
• 1 Tray, STE

727 657N Supplementary set T 6.1.18
Standard image, contents may differ

Basic machine unit
For mounting of electrical training machines in training panel frames.
Technical data:
• Dimensions: 200 mm x 297 mm
• Terminals: 4 mm sockets (5 x 2 sockets)
• Connector for rotor position sensor: 10-pin terminal strip
• Connector for three-phase generator: 6-pin DIN socket
• Rotor axle: 100 mm, 8 mm Ø

727 811 Basic machine unit
INDIVIDUAL COMPONENTS

Rotor position pick-up

Electronic device to pick up the position of ELM magnetic rotor (563 19) and ELM 4-pole magnetic rotor (563 191) together with the three phase generator (725 721). The rotor position pick-up is mounted on the basic machine unit (727 811).

727 812 | Rotor position pick-up

ELM set: Multipole stator and rotor

Set consisting of:

Stator
Multi-pole stator for attachment to basic machine unit 727811 or 72781. The stator block is fixed to the base by means of screws. Using 4-mm safety sockets, the three phase windings can be connected in either star or delta configuration. Each phase winding is divided into five strands. The phase windings are easily distinguished by different coil colours.

Rotor
Rotor equipped with 30 surface mounted permanent magnets, 3 of which are combined to one pole. North and south poles are colour-coded. The rotor can be belt-driven using the drive unit 72788.

Technical data:
• Voltage: 12 V
• Current: $I_{\text{max}} = 1$ A
• Number of poles: 5
• Coil resistance: $2.5 \, \Omega$

Scope of delivery:
• Multi-pole stator
• Rotor with surface mounted magnets
• 4 fastening screws

727 815 | ELM set: Multipole stator and rotor

ELM PM magnet rotor with inner magnets

Rotor with 20 inward facing magnets to be used with the stator 727815. Two magnets are combined into one pole, the north and south poles of which are marked with different colours. The rotor can be belt-driven using the drive unit 72788.

727 816 | ELM PM magnet rotor with inner magnets

Basic terminal unit

For electrical connection of the assembled machine with meters and load units, with fastening bolts for the masks of the corresponding assembled machines.

727 82 | Basic terminal unit

Set of masks

Contains a special mask for each motor or generator type which shows the terminal board with the standardised connections and the symbol of the machine. The mask is hung on the bolts of the basic connection unit.

727 83 | Set of masks

Starter

Circular rheostat with scale from 22...0 $\Omega$ for starting DC motors.

Technical data:
• Resistance: 22 $\Omega$

727 85 | Starter
Field regulator

Circular rheostat with scale 47...0 Ω for setting the excitation of DC machines.

Technical data:
- Resistance: 47 Ω

| 727 86 | Field regulator |

Star–delta load

Plug-in board for assembly of loads for generators with STE plug-in units in star or delta connection.

| 727 87 | Star–delta load |

Drive unit

Universal motor with pulley and phase control for continuous speed adjustment from 0 to 3000 rpm. For assembly on the demonstration experiment frame (301 300) or panel frame (726 19).

Technical data:
- Supply voltage: 230 V AC
- Dimensions: 200 mm x 297 mm

| 727 88 | Drive unit |

Additionally required:

<table>
<thead>
<tr>
<th>Count</th>
<th>Cat.-No.</th>
<th>Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>685 96</td>
<td>Driving belt, long for drive unit 72788</td>
</tr>
</tbody>
</table>

Linear motor basic unit

For use as a track for the linear motor with coil assembly (727 92).

Technical data:
- Length 1500 mm
- Diameter: 16 mm

Scope of delivery:
- 2 training panels with holder for track
- 1 track

| 727 91 | Linear motor basic unit |

Linear motor with coil assembly

Carriage with ball bearings and 3 coils, coil terminals with 4-mm safety sockets.

Technical data:
- Voltage: max. 24 V three-phase voltage
- Tractive force: max. 0.8 Nm

| 727 92 | Linear motor with coil assembly |
CBC 12.5 Servo technology

Disc with Windows program in German, English and French for the measurement of servo data via the serial interface from the block commutation, sine commutation control units or the digital position controller. The software is also used to control these devices. The program contains two different user interfaces, an extended block circuit diagram corresponding to the connected device with all the appropriate operating data and a time line plotter for the display of voltage, current, speed and position. With this software it is possible to record step responses of the servo drive and to investigate contour errors. Furthermore, four different position reference variables can be stored which are then moved to in sequence (to simulate a process).

Technical data:

System requirements:
- Equipment sets E2.6.2.1, E2.6.2.2 or E2.6.2.3
- Windows XP/Vista/7/8, two free USB-Ports

CBM10 MOMO/FCCP

The CD contains two Windows programs in German and English, one for the recording of characteristics of electrical machines (MOMO) and one (FCCP) for the control of the universal converter 735 297 via the control unit PWM 735 291. School licence.

MOMO: Program for recording the characteristics of DC, AC and three-phase machines in the four quadrants of the speed/torque planes. The measurement values for speed, torque, current, voltage, active power and frequency of the feeding system are transferred via the serial port from the control unit for the pendulum machine to the PC. The display of these measurement variables and the variables derived mathematically from them (apparent power, reactance and mechanical power as well as efficiency and slip), can be evaluated graphically or in tabular form. For three-phase machines the current locus curve can also be depicted and slip can be determined graphically. For this there is a wide range of tools at your disposal. The tables can also be processed further using MS-Excel®.

FCCP: Program for adjusting of the control unit PWM. The following parameters can be set:
- Nominal machine data
- Starting voltage, slip and I x R compensation
- Ramp time
- Magnetisation current
- Modulation type.

The current voltage/frequency characteristic is displayed in a graphic.

Technical data:
- Windows XP/Vista/7/8, two free USB ports

Stepper motor

Stepper motor on experiment panel with built-in control logic.
- Operating modes: single-step, half and full-step, clockwise and anti-clockwise rotation
- 64 steps per revolution in half-step mode
- Control: manually via a push button, by means of an external generator or microcomputer, each with TTL level

Technical data:
- Max. control frequency half-step: 800 Hz
- Max. control frequency full-step: 400 Hz
- Inputs and outputs via 4 mm-sockets
- Supply voltage: ±15 V DC

Lamp sockets E14, set of three

3 built-in E14 sockets for incandescent light bulbs, max. 60 W. With 19-mm bridging plugs which can be connected in parallel.

The software is available for download at www.ld-didactic.com.
RS-232 cable, 9-pole
RS 232 cable (1:1) with a 9-pin sub-D connector and a 9-pin sub-D socket.

Coupling 0.3
Rubber coupling sleeve for mechanical connection of two electrical machines of the 0.1 kW or 0.3 kW series.

Shaft end guard 0.3
Attachable guard for protection against contact with electrical machine rotating parts of the 0.1 kW or 0.3 kW series.

Gearbox 0.3
Two-stage planetary gearbox with free-moving motor shaft and drive shaft. Suitable for stepping down high servo speeds (e.g. 6000 rpm) to lower working speeds as well as for increasing the working torque.

Technical data:
- Gear ratio: 36:1
- Constant torque: max. 24 Nm
- Input speed: max. 6000 rpm with CDF (cyclic duration factor) = 10%

Coupling guard 0.3
Attachable guard for protection against contact with electrical machine rotating parts of the 0.1 kW or 0.3 kW series.

Coupling guard 0.3 transparent
Attachable guard for protection against contact with electrical machine rotating parts of the 0.1 kW or 0.3 kW series.

Linear unit 0.3
Linear guide rail with a ball-and-screw spindle for driving a sled. The sled moves a pointer with a vernier scale along a measuring tape with mm divisions and activates the integrated limit switches (NO contacts) at the left and right ends. The entire linear unit is equipped with a plexiglass hood which serves as protection against it being touched.

Technical data:
- Length: 900 mm
- Travel: 650 mm
- Pitch: 5 mm/rotation
- Reading accuracy: 0.1 mm
- Speed: 3000 rpm max.
- Limit switches: 2 NO contacts
- Contact load: 100 V, 0.1 A DC

Similar to illustration
INDIVIDUAL COMPONENTS

Linear unit with position encoder 0.3

Linear guide rail with a ball-and-screw spindle for driving a sled. The sled moves a pointer with a vernier scale along a measuring tape with mm divisions and activates the integrated limit switches (NO contacts) at the left and right ends. A cord connects the slide to an incremental position encoder which supplies two square-wave signals (A, B) displaced by 90° and a reference pulse (REF). The entire linear unit is equipped with a plexiglass hood which serves as protection against it being touched.

Technical data:
- Length: 900 mm
- Travel: 650 mm
- Pitch: 5 mm/rotation
- Reading accuracy: 0.1 mm
- Speed: 3000 rpm max.
- Limit switches: 2 NO contacts
- Contact load: 100 V, 0.1 A DC
- Incremental position encoder, tracking (A, B): 5 pulses/mm
- Incremental position encoder, REF tracking: 1 pulse/100 mm

Scope of delivery:
- Connecting lead, 6-pole, L = 1.5 m

| 731 086 | Linear unit with position encoder 0.3 |

Potentiometric angle transducer 0.3

Transducer used for measuring the actual angular position of a shaft for the precise positioning of a drive via position servo control. The transducer is equipped with a 360 degree scaled angle disc for visual display of the shaft position.

Technical data:
- Reading accuracy: 1°
- Speed: 200 rpm max.
- Potentiometer: 10 kΩ
- Extent of rotation, mechanical, 360° unlimited
- Extent of rotation, electric, 340°
- Resolution with respect to infinity
- Supply voltage: ±15 V DC

| 731 089 | Potentiometric angle transducer 0.3 |

Tacho generator 0.3

For registering the speed of electrical machines in the 0.1 kW and 0.3 kW series.

Technical data:
- Output voltage: ±1 V/1000 rpm

| 731 09 | Tacho generator 0.3 |

Incremental tacho 0.3

For registering the speed of electrical machines in the 0.1 kW and 0.3 kW power class, as well as for incremental positioning of a servo machine. The TTL-compatible signals, A, B and REF, are accessible via 4-mm sockets. 1024 pulses at A or B correspond to a mechanical angle of rotation of 360 degrees. The signals A and B are phase-shifted by 90 degrees for the determination of the shaft's rotation direction. The REF pulse is generated once per shaft revolution. The universal speed indicator or the control unit block commutation is needed for the power supply and display.

Technical data:
- Connection: 6-pin DIN socket
- Speed: 10,000 rpm max.
- Increments: 1024 pulses/360°

Scope of delivery:
Contained in Scope of delivery: Connection cable, 6-pole, L = 1.5 m.

| 731 092 | Incremental tacho 0.3 |
Resolver 0.3

Brushless hollow-shaft resolver for detecting the angular position of a shaft. The resolver serves as a detector for the sine commutation of a permanently excited brushless DC motor as well as for recording the speed and positioning in AC servo drives. In order to set the shaft position of the resolver in a definite position with respect to the AC servo motor, the resolver stator can be mechanically adjusted by ±45 degrees. The resolver is fed with a sinusoidal signal and supplies two signals of equal frequency, but different amplitudes to the output. The amplitudes are dependent on the angular position of the shaft. With one revolution of the shaft, the envelope curves of the amplitudes produce one sinusoidal and one cosine signal of 360° electrical each. From these signals the evaluating electronics in the sine commutation control unit (735 293) determines the absolute position of the shaft.

Technical data:
- Speed: 10,000 rpm max.
- Transformation ratio: 0.5
- Electrical error: ±0.25°
- The inputs and outputs are each accessible via 4-mm sockets or 6-pin DIN socket
- Supply voltage: 4 V/10 kHz supplied by the sine commutation control unit

Scope of delivery:
- Connection cable 6-pole, L = 1.5 m

Commutation pick-up 0.3

For determining the rotor position of a permanently-excited brushless DC motor (AC servo). The pick-up contains three Hall-type switches and a 4-pole pick-up magnet mounted to the shaft. In order to set the shaft position of the commutation pick-up in a definite position with respect to the AC servo motor, the pick-up magnet can be mechanically adjusted by ± 45 degrees. The signals generated during the rotation of the shaft supply the evaluating criteria for the block signal type commutation of a 4-pole AC servo motor.

Technical data:
- Speed: 10,000 rpm max.
- Output voltage: TTL level
- Supply voltage: + 15 V DC supplied by block commutation control unit, cat. no. 735 292

Scope of delivery:
- Connection cable 6-pole, L = 1.5 m

Interference suppressor filter 0.3

Two-stage interference suppressor filter with two current-compensated chokes each and two class X and Y capacitors each and one choke connected to the protective earth connector for the disturbance suppression of the universal motor 0.3 and repulsion motor 0.3. The filter is connected between the mains and machine and reduces the machine's output of line-bound disturbance signals in a low-voltage network in accordance with EN 5008-1.

Technical data:
- V = 110/230 V, 47...62 Hz
- I_n = 6 A

Squirrel cage fault simulator

The fault simulator, in conjunction with asynchronous squirrel-cage motors allows for simulation of typical malfunctions like shorts to ground, winding breaks, turn-to-turn faults, winding-to-frame shorts and tripping of the thermal circuit breaker. The faults are generated by 13 switches arranged behind a locked cover. The fault simulator is an adapter to be attached to the terminal panel of the squirrel cage motor.

731 391 Squirrel cage fault simulator
INDIVIDUAL COMPONENTS

On/off switch, three-pole
For switching of three-phase units.

Technical data:
• Switch load: 20 A / 500 V AC
• Switch positions: 0 - 1

731 42 On/off switch, three-pole

Star–delta switch
To start induction machines.

Technical data:
• Switch load: 20 A / 500 V AC
• Switch positions: 0 - Y - Δ

731 47 Star–delta switch

Star–delta reversing switch
To start and to change the direction of rotation of induction machines.

Technical data:
• Switch load: 20 A / 500 V AC
• Switch positions: Δ - Y - 0 - Y - Δ

731 48 Star–delta reversing switch

Reversing switch
To change the direction of rotation of three-phase motors.

Technical data:
• Switch load: 20 A / 500 V AC
• Switch positions: 1 - 0 - 2

731 49 Reversing switch

Star–delta starter
Contactor group with time relays for starting three-phase motors of up to approx. 1.5 kW. On/off switching is carried out via two pushbuttons I and 0. Automatic switchover from star to delta is carried out after the preset time elapses. The momentary operating status is displayed via two signal lamps.

Technical data:
• Switching capacity: 1.5 kW
• Switchover time delay: 0.3...30 s
• Supply voltage: 3 x 400 V AC

731 50 Star–delta starter

Soft starter 0.3 /1.0
3-phase soft control device for asynchronous machines with control input and the following setting options:
• Start ramp time
• Start voltage
• Stop ramp time

731 51 Soft starter 0.3 /1.0
### Pole reverser, Dahlander

Switching over the stator windings of special asynchronous machines alters the number of pole pairs and therefore the synchronous speed of the rotating field.

Technical data:
- **Switch load:** 20 A/500 V AC
- **Switch positions:** 0 - 1 - 2

| 731 55 | Pole reverser, Dahlander |

### Pole reverser SW

For switching over the stator windings of asynchronous machines with separate windings.

Technical data:
- **Switch load:** 20 A/500 V AC
- **Switch positions:** 0 - 1 - 2

| 731 57 | Pole reverser SW |

### Blocking gear 0.3

Hand operated gear mechanism for setting the rotor of three-phase 0.3 kW asynchronous motors with slip ring rotor when used as a phase shifting transformer.

Technical data:
- \( n_2 = 1 \)
- \( n_1 = 20 \)

| 731 65 | Blocking gear 0.3 |

### DC compound machine 0.3

DC compound machine for motor and generator operation, can be used as shunt, series, or compound wound machine; series winding with tap for compounding and shunt winding. All windings are separately connected to 4 mm safety sockets.

Technical data:
- **Power:** 0.3 kW
- **Voltage:** 220 V
- **Current:** 1.8 A
- **Excitation voltage:** 220 V
- **Excitation current:** 0.25 A
- **Speed:** 2000 rpm

| 731 86 | DC compound machine 0.3 |

### Shunt wound machine 0.3

DC shunt wound machine for motor and generator operation. All windings are separately connected to 4 mm safety sockets.

Technical data:
- **Class:** 0.3
- **Power:** 0.3 kW
- **Voltage:** 220 V
- **Current:** 1.8 A
- **Excitation voltage:** 220 V
- **Excitation current:** 0.25 A
- **Speed:** 2000 rpm
- **International protection code:** IP 20
- **Insulation system:** B/F

| 731 91 | Shunt wound machine 0.3 |
Series wound machine 0.3

DC series wound machine for motor and generator operation. All windings are separately connected to 4 mm safety sockets.

Technical data:
- Power: 0.3 kW
- Voltage: 220 V
- Current: 1.9 A
- Speed: 2000 rpm

731 92 Series wound machine 0.3

Double wound machine 0.3

DC double wound machine for motor and generator operation. All windings are separately connected to 4-mm safety sockets.

Technical data:
- Power: 0.3 kW
- Voltage: 220 V
- Current: 1.8 A
- Excitation voltage: 220 V
- Excitation current: 0.25 A
- Speed: 2000 rpm

731 93 Double wound machine 0.3

Starter 0.3

Circular rheostat (step winding) with scale (100 - 0%) for starting 0.3 kW DC motors.

Technical data:
- Resistance: 47 Ω
- Current: 2.5 A

731 94 Starter 0.3

Field regulator, motor 0.3

Circular rheostat with scale (0 - 100%) for adjusting the excitation in 0.3 kW DC shunt and compound wound motors.

Technical data:
- Resistance: 560 Ω
- Current: 0.52 A

731 95 Field regulator, motor 0.3

Field regulator, generator 0.3

Circular rheostat with short-circuit contact and scale 0 - 100% for adjusting the excitation in 0.3 kW DC shunt and compound wound generators.

Technical data:
- Resistance: 560 Ω
- Current: 0.52 A

731 96 Field regulator, generator 0.3
Machine test system 0.3

Equipment set for recording the characteristics of electrical machines of the 0.3 kW class in all four quadrants, consisting of:

- Cradle-type three-phase asynchronous machine
- Control unit

Cradle-type three-phase asynchronous machine
Squirrel-cage rotor on oscillating bearing with integrated torque pick-up for recording speed, plus stainless steel bending bar with strain gauge for measuring torque. This specially-designed machine can drive any of the machines contained in the electrical machine system 0.3 kW power class and brake any of them down to a standstill. Power is supplied from a control unit via a 7-pole connecting cable with round 7-pin connector, while signals are transmitted via a fixed cable with D-Sub plug connectors.

Control unit
Microcontroller equipped device with integrated frequency converter for the power supply and control of the cradle-type three-phase asynchronous machine. Display of speed and torque of the machine under test. Manual and automatic recording of the characteristics in all four quadrants of the speed/torque plane. Connection to the PC via USB port.

Technical data:
- Automatic digital speed control: ±5000 rpm
- Automatic digital torque control: ±9.9 Nm
- Automatic recording of run-up and load characteristics
- Load simulations: flywheel, freely adjustable fan drive (M→ kN), lift drive (constant torque)
- Characteristics recorded in accordance with user specifications (M=ni)
- External control: ±10 V
- Seven-segment display, 25 mm high
- Speed: 4 digits
- Torque: 3 digits
- Parallel operation is possible with the help of the software
- Temperature monitoring:
  - Machine under test
  - Cradle type three-phase asynchronous machine
  - Control unit
- Shaft guard monitoring: system shut-down with protection for unintended system start
- Four quadrant display with LEDs for operating mode of the machine under test
- Adjustable torque limiting (overload protection) and stop speed (for automatic characteristic recording)
- RMS measurement: three inputs for voltage measurement (Vmax=600 V AC/DC), one input for current measuring (Imax=10 A AC/DC), all suitable for frequency converter
- USB connection for transmission of measured values and remote control via software CBM 10
- Highest security standards: leakage current <5 mA
- Power supply: 230 V, 47 ... 62 Hz, 2 kW

Scope of delivery:
- Mains lead with earth-contact plug
- Demo version of software CBM 10
- USB cable, 3 m
- 25-pole connecting cable
- Supply cable for cradle-type machine
- Dynamometer
- Cylindrical bar

AC servo motor 0.3

Permanently-excited 4-pole brushless DC motor for use as a direct drive and for implementing highly dynamic positioning and automatic drives in 4-quadrant operation mode.
Universal motor 0.3

For operation with AC or DC.

Technical data:

Ratings for connection to AC:
• Power: 0.2 kW
• Voltage: 230 V
• Current: 2.5 A
• Frequency: 50 Hz
• Speed: 3000 rpm

Ratings for connection to DC:
• Power: 0.2 kW
• Voltage: 140 V
• Current: 3 A
• Speed: 3000 rpm

Repulsion motor 0.3

With adjustable brushes for change of speed and direction.

Technical data:
• Setting range: -2100...0...+2100 rpm
• Power: 0.25 kW
• Voltage: 230 V
• Current: 2.9 A
• Frequency: 50 Hz
• Power factor: 0.69
• Speed: 2100 rpm

Auxiliary phase motor R 0.3

Single-phase AC motor with starting relay and bifilar starter winding.

Technical data:
• Power: 0.2 kW
• Voltage: 230 V
• Current: 2.6 A
• Frequency: 50 Hz
• Power factor: 0.7
• Design: 4-pole
• Speed: 1380 rpm

Capacitor motor R 0.3

Single-phase AC motor with starting relay, starting and operating capacitor. Industrial design with one shaft end.

Technical data:
• Power: 0.37 kW
• Voltage: 230 V
• Current: 2.6 A
• Frequency: 50 Hz
• Power factor: 0.93
• Starting capacitor $C_s$: 50-63 µF
• Operating capacitor $C_r$: 20 µF
• Design: 4-pole
• Speed: 1400 rpm
Auxiliary phase motor F 0.3

Single-phase AC motor with centrifugal switch and bifilar starter winding.

Technical data:
- Power: 0.2 kW
- Voltage: 230 V
- Current: 2.6 A
- Frequency: 50 Hz
- Design: 4-pole
- Speed: 1380 rpm

Capacitor motor F 0.3

Single-phase AC motor with centrifugal switch, starting and operating capacitor.

Technical data:
- Power: 0.25 kW
- Voltage: 230 V
- Current: 2.2 A
- Frequency: 50 Hz
- Power factor: 0.85
- Design: 4-pole
- Speed: 1420 rpm

Squirrel cage motor 230/400/0.3

Three-phase asynchronous motor with squirrel cage rotor, industrial design with one shaft end.

Technical data:
- Class: 0.3
- Power: 0.25 kW
- Voltage: 400 /230 V, Y/ Δ
- Current: 0.76 /1.32 A
- Frequency: 50 Hz
- Power factor: 0.79
- Design: 4-pole
- Speed: 1350 rpm
- International protection code: IP 20
- Insulation system: F

Squirrel cage motor 400/690/0.3

Three-phase asynchronous motor with squirrel cage rotor and distinct pull-out torque. Industrial design with one shaft end.

Technical data:
- Class: 0.3
- Power: 0.27 kW
- Voltage: 400/690 V, Δ/Y
- Current: 1.0/0.58 A
- Frequency: 50 Hz
- Power factor: 0.7
- Design: 4-pole
- Speed: 1350 rpm
Squirrel cage motor basic 230/400/0.3
Industrial three-phase asynchronous motor with squirrel cage rotor.

Technical data:
• Power: 0.25 kW
• Voltage: 230/400 V, Δ/Y
• Current: 1.0/0.58 A
• Frequency: 50 Hz
• Design: 4-pole
• Speed: 1445 rpm

Squirrel cage motor basic 230/400, brake 0.3
Industrial three-phase asynchronous motor with cage rotor, with one shaft extension. With electro-mechanical holding brake, controlled via a rectifier.

Technical data:
• Power: 0.25 kW
• Voltage: 230/400 V, Δ/Y
• Current: 1.0/0.58 A
• Frequency: 50 Hz
• Design: 4-pole
• Speed: 1445 rpm

Squirrel cage motor basic 400/690/0.3
Industrial three-phase asynchronous motor with squirrel cage rotor, one shaft end.

Technical data:
• Class: 0.3
• Power: 0.25 kW
• Voltage: 400/690 V, Δ/Y
• Current: 1.0/0.58 A
• Frequency: 50 Hz
• Design: 4-pole
• Speed: 1445 rpm

Capacitor motor CS basic 0.3
Industrial single phase alternating current motor with centrifugal switch, start and operation condenser and one shaft extension end.

Technical data:
• Power: 0.25 kW
• Voltage: 230 V
• Current: 1.0/0.58 A
• Frequency: 50 Hz
• Design: 4-pole
• Speed: 1440 rpm
Motor protection switches

<table>
<thead>
<tr>
<th>Cat.-No.</th>
<th>Designation</th>
</tr>
</thead>
<tbody>
<tr>
<td>732 13</td>
<td>Motor protection switch, 0.6-1 A</td>
</tr>
<tr>
<td>732 14</td>
<td>Motor protection switch, 1-1.6 A</td>
</tr>
<tr>
<td>732 83</td>
<td>Motor protection switch, 1.6-2.4 A</td>
</tr>
<tr>
<td>732 84</td>
<td>Motor protection switch, 2.4-4 A</td>
</tr>
<tr>
<td>733 54</td>
<td>Motor protection switch, 6-10 A</td>
</tr>
</tbody>
</table>

Squirrel cage motor D 0.3

Three-phase asynchronous motor with squirrel cage rotor, Dahlander circuit, pole reversible. Industrial design with one shaft end.

Technical data:
- Power: 0.25/0.37 kW
- Voltage: 400 V, Δ/Y-Y
- Current: 1.0/1.1 A
- Frequency: 50 Hz
- Power factor: 0.62/0.75
- Design: 4/2-pole
- Speed: 1400/2800 rpm

Squirrel cage motor SW 0.3

Three-phase asynchronous motor with squirrel cage rotor, 2 separate windings, pole reversible.

Technical data:
- Power: 0.11/0.20 kW
- Voltage: 400 V, Y/Y
- Current: 0.6/0.7 A
- Frequency: 50 Hz
- Power factor: 0.71/0.72
- Design: 6/2-pole
- Speed: 880/1390 rpm

Multi-function machine 0.3

Three-phase multi-function machine, can be used as slip ring motor or as synchronous machine for motor and generator operation.

Technical data:
Operation as asynchronous motor
- Power: 0.27 kW
- Voltage: 230/400 V, Δ/Y
- Current: 1.44/0.83 A
- Frequency: 50 Hz
- Power factor: 0.7
- Design: 4-pole
- Speed: 1360 rpm

Operation as synchronous motor
- Power: 0.27 kW
- Voltage: 230/400 V, Δ/Y
- Current: 0/0.52 A
- Excitation voltage: 20 V
- Excitation current: 4 A
- Frequency: 50 Hz
- Power factor: 1
- Design: 4-pole
- Speed: 1500 rpm
INDIVIDUAL COMPONENTS

Rotor starter 0.3

Three resistors, synchronously adjustable in 6 steps, for slip ring motors and 0.3 kW multi-function machines.

Technical data:
- Resistance values of switch steps: 20/10/5.5/2.5/1/0 Ω
- Additional fixed taps at: 10/2.5 Ω

Slip–ring motor 0.3

Three-phase asynchronous motor with slip ring rotor.

Technical data:
- Power: 0.27 kW
- Voltage: 230/400 V, Δ/Y
- Current: 2/1.16 A
- Frequency: 50 Hz
- Power factor: 0.72
- Design: 4-pole
- Speed: 1340 rpm

Synchronous machine SP 0.3

Three-phase synchronous machine with salient pole rotor and damper cage for motor and generator operation.

Technical data:
- Power: 0.3 kW
- Voltage: 400 V, Y
- Current: 0.43 A
- Excitation voltage: max.140 V
- Excitation current: max.0.55 A
- Frequency: 50 Hz
- Power factor: 1/0.8
- Design: 4 pole
- Speed: 1500 rpm

Synchronous machine SR 0.3

Three-phase synchronous machine with smooth-core rotor and damper cage for motor and generator operation.

Technical data:
Motor operation
- Power: 0.3 kW
- Voltage: 230/400 V, Δ/Y
- Current: 0.66/1.14 A
- Excitation voltage: max.150 V
- Excitation current: max.0.95 A
- Frequency: 50 Hz
- Power factor: 0.97
- Design: 4-pole
- Speed: 1500 rpm
Resistive load 0.3

Three synchronously adjustable circular rheostats (step winding) with scale (100 - 0%), each with a series resistor and fuse in the sliding-contact connection, suitable for parallel, series, star and delta circuits.

Technical data:
- Resistance: 3 x 1800 Ω
- Series resistance: 3 x 47 Ω
- Current: 3 x 1 A

Capacitive load 0.3

Three groups of MP capacitors, each consisting of four capacitors, suitable for parallel, series, star and delta circuits.

Technical data:
- Capacitors:
  - 3 x 1/2/4 µF, 450 V
  - 3 x 8 µF, 400 V

Inductive load 0.3/1.0

Three inductors with taps suitable for parallel, series, star and delta circuits.

Technical data:
- Inductors:
  - 0.2/0.4/0.6 H (0.65 A)
  - 0.8/1.0/1.2 H (0.5 A)
  - 2.4/4.8/6.0 H (0.25 A)

Flywheel 0.3

Suitable for determining friction losses in electrical machines with the aid of run-down experiments. In the case of electrical machines with exciter circuits, the iron and copper losses can also be determined. In the case of two and four quadrant drives, the energy recovery into the mains can be enlarged using the flywheel.

Technical data:
- Class: 0.3
- Speed: max. 3000 rpm
- Inertial torque: 0.006 kg m²

Reluctance motor 0.3

Three-phase synchronous motor without separate excitation.

Technical data:
- Power: 0.25 kW
- Voltage: 380 V Δ
- Current: 1.5 A
- Frequency: 50 Hz
- Power factor: 0.45
- Design: 4-pole
- Speed: 1500 rpm
INDIVIDUAL COMPONENTS

Motor with FCC 0.3

FCM 305 industrial frequency converter motor from the DANFOSS FCM 300 series, with 0.55 kW four-pole three-phase asynchronous motor and attached VLT® frequency converter. With optimum frequency converter and motor integration performed by the manufacturer. Standard start/stop and jog operating modes with variable speed carried out using the components already integrated into the motor cover.

Technical data:
- PROFIBUS DP/RS 485 compatible.
- Motor output power: 0.55 kW
- Mains voltage range: 3x 380...480 V ±10%
- Input current: 1.4 A (380 V), 1.1 A (480 V)
- Mains frequency: 50/60 Hz
- Power factor cos φ: 0.88/1.0 at nominal load
- Frequency range: 0...132 Hz
- Protection against: excess temperature, phase failure, under and over-voltage, voltage spikes

Socket assignment on the motor cover (4-mm safety sockets with PELV electrical isolation):
- START, JOG, RESET: with respect to internal +24 V, suitable for PLC programmable control.
- ANALOG 1 IN: with respect to internal +10 V, suitable for automatic control applications
- ANALOG 2 IN: 0...20 mA (with respect to the GND socket, measurement current loop input)
- ANA/DIG OUT: 0...20 mA/high-low level
- Mains connection: 4-mm safety sockets L1, L2, L3, PE
- PROFIBUS connection: 9-pin sub-D socket, contact assignment in conforming to EN 50170

Scope of delivery:
- Including technical documentation and software for setting parameters, observing and documenting the frequency converter.

Motor with FCC 1.0

FCM 311 industrial frequency converter motor from the DANFOSS FCM 300 series, with 1.1 kW four-pole three-phase asynchronous motor and attached VLT® frequency converter. With optimum frequency converter and motor integration performed by the manufacturer. Standard start/stop and jog operating modes with variable speed carried out using the components already integrated into the motor cover.

Technical data:
- PROFIBUS DP/RS 485 compatible.
- Motor output power: 1.1 kW
- Mains voltage range: 3x 380...480 V ±10%
- Input current: 2.5 A (380 V), 2.0 A (480 V)
- Mains frequency: 50/60 Hz
- Power factor cos φ: 0.88/1.0 at nominal load
- Frequency range: 0...132 Hz
- Protection against: excess temperature, phase failure, under and over-voltage, voltage spikes

Socket assignment on the motor cover (4-mm safety sockets with PELV electrical isolation):
- START
- JOG
- RESET: with respect to internal +24 V, suitable for PLC programmable control.
- ANALOG 1 IN: with respect to internal +10 V, suitable for automatic control applications
- ANALOG 2 IN: 0...20 mA (with respect to the GND socket, measurement current loop input)
- ANA/DIG OUT: 0...20 mA/high-low level
- Mains connection: 4-mm safety sockets L1, L2, L3, PE
- PROFIBUS connection: 9-pin sub-D socket, contact assignment in conforming to EN 50170

Scope of delivery:

Coupling 1.0

Rubber coupling sleeve for mechanical connection of two electrical machines of the 1.0 kW series.

www.ld-didactic.com
Shaft end guard 1.0
Attachable guard for protection against contact with electrical machine rotating parts of the 1.0 kW series.

732 57  Shaft end guard 1.0

Coupling guard 1.0
Attachable guard for protection against contact with electrical machine rotating parts of the 1.0 kW series.

732 58  Coupling guard 1.0

DC multi-function machine 1.0
DC multi-function machine for motor and generator operation, can be used as shunt, series, or compound wound machine, series and shunt winding with tap for compounding, with commutating winding and compensation winding. All windings are separately connected to 4 mm safety sockets.

Technical data:
Operation as compound wound motor
• Class: 1.0
• Power: 0.75 kW
• Voltage: 220/135 V
• Current: 4.8/5.8/5.4 A
• Excitation voltage: 220 V
• Excitation current: 0.24 A
• Speed: 2000/1700 rpm
• International protection code: IP 20
• Insulation system: B/F

732 60  DC multi-function machine 1.0
Similar to illustration

Shunt wound machine 1.0
DC shunt wound machine for motor and generator operation, with commutating winding and compensation winding. All windings are separately connected to 4-mm safety sockets.

Technical data:
Motor operation
• Class: 1.0
• Power: 1.0 kW
• Voltage: 220 V
• Current: 6.2 A
• Excitation voltage: 200 V
• Excitation current: 0.25 A
• Speed: 2100 rpm
• International protection code: IP 20
• Insulation system: B/F

732 61  Shunt wound machine 1.0
Similar to illustration

Series wound machine 1.0
DC series wound machine for motor and generator operation, with commutating winding and compensation winding. All windings are separately connected to 4-mm safety sockets.

Technical data:
Motor operation
• Class: 1.0
• Power: 1.0 kW
• Voltage: 220 V
• Current: 6.5 A
• Speed: 2200 rpm
• International protection code: IP 20
• Insulation system: B/F

732 62  Series wound machine 1.0
Similar to illustration
INDIVIDUAL COMPONENTS

Starter 1.0
Circular rheostat (step winding) with scale 100 - 0 % for starting DC motors 1.0 kW.

Technical data:
• Resistance: 13 Ohm
• Current: 8.5 A

Field regulator, motor 1.0
Circular rheostat with scale 0 - 100 % for adjusting the excitation in DC shunt and compound wound motors 1.0 kW.

Technical data:
• Resistance: 330 Ohm
• Current: 0.68 A

Machine test system 1.0
Equipment set for recording the characteristics of electrical machines of the 1 kW class, consisting of:
• Cradle-type three-phase asynchronous machine
• Control unit

Cradle-type three-phase asynchronous machine
Squirrel-cage rotor on oscillating bearing with integrated torque pick-up for recording speed, plus stainless steel bending bar with strain gauge for measuring torque. This specially-designed machine can drive any of the machines contained in the electrical machine system 1.0 kW power class and brake any of them down to a standstill. Power is supplied from a control unit via a 7-pole connecting cable with round 7-pin connector, while signals are transmitted via a fixed cable with D-Sub plug connectors.

Control unit
Microcontroller equipped device with integrated frequency converter for the power supply and control of the cradle-type three-phase asynchronous machine. Display of speed and torque of the machine under test. Manual and automatic recording of the characteristics in all four quadrants of the speed/torque plane. Connection to the PC via USB port.

Technical data:
• Automatic digital speed control: ±5000 rpm
• Automatic digital torque control: ±19.9 Nm
• Automatic recording of run-up and load characteristics
• Load simulations: flywheel, freely adjustable fan drive (M~ kN) freely adjustable winding drive (M~ k/n), lift drive (constant torque)
• Characteristics recorded in accordance with user specifications (M~ n)
• External control: ±10 V
• Seven-segment display, 25 mm high
  Speed: 4 digits
  Torque: 3 digits
• Parallel operation is possible with the help of the software
• Temperature monitoring:
  Machine under test
  Cradle-type three-phase asynchronous machine
  Control unit
  Shaft guard monitoring: system shut-down with protection for unintended system start
• Four quadrant display with LEDs for operating mode of the machine under test
• Adjustable torque limiting (overload protection) and stop speed (for automatic characteristic recording)
• RMS measurement: three inputs for voltage measurement (V_{max}=600 V AC/DC), one input for current measuring (I_{max}=15 A AC/DC), all suitable for frequency converter
• USB connection for transmission of measured values and remote control via software CBM 10
• Highest security standards: leakage current <5 mA
• Power supply: 230 V, 47 ... 62 Hz, 2 kW

Scope of delivery:
• Mains lead with earth-contact plug
• Demo version of software CBM 10
• USB cable, 3 m
• 25-pole connecting cable
• Supply cable for cradle-type machine
• Dynamometer
• Cylindrical bar

www.ld-didactic.com
Universal motor 1.0
For operation with 230 V AC or DC.

Technical data:
• Class: 1.0
• International protection code: IP 20
• Insulation system: B/F

Ratings for connection to AC:
• Power: 0.75 kW
• Voltage: 230 V
• Current: 5.2 A
• Frequency: 50 Hz
• Power factor: 0.78
• Speed: 2650 rpm

Ratings for connection to DC:
• Power: 0.8 kW
• Voltage: 220 V
• Current: 5.2 A
• Speed: 2650 rpm

Interference suppressor filter 1.0
Two-stage interference suppressor filter with two current-compensated chokes each and two class X and Y capacitors each for the disturbance suppression of the 1.0 kW universal motor and 1.0 kW repulsion motor. The filter is connected between the mains and machine and reduces the machine's output of line-bound disturbance signals in a low-voltage network in accordance with EN 5008-1.

Technical data:
• V = 110/250 V, 50/60 Hz
• IN = 10 A

Repulsion motor 1.0
With adjustable brushes for change of speed and direction.

Technical data:
• Class: 1.0
• Setting range: -2900...0...+2900 rpm
• Power: 1.0 kW
• Voltage: 230 V
• Current: 10.2 A
• Frequency: 50 Hz
• Power factor: 0.65
• Speed: 2900 rpm
• International protection code: IP 20
• Insulation system: B/F

Auxiliary phase motor R 1.0
Single-phase AC motor with starting relay and bifilar starter winding.

Technical data:
• Power: 0.75 kW
• Voltage: 220 V
• Current: 5.8 A
• Frequency: 50 Hz
• Power factor: 0.81
• Design: 2-pole
• Speed: 2870 rpm
**INDIVIDUAL COMPONENTS**

**Capacitor motor R 1.0**

Single-phase AC motor with starting relay, starting and operating capacitor.

Technical data:
- Power: 1.0 kW
- Voltage: 230 V
- Current: 6.4 A
- Frequency: 50 Hz
- Power factor: 0.99
- Design: 2-pole
- Speed: 2790 rpm

**Capacitor motor F 1.0**

Single-phase AC motor with centrifugal switch, starting and operating capacitor. Industrial design with one shaft end.

Technical data:
- Class: 1.0
- Power: 1.1 kW
- Voltage: 230 V
- Current: 6.6 A
- Frequency: 50 Hz
- Power factor: 0.98
- Starting capacitor: C_s = 80 µF
- Operating capacitor: C_o = 30 µF
- Design: 4-pole
- Speed: 1400 rpm
- International protection code: IP 20
- Insulation system: F

**Squirrel cage motor 230/400 1.0**

Three-phase asynchronous motor with squirrel cage rotor, industrial design with one shaft end.

Technical data:
- Class: 1.0
- Power: 1.0 kW
- Voltage: 230/400 V, Δ/Y
- Current: 4.6/2.7 A
- Frequency: 50 Hz
- Power factor: 0.83
- Design: 4-pole
- Speed: 1410 rpm
- International protection code: IP 20
- Insulation system: F

**Squirrel cage motor 400/690 1.0**

Three-phase asynchronous motor with squirrel cage rotor and distinct pull-out torque.

Technical data:
- Class: 1.0
- Power: 1 kW
- Voltage: 400/690 V, Δ/Y
- Current: 2.5/1.44 A
- Frequency: 50 Hz
- Power factor: 0.79
- Design: 4-pole
- Speed: 1405 rpm
- International protection code: IP 20
- Insulation system: B
Squirrel cage motor D 1.0

Three-phase asynchronous motor with squirrel cage rotor, Dahlander circuit, pole reversible. Industrial design with one shaft end.

Technical data:
- Power: 0.75/1.1 kW
- Voltage: 400 V, Δ/Y-Y
- Current: 1.8/2.7 A
- Frequency: 50 Hz
- Power factor: 0.8/0.84
- Design: 4/2 pole
- Speed: 1425/2850 rpm

Similar to illustration

Squirrel cage motor SW 1.0

Three-phase asynchronous motor with squirrel cage rotor, 2 separate windings, pole reversible. Industrial design with one shaft end.

Technical data:
- Power: 0.4/1.0 kW
- Voltage: 400 V, Y/Y
- Current: 1.6/3.1 A
- Frequency: 50 Hz
- Power factor: 0.64/0.76
- Design: 6/2 pole
- Speed: 930/2870 rpm

Similar to illustration

Multi-function machine 1.0

Three-phase multi-function machine with slip ring rotor can be used as induction machine or as synchronous machine for motor and generator operation.

Technical data:
- Class: 1.0
- International protection code: IP 20
- Insulation system: B/F

Ratings for operation as slip ring motor:
- Power: 0.8 kW
- Voltage: 230/400 V, Δ/Y
- Current: 3.5/2.0 A
- Frequency: 50 Hz
- Power factor: 0.75
- Design: 4-pole
- Speed: 1400 rpm

Ratings for operation as synchronous motor:
- Power: 0.8 kW
- Voltage: 230/400 V, Δ/Y
- Current: 2.6/1.5 A
- Excitation voltage: 24 V
- Excitation current: 11 A
- Frequency: 50 Hz
- Power factor: 1.0
- Design: 4-pole
- Speed: 1500 rpm

Similar to illustration
### Rotor starter 1.0

Three resistors, synchronously adjustable in 6 steps, for slip ring motor and 1.0 kW multi-function machine.

Technical data:
- Resistance values of switch steps: 10/5/2.75/1.25/0.5/0 Ω
- Additional fixed taps at: 5/1.25 Ω

### Slip-ring motor 1.0

Three-phase asynchronous motor with slip ring rotor.

Technical data:
- Class: 1.0
- Power: 1.0 kW
- Voltage: 230/400 V, Δ/Y
- Current: 4.8/2.8 A
- Power factor: 0.71
- Design: 4-pole
- Speed: 1420 rpm
- International protection code: IP 20
- Insulation system: B/F

### Synchronous machine SP 1.0

Three-phase synchronous machine with salient pole rotor and damper cage for motor and generator operation.

Technical data:
- Class: 1.0
- Power: 1.0 kVA / 0.8 kW
- Voltage: 400 V, Y
- Current: 1.52 A
- Excitation voltage: max. 220 V
- Frequency: 50 Hz
- Power factor: 0.8-1-0.8
- Design: 4-pole
- Speed: 1500 rpm
- International protection code: IP 20
- Insulation system: B/F

### Synchronous machine SC 1.0

Three-phase synchronous machine with smooth core rotor and damper cage for motor and generator operation.

Technical data:
- Class: 1.0
- Power: 0.8 kVA / 0.8 kW
- Voltage: 230/400 V, Δ/Y
- Current: 2.66/1.52 A
- Excitation voltage: max. 220 V
- Frequency: 50 Hz
- Power factor: 0.8-1-0.8
- Design: 4-pole
- Speed: 1500 rpm
- International protection code: IP 20
- Insulation system: B/F
Resistive load 1.0

Three synchronously adjustable circular rheostats (step winding) with scale (100 – 0%), each with a series resistor and fuse in the sliding-contact connection, suitable for parallel, series, star and delta circuits.

Technical data:
- Resistance: 3 x 1000 Ω
- Series resistance: 3 x 22 Ω
- Current: 3 x 2.5 A

Capacitive load 1.0

Three groups of MP capacitors, each consisting of four capacitors, suitable for parallel, series, star and delta circuits.

Technical data:
- Capacitances:
  - 3 x 2/4 µF, 450 V
  - 3 x 8/16 µF, 400 V

Flywheel 1.0

Suitable for determining friction losses in electrical machines with the aid of run-down experiments. In the case of electrical machines with exciter circuits, the iron and copper losses can also be determined. In the case of two and four quadrant drives, the energy regenerating into the mains can be prolonged using the flywheel.

Technical data:
- Class: 1.0
- Speed: max. 3000 rpm
- Inertial torque: 0.03 kg m²

Three-phase transformer 0.3

Suitable for all circuit configurations. All connections via 4-mm safety sockets.

Technical data:
- Power: 300 VA
- Primary: 3 x 400/230 V, 50 Hz
- Secondary: 3 x 2 x 115 V

Three-phase transformer 1.0

Suitable for all circuit configurations. All connections via 4-mm safety sockets.

Technical data:
- Power: 1000 VA
- Primary: 3 x 400/230 V, 50 Hz
- Secondary: 3 x 2 x 115 V
### Scott transformer

For transforming from a two-phase to a three-phase mains and vice-versa using a Scott circuit. It can also be used as a three-phase isolating transformer for transformation of 3 x 115/230/400 V into 3 x 115/230 V and vice-versa.

**Technical data:**
- All connections via 4-mm safety sockets
- Power: 2 x 150 VA
- Primary: 2 x 115/200/220/346/400 V, 50 Hz
- Secondary: 2 x 115/230 V

| 733 93 | Scott transformer |

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### Single-phase transformer 0.3

All connections via 4-mm safety sockets.

**Technical data:**
- Power: 300 VA
- Primary: 230 V, 50/60 Hz
- Secondary: 2 x 115 V

| 733 97 | Single-phase transformer 0.3 |

---

### AC toroidal core transformer 0.3

All connections via 4-mm safety sockets.

**Technical data:**
- Power: 300 VA
- Primary: 230 V, 50 Hz
- Secondary: 2 x 115 V

| 733 98 | AC toroidal core transformer 0.3 |

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### AC autotransformer 0.3

All connections via 4-mm safety sockets.

**Technical data:**
- Power: 300 VA
- Primary: 230 V, 50 Hz
- Secondary: 115/230/240 V

| 733 99 | AC autotransformer 0.3 |

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### Reference variable generator

For the generation of a setpoint value, with linear division of the reference variable potentiometer.

**Technical data:**
- Output: 0...+10 V can be reconnected to -10...+10 V using bridging plug.
- Output can be switched over to an external reference voltage $V_{ref}$ with the toggle switch or to 0 V using a bridging plug.
- Supply voltage: ±15 V DC

| 734 02 | Reference variable generator |
**PID digital controller**

Standard industrial compact controller with fast microprocessor support for use as P, PI, PD or PID controller for continuous closed-loop control systems. With input summing point for one reference variable and one controlled variable, measurement point for error signal, tendency indication of the error signal with 3 LEDs, I and D elements can be switched off individually, I element can be reset via separate input (I off). Including output summing point for adding or subtracting operations of disturbance variables. Manual selection of controller parameters with buttons and digital encoders. Representation of actual parameters on three four-digit 7-segment displays. Overload indication via three-colour LED.

Technical data:
- Signal voltage range: \(-10 \text{ V}...+10 \text{ V}\)
- Sampling interval: 50 µs
- Proportional rate \(K_p: 0.1...100\)
- Correction time \(T_N: 0.1 \text{ s}...100 \text{ s}\)
- Rate time \(T_v: 0.1 \text{ s}...100 \text{ s}\)
- Selection of controller parameters with buttons and digital encoder
- Representation of actual parameters on 7-segment displays
- Overload indication via three-colour LED
- Supply voltage: ±15 V DC

**PID digital controller Net**

Standard industrial compact controller using 32-bit architecture for integration into the LeyLab network. The internal ARM microprocessor excels in a high sampling rate and a fast control response. The controller is used for continuous closed-loop systems e.g. in P, PI, PD or PID configuration. With input summing point for two reference variables and one controlled variable, measurement point for error signal, tendency indication of the error signal with three LEDs, PI and D elements can be switched off individually. The I element can be reset via separate input (RESET). Including an output summing point for adding or subtracting of two external and one internal disturbance variables. The internal disturbance variable can be activated via the LAN. Manual selection of controller parameters with buttons and digital encoders. Representation of actual parameters on three four-digit 7-segment displays. Overload indication via three-colour LED.

Equipped with a RJ45 socket for LAN operation. Internal control by the software LeyLab.control 725006 or LeyLab.control Lite 725007 to set and record the controller parameters from a central master PC and to generate disturbances. Suitable for use with patented „Learning networks“ system.

Technical data:
- Signal voltage range: \(-10 \text{ V}...+10 \text{ V}\)
- Sampling interval: 50 µs
- Proportional rate \(K_p: 0.1...100\)
- Correction time \(T_N: 0.1 \text{ s}...100 \text{ s}\)
- Rate time \(T_v: 0.1 \text{ s}...100 \text{ s}\)
- Selection of controller parameters with buttons and digital encoder
- Representation of actual parameters on 7-segment displays
- Overload indication via three-colour LED
- Supply voltage: ±15 V DC

**Servo setpoint generator**

Position pick-up with rotating angular disc for application in servo systems. With input summing point for forward feeding of disturbance variables or for setpoint variable change and with connectable rate-of-change limiter with rise times of 1 V/s up to 1000 V/s.

Technical data:
- Signal voltage range: \(-10 \text{ V}...+10 \text{ V}\)
- Rotating angle:
  - Mechanical \(360°\) without limit stop
  - Electrical \(340°\) ±5°
- Fine setting of zero-point and scale factor
- Coarse setting with rotary switch
- Fine setting with potentiometer
- Supply voltage: ±15 V DC
**Set of machines 10 W**

The set of 10 W machines is a technical controlled system for experiments on speed and voltage control. It consists of an electrical drive including digital speed sensing, a generator machine and an electronic load. Using the adjustable load, real generator operation can be investigated. The machine set makes it possible to measure the load characteristic of the generator and the dynamic behaviour of systems of higher order. A microprocessor controlled power module supplies the drive machine. Thus no external power amplifier is required. The set of machines comes with 7-segment displays for the measurement of speed and torque.

**Technical data:**
- Speed: 3000 rpm max.
- Control voltage: ±10 V
- Tachogenerator: ±10 V
- Switchable prefilter, time constant $T = 800$ ms
- Power consumption: 10 W max.
- Generator efficiency: 40%
- Supply voltage: ± 15 V DC

**Power amplifier**

Used for operating the simulated controlled system models. Two amplifier stages each with a voltage gain of +1 and -1, symmetrical operation possible with voltage gain of 2.

**Technical data:**
- Signal voltage range: -10 V...+10 V
- Output voltage range: -10 V...+10 V with respect to earth or symmetrical 0...± 20 V
- Output power: max. 30 W, short-circuit proof
- Supply voltage: ±15 V DC

**DC servo**

Motor potentiometer with 360° mechanical rotation angle without limit, electrical rotation angle 340° ±5°, with DC motor and friction wheel drive, as model of an integral controlled system without compensation with negligible dead time, can also be used in a closed-loop positioning control system.

**Technical data:**
- Controlled system output signal (controlled variable): -10 V...+10 V
- Supply voltage: ±15 V DC

**Gain and offset adjust**

For the adjustment and matching of external signals to the normal voltage used in automatic control systems.

**Technical data:**
- Input voltage range: -50 V...+50 V
- Level matching via adjustable gain: 0...1, 0...10, 0...100
- Smoothing of pulsating signals:
  - Time constants $\tau$: 0.1...10 ms, 10...100 ms
- Offset voltage, switchable: -10 V...+10 V
- Coarse setting via rotary switch
- Fine setting via potentiometer
- Supply voltage: ±15 V DC
Actuator, 115...230 V/1 kW

For the connection of mains-operated DC motors 0.1 kW...1.0 kW. Electrical isolation between the control and the load side.

Technical data:
- Signal voltage range (manipulated variable): 0...+10 V
- Output voltage of the thyristor half-bridge: $0...V_{\text{mains}}$ with a max. load of 1.0 kW
- Built-in automatic circuit-breaker (T 10 A) triggered thermally and for overcurrent
- Output voltage for excitation: $V_{\text{exc}} = f(V_{\text{mains}})$, max. 10 A
- Outputs: 4-mm safety sockets
- Mains connection for thyristor half-bridge: 115...230 V, 48...62 Hz
- Supply voltage: ±15 V DC

Scope of delivery:
- Mains lead and earth-contact plug

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
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<tbody>
<tr>
<td>734 22</td>
<td>Actuator, 115...230 V/1 kW</td>
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</tbody>
</table>

Weight disc with hook

To increase the moment of inertia for cat. no. 73444.

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
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<tbody>
<tr>
<td>734 36</td>
<td>Weight disc with hook</td>
</tr>
</tbody>
</table>

DC servo with tachogenerator

Motor-potentiometer combination with gear mechanism, control amplifier and angle code disc with toothed belt pinion.

Technical data:
- Control range: 270°
- Linearity: 1%
- Output voltage range: ±10 V
- Short-circuit proof

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
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</thead>
<tbody>
<tr>
<td>734 44</td>
<td>DC servo with tachogenerator</td>
</tr>
</tbody>
</table>

AC servo

Motor-potentiometer combination with gear mechanism, control amplifier and angle code disk with toothed belt pinion.

Technical data:
- Control range: 270°
- Output voltage range: ±10 V
- Short-circuit proof

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
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<tbody>
<tr>
<td>734 45</td>
<td>AC servo</td>
</tr>
</tbody>
</table>

Torque synchro

For use as rotating-field transmitter and receiver (‘electric waves’).

Technical data:
- 360° system with three-phase output.
- Linearity: 1%
- Switchable 50 V (60 V) AC voltage rotor excitation via built-in mains supply (110 V - 240 V, 50 - 60 Hz)
- Angle code disc with pinion for coupling via toothed belt

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
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<tbody>
<tr>
<td>734 46</td>
<td>Torque synchro</td>
</tr>
</tbody>
</table>
INDIVIDUAL COMPONENTS

WinFACT COM3LAB/CASSY edition, german

WinFACT (Windows Fuzzy and Control Tools), German version, modularly designed software program for the analysis, synthesis and simulation of conventional automatic control systems. Single user licence. Allows integration of CASSY interfaces, cat. no. 524 013, 524 016 and COM3LAB master unit, cat. no. 700 00USB as processing interfaces.

Technical data:

Contents
- **BORIS** (Block-oriented simulation, 15 blocks):
  Control-loop simulation, measurement data acquisition and processing, open-loop and closed-loop control. Endless, single-step and real-time simulation. Comprehensive system block library, exportable project documentation.
- **INGO** (Intelligent Graphic Interface):
  Graphic representation of the following WinFACT files:
  - Simulation results (SIM extension)
  - General value pairs (XY extension)
  - Trajectory fields (MXY extension)
  - Bode plot (BD extension)
  - Locus curves (OK extension)
  - 3D family of characteristics or height lines (FWM extension)

System requirements
- Windows XP/Vista/7/8, two free USB ports

Phase-commutated converter

Phase-commutated converter consisting of:
- 8 thyristors
- 6 diodes
- 1 triac with optional RC circuitry
- Compact universal converter for all conventional converter circuits, e.g. uncontrolled and controlled rectifiers, inverters, 4-quadrant operation

Control is effected via floating-potential signals transmitted along a 25-pole conductor cable from the converter control unit (735 112).

Technical data:
- Overload protection via fast-blow fuses
- Snubber circuit
- Mains connection: max. 230 V
- Output current: max. 1 A
- Trigger output
- Gate control signals accessible as floating potential signals

Scope of delivery:
Set of 13 overlay masks phase-commutated converter
Detection of the applied mask is automatic, thus establishing a preset base state in the converter controller unit (735 122) to prevent the destruction of components through incorrect control commands, thereby simplifying operation of the controller unit. The supplied overlay masks reduce considerable the effort for the experiment set up. Overlay masks do not physically cover necessary connections, they do graphically show the given circuit as a schematic:
- M1/M3, uncontrolled
- M1, controlled
- M3, controlled
- B2, uncontrolled
- B2, controlled
- B2, (un-)controlled for 3 half-waves
- B6, uncontrolled
- B6, controlled
- B6, (un-)controlled for 2 half-waves
- B2, doubled for polarity reversal (B2C)A(B2C
- W1, anti-parallel 1p
- W3, anti-parallel 3p
- Triac
Diode, 1000 V/10 A

Fast-acting silicon rectifier diode with RCD suppressor circuit, which can be switched off, for the assembly of uncontrolled rectifier circuits or use as free-wheeling diode.

Technical data:
- Periodic repetitive peak reverse-bias voltage (V_{RRM}): max. 1000 V
- On-state current (I_{Fmax}): max. 10 A

Rectifier B6, 3X400 V/10 A

Uncontrolled mains rectifier in three-phase bridge circuit for the generation of a DC voltage from a three-phase mains. For the generation of link voltages with converters, switched-mode power supplies and in drive technology.

Technical data:
- Nominal voltage (V_{Nm}): 3 x 400 V
- Nominal current (I_{NM}): 10 A
- Surge forward current (I_{FSM}): 300 A
- FT-value: 450 A/s
- Conducting state voltage (V_{f}): 1 V (per diode)

Thyristor branch pair, 1000 V/12 A

Two thyristors with high blocking capacity and RC suppressor circuit for the assembly of line-commutated rectifier and inverter circuits.

Technical data:
- Gate suppressor circuit
- Periodic repetitive peak reverse-bias voltage (V_{RRM}): max. 1000 V
- On-state current (I_{Fmax}): max. 12 A

Load power electronics

Resistive, inductive and capacitive load for all single-phase and three-phase circuits in power electronics.

Technical data:
- 3 resistors 100 Ω, 1 A, with T 1.25 A fuse
- 1 resistor 1000 Ω, 220 mA
- 2 inductors 50 mH, 2.5 A, with tap at 12.5 mH
- 3 capacitors 4/8/16 μF, 450 V AC

Capacitors 2x 1000 μF, 385 V

Two electrolytic capacitors which are short-circuit proof and switch-proof. For high performance in all application areas, especially for switched-mode and conventional power supplies or used to form DC voltage link. Built-in reverse voltage protection.

Technical data:
- Nominal capacitance: 2 x 1000 μF
- Nominal voltage: 385 V
Transformer for SMPS

Power transformer for primary switched-mode power supplies in a forward converter circuit. With the aid of four
turn-off converter valves as well as two fast rectifiers, the following primary switched-mode power supplies can be
implemented:

- Single-phase forward converter
- Push-pull converter with full-wave rectification
- Asymmetric half-bridge forward converter
- Full-bridge forward converter
- Owing to the shield winding the transformer is suitable for generating a reliable safety extra-low voltage in com-
plication with VDE 0100 (safety standards). The primary windings are equipped with thermal circuit breakers.

Technical data:

- Primary side:
  - Input voltage \((V_{\text{in}})\): 2 x 115 V
  - Winding: 2 x 48 turns
- Secondary side:
  - Output voltage \((V_{\text{out}})\): 2 x 15 V/4.5 A
  - Winding: 2 x 7 turns
  - Nominal power \((P_{\text{n}})\): 135 VA
  - Nominal frequency \((f)\): > 15 kHz
  - Protective-conductor terminal on the shield winding.

Converter controller unit

Microcontroller unit for line-commutated and self-commutated converters for setting up DC, AC and three-phase
converters. Operation is performed manually via a selector and keys or via optional PC software.

Operational modes and operations for the line-commutated converter:

- 4-quadrant mode: (B2C)A(B2C)
- Pulse group control (modulation packet control with zero-crossover switch)
- Control angle limitation
- 2 four-digit, 7-segment displays for control angle and three-phase indicator or duty cycle

Operational modes and operations for the self-commutated converter:

- Pulse width modulation
- Produces 3-phase alternating voltages with adjustable amplitude and frequency for the
  following types of commutation: block, trapezoidal, sine-wave, and VVC
- Single-phase high and low signal generator
- 2 four-digit, 7-segment displays for amplitude and frequency

Technical data:

Connections:

- Analog input for external reference value (control angle, amplitude or frequency)
- USB port
- 25-pole male connector for attaching converter units (including connecting cable)
- Supply voltage via 12 V AC
Control unit six pulse, digital
Trigger pulse generator with analog and digital interface (8 bit) for connection to personal computer with CASSY interface in line-commutated, single-phase and three-phase rectifier and inverter circuits, as well as in AC and three-phase controllers. The matching of the control unit to the converter circuit is carried out using several switches with the following options:
- Single pulse or pulse train operation possible
- Secondary pulse can be switched off (after 60°)
- Phase shift can be set for various natural commutating points: 0°, 30°, 60°
Reliable gate triggering of the valves is guaranteed for even small loads thanks to powerful gate trigger pulses and large voltage-time areas (500 µVs) of the trigger pulse. Rotating field monitoring:
- Green LED when rotating field is clockwise
- Red LED when rotating field is anti-clockwise or for phase-failure

Technical data:
- Signal output for rotating field monitoring (can be OR-operated with the pulse inhibit input)
- 3 x 2 electrically isolated pulse outputs
- Pulse inhibit input
- Synchronising voltage: 1...440 V AC
- Input control voltage: 0...10 V DC for gate control angle 180°...0°
- Digital interface: TTL-level, 8-bit resolution for 180°
- Supply voltage: ±15 V DC

Run-up control unit
For generating a ramp voltage for a reference variable step change at the input.

Technical data:
- Voltage gain: 0.1...1
- Input voltage range: -10 V...+10 V
- Ramp integration time: 0.5...50 s
- Pulse inhibit input
- Supply voltage: ±15 V DC

Fuse threefold super-fast
Set of 3 neozed fuses, ultra-rapid for protection of semiconductor valves.

Technical data:
- 3 x 10 A fuses
- 3 x 6 A fuses

Phase control noise filter 3 x 4.5 A
Single-stage, three-phase interference-suppression filter with high common-mode and normal-mode damping, particularly suitable for experiments in power electronics with self-commutated and line-commutated converter circuits. The filter is connected between the three-phase power supply and the experiment set-up and reduces the output of line-bound interference signals into the low-voltage network in accordance with EN 5008-1.

Technical data:
- 3 toroidal core chokes, 1.3 mH
- 3 X2-class capacitors, 0.47 µF
- 1 Y2-class capacitor, 30 nF
- V = 3 x 230/400 V, 47...63 Hz
- Iₚ = 3 x 4.5 A

Fuse threefold super-fast
Set of 3 neozed fuses, ultra-rapid for protection of semiconductor valves.

Technical data:
- 3 x 10 A fuses
- 3 x 6 A fuses
INDIVIDUAL COMPONENTS

Trigger point limiter

For setting rectifier and inverter stability limits. LED indication for overlap.

Technical data:
- Rectifier stability limit: 0°...180°
- Inverter stability limit: 180°...0°
- Supply voltage: ±15 V DC

| 735 20 | Trigger point limiter |

Isolation amplifier, four channel

Four highly linear, crosstalk and noise-immune isolating amplifiers for measurement recording on static converters, drives and frequency converters used in conjunction with an oscilloscope or the CASSY interface. Potential free measurements due to electrical floating inputs. Current measurement is enabled by built-in shunts. A multiplexer allows the four input signals to be displayed on one (storage) oscilloscope. All of the channels can be switched individually and the corresponding zero-line can be displayed on the screen. Position and amplitude can be set separately on the screen for each channel. A space vector indicator with LED display and oscilloscope output permits representation, measurement and evaluation of three-phase systems, particularly in connection with frequency converters and electrical machines. A mathematical module makes it possible to perform addition, subtraction and multiplication of two input signals. An internal filter permits optionally fundamental waves to be reconstructed out of PWM signals.

Technical data:
- Isolation amplifier channels A, B, C, E:
  - Frequency range: DC...80 kHz
  - Voltage: max. 620 V DC/440 V AC
  - Attenuator, 3-stage: x1, x0.1, x0.01
  - Internal resistance: 1 MΩ
  - Accuracy: 2%
  - Current: max. 10 A AC/DC; 16 A for T < 15 min
  - Ranges: 1 V/A and 1/3 V/A
  - Internal resistance: 30 mΩ
  - Accuracy: 5%
  - Overdrive indication via LEDs
  - Outputs: 4-mm sockets

- Multiplexer:
  - Multiplex frequency, adjustable: 50...500 kHz
  - Amplitude attenuator: 0.2...1
  - Y-position: -8 V...+8 V
  - Trigger source: A, B, C, D or E
  - Oscilloscope output: 2 BNC sockets

- Mathematic module and filter:
  - Operating modes for channel D:
    - Low-pass filter, switchable: 1 kHz

Mains connection: 115/230 V, 47...63 Hz

| 735 261 | Isolation amplifier, four channel |

Connecting lead universal converter

25-pole sub-D connecting lead with two plugs, shielded, soft rubber and uncrossed design, length 2 m to connect the COM3LAB Power Electronics Board with the 3 x 230 V universal converter, cat. no 735 297.

For use in COM3LAB course PE II, cat. no. 700 22.

| 735 290 | Connecting lead universal converter |
Control unit PWM

Control unit with microcontroller for the assembly of a frequency converter in accordance with the PWM characteristic curve method, operated together with the universal converter. A three-phase pulse width modulator controls the six power transistors of the universal converter and thus generates a sinusoidally shaped motor current. The r.m.s. value of the motor voltage is set in accordance with a programmable, dynamically adapting V/f characteristic. The parameters are set via 14 menu items. Indication of the reference/actual value of the current, voltage, or frequency as well as all of the other parameters is handled via a four-digit LED display. Reference variable setting either via external analog interface (-10 V...+10 V) or internal manual input via up/down push-button. Serial interface (RS232) for the communication with a PC for the input of all parameters and the output of measured values. Additional output with 4-mm sockets for the triggering of an oscilloscope. Power supply from the universal converter (735 297) via 25-pin sub-D socket.

Technical data:

- **Parameters**
  - Nominal motor data:
    - Power: 0.1...1 kW
    - Voltage: 0...250 V
    - Current: 0...9.9 A
    - Frequency: 0...100 Hz
  - Limiting data:
    - Current: 0...9.9 A
    - Frequency: 0...120 Hz
  - Ramp time: 0.1...25 s
  - Slip compensation: max. 200%
  - IxR compensation: 0...99 V/A
  - Starting voltage: 0...50 V
  - Voltage/frequency ratio: 2...20 V/Hz
- **Modulation types:**
  - PWM
  - Vector modulation (VVC)
  - Trapezoidal-shaped modulated motor voltage
  - Block-shaped modulated motor voltage

735 291 Control unit PWM

Control unit block commutation

Control unit with microcontroller for the assembly of a highly-dynamic AC servo drive with block signal-shape commutation in operation together with the permanently excited brushless DC machine (AC servo), the universal converter and the commutation pick-up. Alternatively, a 0.3 kW synchronous or multi-function machine can be used. The pulse width modulation is selected so that block-shaped currents are generated in the motor windings. The digital controllers for current, speed and positioning are arranged in cascade configuration. The actual speed value is generated internally out of the commutation signals or measured with an analog or incremental tachogenerator. Commutation signals can also be used for positioning with low resolution (30 degrees). Higher resolution servo positioning is possible by connecting an external servo controller via the parallel interface and an external position pick-up.

Technical data:

- **Adjustable limiting data:**
  - Current: 0...9.9 A
  - Speed: 0...9990 rpm
- **Indication of the mark-space ratio or the reference/actual value of the current, speed, or position is carried out via four-digit LED display.**
- **Reference variable setting either via external analog interface (-10 V...+10 V)**
- **Internal manual input via up/down push-button or parallel interface.**
- **Serial interface (RS232) for the communication with a PC for the input of desired values and the output of measured values.**
- **Power supply from the universal converter via 25-pin sub-D socket.**

735 292 Control unit block commutation
INDIVIDUAL COMPONENTS

Control unit sine commutation

Control unit with microcontroller for the assembly of highly-dynamic AC servo drives with sinusoidal signal-shaped commutation in operation together with the permanently-excited brushless DC machine (AC servo), the universal converter and the resolver. Alternatively, a 0.3 kW synchronous or a multi-function machine can be used. The pulse width modulation is designed so that sinusoidally shaped currents are generated in the motor windings. The digital controllers for current, speed and positioning are arranged in cascade configuration. The actual speed value is generated internally out of the resolver signals. The resolver permits positioning with high resolution (10 bit/360 degrees, corresponding to 0.35 degrees).

Technical data:
- Adjustable limiting data:
  - Current 0...9.9 A
  - Speed 0..9990 rpm
- Indication of the amplitude factor or the reference/actual value of the current, speed, or position is carried out via four-digit LED display
- Reference variable setting via external analog interface (-10 V..+10 V) or internal manual input via up/down push-button.
- Serial interface (RS232) for the communication with a PC for the input of desired values and the output of measured values.
- Power supply from the universal converter via 25-pin sub-D socket.

Converter input/output

This connection panel enables the student to perform basic experiments with the universal converter, manual control of the power transistors and/or output of all status messages, control signals as well as galvanically isolated actual current values.

Technical data:
- Input/outputs (TTL-level):
  - PH1/1, PH1/2, PH2/1, PH2/2, PH3/1, PH3/2 for the control of the power transistors via the bridging plugs or TTL-signals, can also be used as measurement output for displaying the control signals on the oscilloscope
  - Inhibit, chopper control input, clear
  - Status outputs for:
    - Motor temperature
    - Brake chopper signal
    - Converter faults
    - Converter ready signal
- Inputs/outputs (analog signals):
  - 0...5 V corresponding to the trigger angle 180..0 degrees of the converter/rectifier
  - Output for current of phases 1, 2 and 3
  - Output current magnitude sum
  - Power supply from the universal converter via 25-pin sub-D socket.

Scope of delivery:
- 25-pole connecting cable
Universal converter 3 x 230 V

Transistor pulse converter with voltage link for the generation of a three-phase, frequency and amplitude-variable output voltage from an AC mains. This unit in conjunction with the corresponding control unit is used to assemble a frequency converter or servo amplifier.

Description:
- Single-phase mains connection
- Variable link voltage via fully controllable B2C rectifier bridge circuit
- Three-phase inverter built with IGBT (insulated gate bipolar transistor)
- Maximum operating frequency 20 kHz, resulting in good approximation of sinusoidal current as well as low noise build-up in the machine
- Output short-circuit proof, earth-fault proof and switch proof
- Interface for connection of the control unit (25-pole sub-D socket, TTL level)
- Each individual transistor can be switched on and off via the interface and is protected from damage with an interlocking device
- The respective activated IGBT’s are displayed via LEDs
- Monitoring of the variable link voltage, machines and converter excess temperature, excess currents in the rectifier and inverter. Output of the switching status via interface and display via LEDs
- Integrated brake chopper
- Safe separated extra-low voltage (SELV) between the power component and the control unit
- Output currents are detected via Hall generators. Electrically separated output via interface
- 2-stage mains filter for the reduction of the line-bound interference
- 3-phase motor filter for the reduction of the edge steepness of the pulse voltages at the converter output to values < 250 V/µs

Technical data:
- Output voltage (V_{out}): 3 x 0...230 V
- Output current (I_{out}): max. 3 x 8 A
- Supply voltage: 200...240 V, 50/60 Hz via 4-mm safety sockets

Scope of delivery:
- 25-pole connecting cable

Position controller, digital

The microprocessor-controlled digital position controller, in conjunction with the AC servo drive with block commutation, is used to set up a high-precision single-axis positioning drive. Actual positions can be recorded either with the 0.3 kW incremental speed sensor (731 092), which supplies 1024 pulses per rotation or the 0.3 kW linear unit with a position encoder (731 086), which supplies 5 pulses per 1 mm of travel.

Technical data:
- Six-digit, seven-segment display to indicate positions in increments, rounds or mm.
- Integrated incremental rotary switch to set the position reference variable, controller parameters (K_p) and acceleration ramp.
- Convenient evaluation of the drive’s operational data via serial interface (RS 232)
- Reference variables and parameters can then be set via the PC interface.

Scope of delivery:
- 20-pin cable for connection with the control unit block commutation (voltage supply and communication)
- 6-pin connecting lead.

Industrial frequency converter 400 V

Industrial frequency converter for the production of a frequency-variable 3-phase source voltage of max. 400 V/120 Hz with a power rating of 1.5 kW. Operation via keypad or PC, for which a connecting set is included. In addition, an RS 485 port is provided.

735 3101 Industrial frequency converter 400 V
Industrial frequency converter 0.3

Industrial microprocessor-controlled transistor frequency converter, designed for educational purposes, with voltage link for the generation of three-phase, frequency and amplitude variable output voltage from a single-phase AC mains. This device can be used for open-loop and closed-loop control of all asynchronous machines of the power classes 0.3 kW. Front panel with printed block circuit diagram specially designed to illustrate the various applications/program settings.

Features:
- Inverter control method in accordance with DANFOSS VVC procedure (voltage vector control)
- Programmable, V/f control characteristic capable of adapting dynamically to various different loads
- Programmable, PLC-compatible control inputs
- Analog inputs 0...10 V and 0/4...20 mA
- Programmable control and relay output, status indication via LEDs
- Inputs and outputs are short-circuit proof, earth-fault proof and switch-proof
- Electronic motor protection (with warning signal or automatic switch-off)
- Quality electrical isolation (SELV) between power circuit and control
- Display language can be set to English, German, French or Danish
- Display of all important operating states (e.g. frequency, motor current, voltage, torque) via LED 7 segment display
- Integratable speed controller

Technical data:
- Output current continuous: max. 3 x 2.2 A (3 x 3.5 A max. 60 s)
- Output power continuous: 0.9 kVA
- Output voltage: 3 x 0...133/230 V
- Output frequency: 0.2...132 Hz/1...1000 Hz
- Mains connection: 220...240 V, 50/60 Hz
- Input current: max. 5.9 A

Scope of delivery:
- Including mains connection cable and earth-contact plug
- Including technical documentation and software for setting parameters, observing and documenting the frequency converter.

LCP2 local control panel

Separate operating unit with display and keyboard (LCP2) for FCM 300, VLT 2800 and VLT 5000, With 1.80 m PROFIBUS DP connection cable.

Technical data:
- Copy function and data memory
- 4-digit display
- Simultaneous display of four current data values
- Attachable or detachable even during VLT operation

USB/RS 485 interface converter

For use with industrial frequency converter (735 312) and with the two frequency converter motors (732 46) and (732 49)

Technical data:
- Input: USB 1.1 and USB 2.0 compatible
- Output: 1 RS-485 serial port
- Genuine two-wire read/write operation
- Transfer rate 300 up to 115,200 bps
- Electronic isolation up to 3000 V
- Electricity supply: via USB port
- 9-pin sub-D plugs for RS 485

Scope of delivery:
- Drivers for Windows XP and LINUX
Thyristor speed control unit

Compact static converter for setting and performing open and closed loop control of DC voltage and current. In addition to making a multitude of experiments possible, it can also be used to control the speed of a shunt wound machine from 0.1 kW to 2.6 kW with cascade current control in 4-quadrant operation.

Technical data:

Features:
- Mains switch and delayed response main contactor for armature and exciter voltages
- Separate fuses, which can be serviced externally, for excitation, the electronic components and three-phase current
- Exciter voltage output: 220 V, 1 A
- Thyristor power circuit with two fully controlled B6 bridges for circulating current-free 4-quadrant operation, nominal data (V_{lin} = 90 V): 0...230 V, 12 A
- Indication of the active static converter via 2 LEDs
- Complete electrical isolation between power circuit and control and regulating unit
- Extensive fault monitoring with signalling and switch-off.
- Activation for phase-failure, rotating field fault, machine or equipment overheating and time limit
- Control and regulating electronics with extensive indication, setting and measuring possibilities

Open- and closed-loop control:
- Potentiometer for the setpoint with changeover switch for single quadrant and four quadrant operation
- Run-up integrator with potentiometer for the run-up time: 0.1...100 V/s
- Speed controller with summing point:
  - 2 inverting input and 1 non-inverting input
  - Variable gain = 1...10 for actual speed value
  - Coarse and fine adjustment of the proportional coefficient: \( K_p = 0.5...5/0.5...50 \)
  - Coarse and fine adjustment of the reset time: \( T_{ri} = 0.1 s...1 s/1 s...10 s \)
  - I controller can be switched off
  - Overdrive indication via LED
- Both converters I and II have a potentiometer for current limitation
  - \( I_{lim} = 0...12 A \)
  - \( I_{lim} = 0...12 A \)
- Instantaneous comparator with adjustable hysteresis
- Absolute-value generator with measurement socket for control signal INVert
- Adaptive current controller with summing point:
  - 2 inverting inputs and 1 non-inverting input
  - Recognition of intermittent current with LED display and measurement socket for the control signal STL (intermittent current)
  - Reduction of the reset time to 1/10, when intermittent current is present, can be switched off
  - Coarse and fine adjustment of the proportional coefficient: \( K_i = 0.05...0.5/0.25...2.5 \)
  - Coarse and fine adjustment of the reset time:
    - \( T_{ri} = 10 ms...100 ms/100 ms...1 s \)
    - I controller can be switched off - overdrive indication with LED
  - Trigger point limiter with the following setting options:
    - Rectifier stability limit 0°...80°
    - Inverter stability limit 180°...100°
  - Switching logic with measurement sockets for the control signals and with a control input STOP
  - 4-quadrant indication with 4 LEDs
  - Current measurement with current converters
  - The control set provides six double-pulse trains which are switched through to the thyristors of the rectifiers I or II via 12 gate pulse transformers

Supply voltage:
- Control unit: 230 V, 50 Hz
- Power circuit: via external three-phase transformer, 3 x 45/80 V, 50 Hz (735 32)
INDIVIDUAL COMPONENTS

Control unit PWM / PFM

Universal control unit for the assembly of switching DC controllers, switched-mode power supplies and single-phase inverters. It is possible to control all the valves used in power electronics, such as thyristors, GTO thyristors, MOSFETs, Darlington transistors and IGBTs with an output amplifier having electrically isolated outputs for triggering and turn-off. Operation can be selected with the following control modes: pulse width modulation (PWM), pulse frequency modulation (PFM) or two-position control.

Technical data:
- Control voltage (all control modes): 0...10 V DC
- Pulse width modulator:
  - Frequency ranges: 20...200 Hz/2 kHz/2...20 kHz
  - Pulse duty cycle \( t_{\text{ON}} \): 0...0.95
- Pulse frequency modulator:
  - Pulse duration ranges: 5...50 ms/0.5...50 ms/0.5...5 ms
  - Frequency: 20 Hz...20 kHz
- Two-position controller:
  - Hysteresis: 0.2 V
- Output amplifier:
  - Sustained short-circuit proof
  - Indication of switching state via 2 LEDs
- 2 x 2 electrically isolated outputs (test voltage 3 kV)
- INHIBIT input
- Supply voltage: ±15 V DC

MOSFET 500 V/10 A

Enhancement-mode n-channel field effect transistor with fast-acting inverse diode (FREDFET) and with RCD protective circuit which can be switched off. For the assembly of DC controllers, switched-mode power supplies of high pulse frequency.

Technical data:
- Drain-source voltage (\( V_{\text{DS}} \)): 500 V
- Drain DC current (\( I_D \)): 10 A
- Drain-source closing resistor (\( R_{\text{DS(ON)}} \)): 0.6 Ω

Thyristor with turn-off circuit 230 V/8 A

Thyristor which can be turned off with capacitor turn-off and free-wheeling arm. The turn-off circuit consists of ring-around coil with blocking diode, a turn-off thyristor and turn-off capacitor. A DC controller can be implemented directly using the PWM/PFM control unit. Four integrated shunts enable problem-free measurement of the main current, turn-off current, ring-around current and the free-wheeling current. All the thyristors and diodes have a RCD protective circuit.

Technical data:
- Main thyristor and turn-off thyristor
  - Repetitive peak forward off-state voltage (\( V_{\text{RSM}} \)): max. 800 V
  - On-state current, mean value (\( I_{\text{AV}} \)): max. 13 A
  - Circuit-commutated recovery time: \( t_{\text{Q}} \): 35 µs
- Free-wheeling diode
  - Repetitive peak forward off-state voltage (\( V_{\text{RSM}} \)): max. 1000 V
  - On-state current, mean value (\( I_{\text{AV}} \)): max. 8 A
  - Shunts: 4 x 0.1 ohms, 1%
  - Turn-off capacitor: 4 μF, 450 V
  - Ring-around reactor: 1 mH
IGBT 1000 V/10 A

This IGBT (insulated gate bipolar transistor) demonstrates the behaviour of an enhancement-mode field-effect transistor (MOSFET) at the input and the behaviour of a bipolar power transistor at the output. With a fast acting inverse diode and an RCD protective circuit which can be switched off. For use in rapid switching applications with high voltages such as: DC controllers, switch-mode power supplies and inverters.

Technical data:
- Collector-emitter reverse-bias voltage ($V_{CEO}$): max. 1000 V
- Collector current ($I_{C}$): max. 10 A
- Collector-emitter saturation voltage ($V_{CES}$): 3.5 V
- Gate-emitter input capacitance ($C_{GE}$): 1.8 nF

Fault simulator for phase control

Standard dimmer circuit for resistive load ($P = \text{max. } 1.2 \text{ kW}$) with preset minimum value, consisting of triac, diac, 2 potentiometers, resistors and capacitors. Various measurement points permit systematic trouble-shooting. A total of 20 faults from the following categories can be switched on:
- Line break
- Short-circuit
- Faulty assembly
- Faulty components

The faults are switched on using slide switches, which are located behind a lockable cover.

Technical data:
- Supply voltage: 110 V...230 V, 47 Hz...63 Hz

Excitation voltage controller 200 V/2.5 A

Adjustable power supply with smoothed current and voltage for supplying power to a synchronous machine in the power class 0.3 kW or 1.0 kW. Adjustment of the output voltage can be carried out internally using the UP/DOWN push-button or externally via 4-mm sockets using switching contacts, TTL-level or 24 V DC. The setting direction is indicated by two yellow LEDs. When the synchronous machine is run up asynchronously, it is not necessary to short circuit the excitation winding.

Technical data:
- Output voltage $V$: 0...200 V
- Output current $I$: max. 2.5 A
- The output is overload-proof and short-circuit-proof.
- Supply voltage: 230 V, 50/60 Hz

Manual synchronisation unit

Synchronisation unit with manual switch to connect the generator to the mains.

Technical data:
- Two 7-segment voltage displays
- Two 7-segment frequency displays
- One 7-segment zero-volt display
- One optical synchronoscope
- Six synchronisation lamps
- One optical synchronisation indicator
- One rotating field indicator
- One manual three pole switch
**INDIVIDUAL COMPONENTS**

**Power circuit breaker module**

3-phase ON/OFF switch with auxiliary contact (NC) for 380 kV transmission line model. Can be controlled manually using ON/OFF push-button or externally via switching contact, TTL level or 24 V DC. The switching state is indicated by LED’s and is additionally available as TTL level from 4-mm sockets. Control input (switching contact, TTL level, 24 V DC) for external switch-off command (tripping on faults).

**Technical data:**
- Contact load capacity: 400 V AC, 3 A
- Mains connection: 115/230 V, 50 Hz

| 745 561 | Power circuit breaker module |

**3-phase stator**

Stator for a three-phase machine in the form of a working model demonstrating function, built with drive-end shield and industrial terminal box, electrically functional, mounted on a base socket. The stator is designed to accommodate different rotors. Rotors are attached to the stator by means of star-grip bolts.

**Technical data:**
- Class: 0.3
- Colour: Machine body, light grey
  - Base, black

| 747 720 | 3 phase stator |

**Squirrel cage rotor**

Rotor for a three-phase asynchronous machine with pull-out torque in the form of a working model demonstrating function, with non-drive-end shield. The rotor is designed for use with the three-phase stator 747720.

**Technical data:**
- Class: 0.3
- Cage material: aluminium
- Colour: light grey

| 747 721 | Squirrel cage rotor |

**Slip-ring rotor**

Rotor for three-phase asynchronous motor with slip ring rotor in the form of a working model demonstrating function, with non-drive-end shield, fan and dust cover. The slip rings, brush holder as well as the brushes are visible through a perspex cover. The rotor is designed for use with the three-phase stator 747720.

**Technical data:**
- Class: 0.3
- Colour: light grey

| 747 722 | Slip-ring rotor |

**Salient pole rotor**

Rotor for three-phase synchronous machine with salient pole rotor in the form of a working model demonstrating function, with non-drive-end shield, fan and dust cover. The slip rings, brush holder as well as brushes are visible through a perspex cover. The rotor is designed for use with the three-phase stator 747720.

**Technical data:**
- Class: 0.3
- Colour: light grey

| 747 723 | Salient pole rotor |
INDIVIDUAL COMPONENTS

Smooth core rotor

Rotor for three-phase synchronous machine with smooth-core rotor in the form of a working model demonstrating function, with non-drive-end shield, fan and dust cover. The slip rings, brush holder as well as brushes are visible through a perspex cover. The rotor is designed for use with the three-phase stator 747720.

Technical data:
- Class: 0.3
- Colour: light grey

<table>
<thead>
<tr>
<th>747 724 Smooth core rotor</th>
</tr>
</thead>
</table>

Reluctance rotor

Rotor for three-phase synchronous machine with reluctance rotor in the form of a working model demonstrating function, with non-drive-end shield, fan and dust cover. The slip rings, brush holder as well as brushes are visible through a perspex cover. The rotor is designed for use with the three-phase stator 747720.

Technical data:
- Class: 0.3
- Colour: light grey

<table>
<thead>
<tr>
<th>747 725 Reluctance rotor</th>
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</thead>
</table>

DC shunt stator

Stator for a DC shunt current machine in the form of a working model demonstrating function, featuring drive-end shield and industrial terminal boxes mounted on a base. The stator is designed to accommodate different rotors and equipped with star-grip bolts to attach them.

Technical data:
- Class: 0.3
- Colour: Machine body, light grey
  Base, black

<table>
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<tr>
<th>747 726 DC shunt stator</th>
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</table>

Similar to illustration

DC rotor

Rotor for DC machine in the form of a working model demonstrating function, with non-drive-end shield, fan and dust cover. The collector, brush holder as well as the brushes are visible through a perspex cover. The rotor is designed for use with the DC stator (747 726).

Technical data:
- Class: 0.3
- Colour: light grey

<table>
<thead>
<tr>
<th>747 728 DC rotor</th>
</tr>
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</table>

Similar to illustration

Efficiency rotor

Rotor for a three-phase asynchronous machine with copper cage in the form of a working model demonstrating function, with non-drive-end shield. The rotor is designed for use with the three-phase stator 747720.

Technical data:
- Class: 0.3
- Cage material: copper
- Colour: light grey

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System: Electrical machines training system

Supplementary set for electrical machines training system (62-005-230) for recording characteristics of electrical machines in all four operating quadrants.

Technical data:
- Machine test system
- CBM10 software MOMO / FCCP
- 3-phase transformer
- 3-pole on-off switch
- EMT adapter kit (adapter base for machine test system)
- Coupling
- Set of safety experiment leads

MPS set: Electrical machines training system

Electrical machines training system (62-005-230) with machine test system for recording characteristics of electrical machines in all four operating quadrants, consisting of:

- Electrical machines training system
- EMT storage frame
- EMT system frame
- Machine test system
- Software CBM10 MOMO / FCCP
- 3-phase transformer
- 3-pole on-off switch
- EMT adapter kit (adapter base for machine test system)
- Coupling
- Set of safety experiment leads

*The MPS set Electrical machines training system (762 102) is not available in all countries. Please contact your local dealer.
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The literature is also available in other languages.
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